Bisection Acceleration for the Symmetric Tridiagonal Eigenvalue Problem *

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Summary. We present new algorithms that accelerate the bisection method for the symmetric tridiagonal eigenvalue problem. The algorithms rely on some new techniques, including a new variant of Newton's iteration that reaches cubic convergence (right from the start) for a well-conditioned eigenvalue problem and can be further applied to acceleration of some other iterative processes, in particular, of the divide-and-conquer methods for the symmetric tridiagonal eigenvalue problem.

Key words: symmetric eigenvalue problem, bisection algorithm, divide-and-conquer eigenvalue algorithms, Newton's iteration, convergence acceleration, approximating polynomial zeros.

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* The results of this paper (apart from numerical experiments, designed and performed by the second author) have been presented (in the preliminary form of [P92]) at the Copper Mountain Conference on Iterative Methods, Copper Mountain, Colorado, 1992.

1 Introduction

The classical bisection method is a reliable approach to the solution of the symmetric eigenvalue problem [Par], pp. 53-54; [GL], pp. 437-443, particularly effective for approximating a few eigenvalues confined to a fixed interval. Successful acceleration of the convergence of this method usually attracts a lot of interest; celebrated examples are given in [B], [LPS], and [PR]. In this paper, we propose new acceleration techniques, extending the ones of [P87], [P89], [P94], originally developed for approximating polynomial zeros (also compare [DP], [P92]). The presented analysis of our algorithms and the formal rigorous proofs of all the complexity estimates are quite involved, but the implementation and coding of our algorithms are sufficiently simple, and the results of our numerical experiments, presented in section 13, confirm the expected behavior of the algorithms, which substantially accelerate bisection for higher precision approximation of the eigenvalues.

Our bisection acceleration relies on some general techniques of convergence acceleration, already proved to be effective for approximating polynomial zeros [P87], [P94] and matrix eigenvalues [BP91], [BP92]. These techniques are less known in the numerical linear algebra community but have some attractive features, such as global quadratic or cubic convergence of iterations (right from the start). In particular, such a convergence is guaranteed if we have a real symmetric input matrix A whose invariant subspace associated with the eigenvalues of A from a fixed real interval J is well-conditioned. The condition of such a subspace is quantitatively measured by $ir(J)$, the *isolation ratio* of J (according to our definition 4.1, which we borrow from [P87]), and we supply some effective techniques, which either define an interval associated with a well-conditioned subspace or enable us to partition the original problem for approximating k eigenvalues of A into 2 subproblems of smaller sizes. The techniques of this paper can be also used in order to accentuate the power o known methods, in particular, of the divide-and-conquer method for the symmetric eigenproblem (see our remark 9.1).

Our paper is organized as follows: We recall some fast methods for the evaluation of the characteristic polynomial of A and its derivative, in section 2, and the bisection algorithm, in section 3. In section 4, we outline our main algorithm and define the two basic concepts, of a splitting point and an isolation ratio. To ensure stronger isolation of the eigenvalues, we use bisection in section 5 and the double exponential sieve process of [BOT] in section 6. Our algorithm 7.1 of section 7 approximates well-isolated (clusters of) eigenvalues of A. In section 8, we summarize our first eigenvalue algorithm, which combines the 2 stages: of isolation (via the algorithms of sections 5 and 6) and subsequent rapid approximation (via algorithm 7.1). The algorithms of sections 7 and 8 are further accelerated in section 9. In sections 10 and 11, we analyze the 2 algorithms of sections 7-9 and prove their global su-

perfinear convergence. In section 12, we summarize the resulting computational complexity estimates. In section 13, we show the results of numerical experiments.

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2 Definitions and auxiliary results

Hereafter, $A = (a_{i,j},\ i,\ j = 1, \cdots, n)$ denotes an $n \times n$ real symmetric tridiagonal (rst) matrix, with n real eigenvalues $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_n$; $\alpha_i = a_{i,i}$, $\beta_j = a_{j-1,j} = a_{j,j-1}$, A_i denotes the $i \times i$ leading principal submatrix of $A = A_n$, $p_i(x) = \det(\ xI_i - A_i\ )$ denotes the characteristic polynomial of A_i, $p(x) = p_n(x) = \det(\ xI_n - A\ )$. We have

$$p_0(x) = 1, \quad p_1(x) = x - \alpha_1, \quad p_j(x) = (x - \alpha_j)\, p_{j-1}(x) - \beta_j^2 p_{j-2}(x)\ , \quad j = 2, \ldots, n\ . \tag{2.1}$$

We may precompute the values β_h^2 for all h in $n-1$ multiplications and then apply (2.1) in order to evaluate the sequence $p_1(x), \ldots, p_n(x)$, for any fixed x, in $2n-3$ multiplications and $2n-1$ additions. The number of sign agreements in this sequence (provided that $\text{sign}(p_j(\lambda)) = \text{sign}(p_{j-1}(\lambda))$ if $p_j(\lambda) = 0$) equals the number $n_-(x)$ of the eigenvalues of A that are less than x ([GL], p. 438; [Par], p. 131).

We will employ a nonlinear recurrence ([PS], [BP92], p. 120) to speed-up the computation and to avoid overflow. Write $R_i = R_i(x) = p_i(x)/p_{i-1}(x)$, precompute β_i^2 for all i (this stage does not depend on x), compute $\alpha_i - x$ for all i, and then recursively compute

$$R_{j+1} = x - \alpha_{j+1} - \beta_{j+1}^2/R_j \quad \text{if} \quad R_j \neq 0, \qquad R_{j+2} = x - \alpha_{j+2} \quad \text{if} \quad R_j = 0, \quad j = 1, \ldots, n-1.$$

By the definition of R_j, $n_-(x)$ equals the number of indices j with $R_j \geq 0$. In $3n \pm O(1)$ arithmetic operations, we obtain all $x - \alpha_i$ and all R_j for each x, and then $n_-(x)$ is recovered in n comparisons of R_j with 0, that is, we need a total of $4n \pm O(1)$ operations. If we only need to evaluate R_j, for $j = 1, \ldots, n$, and if we ignore the tests that determine if $R_j \neq 0$, then the total number of operations used decrea to $3n \pm O(1)$.

We also extend this approach to the computation of $p'(x)/p(x)$, by recursively computing the ratios $R_j^* = R_j^*(x) = p_j'(x)/p_j(x)$ as follows ([PS], [BP92], p.120):

$$R_0^* = 0, \qquad R_1^* = 1/(x - \alpha_1)\ ,$$
$$R_j^* = R_{j-2}^* + ((x - \alpha_j)(R_{j-1}^* - R_{j-2}^*) + 1)/R_j\ , \quad j = 2, 3, \ldots, n.$$

This will give us $p'(x)/p(x) = p'_n(x)/p_n(x)$ in $5n \pm O(1)$ additional arithmetic operations. Unlike the computation of $n_-(x)$, the latter evaluation involves no comparisons.

We will measure the computational complexity by the number of operations involved and also by the number of the evaluations of $n_-(x)$, $p(x)$, and $p'(x)/p(x)$.

Hereafter, all logarithms are to the base 2.

3 Bisection algorithm

Algorithm 3.1, *bisection algorithm.*

Input: an $n \times n$ rst matrix A, 3 real numbers a, b, and t, $0 < 2t < b - a$.

Output: approximations (within the absolute error bound t) to all the eigenvalues of A in the semi-open interval $[a, b) = \{ x : a \le x < b\}$.

Initialize: call the interval $[a, b)$ *suspect.*

Recursive step: for every suspect interval $[q, r)$ such that $r - q > 2t$, compute $n_-(\frac{q+r}{2})$; call the subinterval $[\frac{q+r}{2}, r)$ *suspect* if $n_-(r) > n_-((q+r)/2)$; call the subinterval $[q, \frac{q+r}{2})$ *suspect* if $n_-(\frac{q+r}{2}) > n_-(q)$; remove the label "suspect" for the interval $[q, r)$.

Stopping criterion: end the computation when all the suspect intervals have length at most $2t$; for each of them, output its midpoint and the number of the eigenvalues of A lying in it.

Let $\lambda_{j+1}, \ldots, \lambda_{j+k}$ denote the eigenvalues of A in $[a, b)$,

$$\lambda_{j+k+1} < a \le \lambda_{j+k} \le \ldots \le \lambda_{j+1} < b \le \lambda_j \ . \tag{3.1}$$

By definition, a suspect interval contains at least one eigenvalue. Therefore, at each recursive step, there are at most k suspect intervals, and at most k evaluations of $n_-(x)$ are required, at the midpoints of all the suspect intervals. In the s-th recursive step, each suspect interval has length $(b-a)/2^s$, so that in $\lceil H \rceil$ steps, for

$$H = \log((b-a)/(2t)) \ , \tag{3.2}$$

we output the solution. Therefore, the bisection algorithm outputs desired approximations to the k eigenvalues of A in $[a, b)$ by using $4kn\lceil H \rceil + O(k)$ arithmetic operations and comparisons.

4 Accelerated Algorithms (Outline)

We next outline 2 algorithms that converge with nearly quadratic or cubic rates and support the complexity bounds of order $kn \log^2 H$ [versus $4kn\lceil H \rceil + O(k)$ above]. We need 2 basic definitions.

Definition 4.1 *Let $J = [\mu - \ell, \mu + \ell)$ be a real interval. Let $D = \min_{\lambda_i \notin J} |\mu - \lambda_i|$ denote the distance from the midpoint μ to the closest eigenvalue of A lying outside J. Then we write $|J| = 2\ell$ and define (cf. [P87], [P89]) the isolation ratio of J, $ir(J) = 2D/|J| = D/\ell$.*

Definition 4.2 *$x \in J$ is called a splitting point of $J = [\mu - \ell, \mu\ell)$ if*

$$n_-(\mu - \ell) < n_-(x) < n_-(\mu + \ell) \ .$$

Whenever our algorithm applied to $J = [\mu - \ell, \mu + \ell)$ computes a splitting point x, we interrupt the computations and restart them separately for each of the two subintervals $[\mu - \ell, x)$ and $[x, \mu + \ell)$, each of them *containing fewer eigenvalues* of A. Since $[a, b)$ contains k eigenvalues, we encounter *at most* $k - 1$ *splitting points* and need *at most* $k - 1$ *such interruptions.* We may restate our task as follows:

Problem 4.1.

Input: an $n \times n$ rst matrix A, real a, b, t, and the integers k, $n_-(a)$, $n_-(b)$ such that $t > 0$, $a < b$, $k = n_-(b) - n_-(a) > 0$.

Output: a splitting point x satisfying the relations of definition 4.2 or an approximation μ, within t, to all the eigenvalues of A lying in $[a, b)$.

We will solve problem 4.1 in 2 stages.

Stage 1, *lifting an isolation ratio* (see sections 5 and 6). Fix a sufficiently large $N = N(n)$ [cf. (4.2), (4.3) below] and compute and output a splitting point of $J = [a, b)$ or compute a subinterval J^* of J sharing all its k eigenvalues with J and satisfying the bound

$$ir(J^*) \geq N \ . \tag{4.1}$$

Stage 2, *Newton's iteration* (see sections 7 and 9). Assume (4.1) and apply one of the 2 variants of Newton's iteration specified in sections 7 or 9 and converging with quadratic or, respectively, cubic rate (right from the start of stage 2) provided that

$$N > 6n \tag{4.2}$$

or, respectively, $k = n$ and

$$N > \sqrt{6n} + 2 \ . \tag{4.3}$$

Stop the iteration when it solves problem 4.1.

5 Linear increase of an isolation ratio via bisection

The next result is immediately verified.

Fact 5.1. *Let $ir(J_G) = 1+u$ for a suspect interval J_G computed at the G-th recursive step of algorithm* 3.1. *Then the bisection of J_G either outputs two suspect intervals of half length (and then the midpoint of J_G is a splitting point) or defines a single suspect subinterval J_{G+1} of J_G such that*

$$2\,|J_{G+1}| = |J_G|\ , \qquad ir(J_{G+1}) \geq 1 + 2u\ .$$

If h bisection steps have been applied to the interval J_G of fact 5.1 such that $ir(J_G) \geq 1 + u$ and if neither of them computes a splitting point for J_G, then their output suspect subinterval J_{G+h} has length $|J_G|/2^h$ and has an isolation ratio of at least $1 + 2^h u$. If

$$ir(J_G) \geq 3\ , \qquad u \geq 2\ , \tag{5.1}$$

then $1 + 2^h u \geq 1 + 2^{h+1}$, so that $ir(J_Q) \geq N$ for $Q = G + h$, $h = \lceil \log(N-1) \rceil - 1$ [cf. (4.1) for $J^* = J_Q$].

6 Double exponential sieve for increasing an isolation ratio

In this section, we will yield an interval J_G with its isolation ratio of at least 3 [satisfying (5.1)], by applying the *double exponential sieve* algorithm of [BOT], originally proposed for approximating polynomial zeros. For simplicity, let $\mu = \ell = 1$, let A have a unique (single or multiple) eigenvalue λ in the interval $J = [0, 2)$, and see our comments on the extension to the general case at the end of this section.

One bisection step specifies if λ lies in $[0, 1)$ or $[1, 2)$. Without loss of generality, let $0 \leq \lambda < 1$; then A has no eigenvalues in [1,2). Now, the idea is to compute $n_-(x_i)$ not for $x_i = 2^{-i}$ but for $x_i = 2^{-2^i}$, $i = 1, 2, \ldots$, which is clearly more effective if λ lies near 0. Formally, for a fixed $t > 0$, we seek 2 real values $\overline{a}$ and $\overline{b}$ such that

$$0 \leq \overline{a} \leq \lambda < \overline{b} \leq 1$$

and either

$$\overline{b} - \overline{a} \leq 2t\ , \tag{6.1}$$

(in which case $|\ \lambda - (\ \overline{a} + \overline{b}\ )/2\ | \leq t$) or else

$$\overline{b} \leq 2\overline{a} \tag{6.2}$$

(in which case the isolation ratio of the interval $[a, b)$ is at least 3). We first successively evaluate $n_-(x_i)$ for $x_i = 2^{-2^i}$, $i = 1, \ldots, g_1$, where

$$g_1 = \min\{\lceil \log\log(1/(2t)) \rceil \ , \qquad \min_{i \geq 1}\{i,\ n_-(x_i) < n_-(1)\}\ \} \ .$$

If $g_1 = \lceil \log\log(1/(2t)) \rceil$, then $0 \leq \lambda \leq 2^{-2^{g_1}} \leq 2t$, and we satisfy (6.1) for $\overline{a} = 0$, $\overline{b} = x_{g_1}$. Otherwise, λ lies in the interval $J_{g_1} = \{\ \lambda, \overline{a}_1 = x_{g_1} \leq \lambda < x_{g_1 - 1} = \overline{b}_1\ \}$. If $g_1 = 1$, then we write $x_0 = 1$, $J_{g_1} = [1/4, 1)$, so that $ir(J_{g_1}) \geq 5/3$, and we increase this ratio to at least $11/3$ in at most 2 applications of fact 5.1. Otherwise, if $g_1 > 1$, we apply the same (double exponential sieve) procedure to the interval J_{g_1}. Let g_2 denote the number of the evaluations of $n_-(x)$ in this application. Then we either satisfy (6.1) by setting $\overline{a} = \overline{a}_1$, $\overline{b} = \overline{a}_2 = \overline{a}_1 + (\overline{b}_1 - \overline{a}_1)2^{-2^{g_2}}$ or else obtain that

$$\overline{a}_2 = \overline{a}_1 + (\overline{b}_1 - \overline{a}_1)2^{-2^{g_2}} \leq \lambda < \overline{a}_1 + (\overline{b}_1 - \overline{a}_1)2^{-2^{g_2 - 1}} = \overline{b}_2 \ .$$

If $g_2 > g_1$, then $\overline{b}_2 - \overline{a}_2 < \overline{a}_1$ since $\overline{b}_1 - \overline{a}_1 < \overline{b}_0 - \overline{a}_0 = 1$, and we satisfy (6.2) for $\overline{a} = \overline{a}_2$, $\overline{b} = \overline{b}_2$. If $g_2 = g_1$, we argue as follows: According to the definition of $\overline{a}_1$ and $\overline{b}_1$ we have $0 < \overline{b}_1 < 1$ and $\overline{a}_1 = \overline{b}_1^2$. This yields (for $g_1 = g_2$):

$$\overline{b}_2 - \overline{a}_2 = (\overline{b}_1 - \overline{a}_1)(2^{-2^{g_1 - 1}} - 2^{-2^{g_1}}) = (\overline{b}_1 - \overline{a}_1)^2$$

$$= (\overline{b}_1 - \overline{b}_1^2)^2 = \overline{b}_1^2(1 - \overline{b}_1)^2 < \overline{b}_1^2 = \overline{a}_1.$$

It remains to consider the case where $g_2 < g_1$. Recursively, we arrive at a decreasing sequence of positive integers $\{g_1, g_2, \ldots, g_u\}$, such that (6.1) and/or (6.2) are satisfied for $\overline{a} = \overline{a}_u$, $\overline{b} = \overline{b}_u$. Then $u \leq g_1$ and the overall number of the evaluations of $n_-(x)$ in the entire process, including the initial evaluation of $n_-(1)$, is at most

$$G = 1 + \sum_{i=1}^{u} g_i \leq 1 + (g_1 + 1)g_1/2 \ , \quad g_1 = \lceil \log\log(1/(2t)) \rceil \ . \tag{6.3}$$

Extension. We may immediately extend the above process from the input interval $[0, 2)$ to any interval J of length $2l$, which may contain several eigenvalues of A, so that, in at most $G^* = (g_1^* + 1)g_1^*/2 + 1$ evaluations of $n_-(x)$, for $g_1^* = \lceil \log\log(l/(2t)) \rceil$, we either compute a splitting point x in J or output a subinterval $\widetilde{J} = J_{G^*}$ of J containing exactly the same eigenvalues of A as J and such that $|\widetilde{J}| \leq 2t$ and/or $ir(\widetilde{J}) \geq 3$.

Remark 6.1. The equation (6.3) gives us overly pessimistic estimates. Indeed, under the uniform probability distribution of random λ on [0,1), one may easily deduce that Probability$\{g_1 > i\} = 2^{-2^i}$, and similarly, Probability$\{g_k > i\}$ rapidly decreases to 0 as i grows, for all k.

7 Accelerated computation in the case of very good initial isolation

The algorithms of sections 5 and 6 enable us to reduce problem 4.1 to the following problem:

Problem 7.1

Input: real a^*, b^*, N, t and integers j, k, $n_-(a^*)$, $n_-(b^*)$ such that

$$t > 0 \ , \quad b^* > a^* \ , \quad j \geq 0 \ , \quad k \geq 1 \ , \quad j + k \leq n \ ,$$

$$\lambda_{j+k+1} \leq a^* - C < a^* \leq \lambda_{j+k} \leq \ldots \leq \lambda_{j+1} < b^* < b^* + C \leq \lambda_j \ , \tag{7.1}$$

where $C = (b^* - a^*)(N-1)/2$, $\lambda_0 = +\infty$, $\lambda_{n+1} = -\infty$. (The interval $J^* = [a^*, b^*)$ contains exactly k eigenvalues of A, and $ir([a^*, b^*)) \geq N$.)

Output: a real μ such that

$$\lambda_{j+k} - t \leq \mu \leq \lambda_{j+1} + t \tag{7.2}$$

and the integers $n_-(\mu - t)$, $n_-(\mu + t)$.

Once these output values are available, we have either

$$n_-(\mu + t) = n_-(b^*) \ , \quad n_-(\mu - t) = n_-(a^*)$$

(in which case $\mu - t \leq \lambda_{j+k} \leq \ldots \leq \lambda_{j+1} < \mu + t$) or

$$n_-(\mu + t) < n_-(b^*)$$

[and then $\mu + t$ is a splitting point, $\lambda_{j+k} \leq \mu + t < \lambda_{j+1}$] or

$$n_-(\mu - t) > n_-(a^*)$$

[and then $\mu - t$ is a splitting point, $\lambda_{j+k} < \mu - t \leq \lambda_{j+1}$].

For large N and C, the k eigenvalues of A in [a,b) can be viewed as a cluster well isolated from the other eigenvalues of A. *Newton's iteration* for computing the k-fold zero of $p(x)$ rapidly converges to such a cluster (cf. (7.4) and section 10). Here is a recursive algorithm for problem 7.1 that elaborates the details, where we will assume that $N_0 = N$ is large enough to allow the choice of nonnegative h_0 in remark 7.1 below. (We will show later on that N_i grows as i grows.)

Algorithm 7.1

Initialization: set $a_0 = a^*$, $b_0 = b^*$, $N_0 = N$, $t_0 = (b_0 - a_0)/2$.

Recursive step i, $i = 0, 1, \ldots$. Choose a nonnegative h_i (according to remark 7.1 below) and compute

$$c_i = b_i + (b_i - a_i)h_i \ , \tag{7.3}$$

$$\mu_i = c_i - k\,p(c_i)/p'(c_i)\ , \tag{7.4}$$

$$M_i = \max\{\frac{n-j-k}{N_i+1+2h_i}\ ,\ \frac{j}{N_i-1-2h_i}\}\ , \tag{7.5}$$

$$t_{i+1} = 2(b_i-a_i)(h_i+1)^2 M_i\,/\,(k-2(h_i+1)\,M_i)\ . \tag{7.6}$$

If $t_{i+1} \le t$, then output $\mu = \mu_i$, compute and output $n_-(\mu - t)$, $n_-(\mu + t)$, and end the computation. Otherwise, compute $a_{i+1} = \mu_i - t_{i+1}$, $b_{i+1} = \mu_i + t_{i+1}$, $n_-(a_{i+1})$ and $n_-(b_{i+1})$. If $n_-(a^*) < n_-(a_{i+1})$, output $\mu = a_{i+1}$, $n_-(\mu - t)$, $n_-(\mu + t)$ and stop. Otherwise, if $n_-(b_{i+1}) < n_-(b^*)$, output $\mu = b_{i+1}$, $n_-(\mu - t)$, $n_-(\mu + t)$ and stop. Otherwise, set

$$N_{i+1} = \frac{(N_i-1)(k-2(h_i+1)M_i)}{4(h_i+1)^2\,M_i} - 1\ , \tag{7.7}$$

where M_i is defined by (7.5), and go to step $i+1$.

Remark 7.1. In our algorithms 7.1 and 9.1, we may choose any sufficiently small nonnegative h_i. In particular, h_i should be less than

$$\min\{\ \frac{N_i-1}{2}\ ,\ \frac{(N_i-1)k+2-2n}{2(n+k-1)}\ \}\quad \text{or}\quad \min\{\ \frac{N_i-2}{2}\ ,\ \frac{(N_i-1)(N_i-2)k-2(n-k)}{2k(2N_i-3)+2(n-k)}\ \}\ ,$$

respectively. (By our initial choice of $N = N_0$, these minima are positive for $i = 0$, and this property is recursively maintained for all i.) Due to the symmetry, we may alternatively try $h_i < -1$ [with respective adjustment of the expressions (7.5) and (7.6) for M_i and t_i]. To present our algorithms in a more general form, we include h_i as parameters, but the reader may simplify further reading by assuming $h_i = 0$ for all i. In particular, in our experiments, reported in section 13, we have let $N = 8n$ and $h_i = 0$ for all i; actually we have also performed tests with $h_i = 1$ for all i; in both cases, we observed convergence with about the same running time.

8 Summary of an eigenvalue algorithm

By combining our algorithms of sections 4-7, we specify our first algorithm for problem 4.1.

Algorithm 8.1

1) Apply the double exponential sieve process of section 6 to the interval $J = [a, b)$. The process either solves problem 4.1 or outputs a subinterval $\widetilde{J}$ of $[a, b)$ containing the same eigenvalues as the input interval $[a, b)$ and having an isolation ratio of at least 3.

2) In the latter case, apply $h = \lceil \log((N-1)/2) \rceil$ bisection steps (supporting Fact 5.1) to the interval $\widetilde{J}$. This either solves problem 4.1 or outputs a subinterval J_Q of $\widetilde{J}$ sharing all the eigenvalues with $\widetilde{J}$ and having an isolation ratio of at least N.

3) In the latter case, choose nonnegative h_i (say, $h_i = 0$), $i = 0, 1, \dots$, and apply algorithm 7.1 to the interval $J_Q = [a^*, b^*)$.

There can be at most $k-1$ splitting points of J; therefore, approximating all the k eigenvalues of A in $[a, b)$ requires at most $2k-1$ calls for algorithm 8.1.

Remark 8.1. The latter (worst case) estimate of $2k-1$ is overly pessimistic on the average case, according to our experiments and some theoretical consideration.

9 Acceleration of algorithms 7.1 and 8.1

If some approximations λ_r^* to the eigenvalues λ_r of A for all $r \le j$ and $r > j+k$ are available when we apply algorithm 7.1 at stage 3 of algorithm 8.1, then we may subtract the reciprocals $1/(\ \lambda_r^* - c_i\ )$ for all $r \le j$ and all $r > j+k$ from the value $-p'(c_i)/p(c_i)$ in (7.4), thus decreasing the influence of these remote eigenvalues on the sum of the reciprocals, $-p'(c_i)/p(c_i)$. Our further analysis in section 11 and our experiments show that this accelerates the convergence and enables us to decrease the lower bound on N from (4.2) to (4.3). Next, we will specify the first recursive step of the modified algorithm (accelerating step 0 of algorithm 7.1) assuming for simplicity that the available approximations λ_r^* to all the eigenvalues λ_r of A, for $r = 1, \dots, n$, satisfy the bound

$$|\lambda_r^* - \lambda_r| \le t^* = (b-a)/2\ . \tag{9.1}$$

In fact, we may ensure this assumption by arranging the steps of algorithm 7.1 so as to work always with the *largest* of the available suspect intervals output at stage 2.

We now modify algorithm 7.1 by replacing the values μ_i [of (7.4)] by the values

$$\mu_i^* = c_i + k/q_i, \quad q_i = -\frac{p'(c_i)}{p(c_i)} - \sum_{r=1}^{j} \frac{1}{\lambda_r^* - c_i} - \sum_{r=j+k+1}^{n} \frac{1}{\lambda_r^* - c_i}\ , \quad i = 0, 1, \dots\ .$$

[This requires $3(n-k)$ extra arithmetic operations for each i.] We will cite this modification of algorithm 7.1 as **algorithm 9.1** and the respective modification of algorithm 8.1 as **algorithm 8.1a**.

We may set $h_i = 0$ for all i in algorithms 8.1a and 9.1, which would imply faster convergence but would leave the value $r(c_i) = -p'(c_i)/p(c_i)$ unbounded. We have 2 good options for avoiding overflow. In one approach, we first compute the reciprocal $1/r(c_i)$. If it is close to 0, we end the computation by detecting some eigenvalues of A in the interval $[b_i - t\ ,\ b_i) = [\ c_i - t\ ,\ c_i)$. Another option is to choose a small positive h_i, thus preventing the computer from overflow since

$$|p'(c_i)/p(c_i)| = \sum_{r=1}^{n} \frac{1}{\lambda_r - c_i} < \frac{k}{h_i^*} + \frac{n-k}{C - h_i^*}, \quad C = (b^* - a^*)(N-1)/2, \quad h_i^* = (b_i - a_i)h_i.$$

If V denotes the minimum value that causes overflow, then we need to ensure the bound $|p(c_i)/p(c_i)| < V$, which follows from the above inequality for any small positive h_i^* exceeding $k/(V - \frac{n-k}{C-h_i^*})$ (Note that for large V and C the latter fraction is positive but close to 0.) In fact, in our numerical experiments, we experienced no overflow problem even when we simply set $h_i = 0$ for all i and choose t_{i+1} (in algorithms 9.1 and 8.1a) according to the formula

$$t_{i+1} = \max\left(0.9t\ ,\ \frac{2(h_i+1)^2(n-k)(b_i-a_i)}{(N_i-1-2h_i)(N_i-2-2h_i)k(1+\rho_i^*)}\right) = \max\left(0.9t, \frac{2(n-k)(b_i-a_i)}{(N_i-1)(N_i-2)k(1+\rho^2)}\right),$$

$$\rho_i^* = \frac{2M_i}{k} \tag{9.2}$$

[cf. (11.4)]. In section 11, we show rapid convergence of algorithm 9.1 already for $N = \Theta n^{1/2} + 2$, $\Theta > 4$, and indicate an extension to any $\Theta > \sqrt{6}$.

Remark 9.1. [BP91], [BP92] use Newton's iteration to ensure faster convergence of the divide-and-conquer (d.-c.) eigenvalue algorithms [C], [DS]. We may further improve this iteration, by using our algorithm 9.1. *Its power is accentuated in the case of the d.-c. algorithms*, which readily furnish us with splitting points for the eigenvalues of A (cf. [BP91], [BP92]).

10 Analysis of algorithm 7.1

Analyzing algorithm 7.1, we simplify the notation by replacing a^* by a and b^* by b, assume that $2h_i < N_i - 1$, and recall that

$$-p'(x)/p(x) = \text{trace}(\,(A - xI)^{-1}) = \sum_{r=1}^{n} 1/(\lambda_r - x)\ ,$$

$$a \le \lambda_r < b\ , \qquad r = j+1, \ldots, j+k\ ,$$

$$\lambda_r \le a - C\ , \qquad r = j+k+1, \ldots, n\ ,$$

$$\lambda_r \ge b + C\ , \qquad r = 1, \ldots, j\ ,$$

where $C = (b-a)(N-1)/2$ [as in (7.1)].

For large C and N and small positive h_0, the reciprocals of the eigenvalues of $A - xI$ from the interval $[a-x, b-x)$ dominate in the sum $-p'(x)/p(x) = \sum_{r=1}^{n} 1/(\lambda_r - x)$ if $a \le x < b$. Therefore, $-p'(x)/(kp(x))$ closely approximates the average value S_0/k of these k largest reciprocals. On the other hand, k/S_0 lies between $\lambda_{j+k} - x$ and $\lambda_{j+1} - x$, and consequently, the value $-kp(x)/p'(x)$ lies in or near the interval $[\lambda_{j+k} - x, \lambda_{j+1} - x)$. Knowing $-kp(x)/p'(x)$ for $x = c_0$, we may cover the latter unknown interval by a small interval lying about μ_0 of (7.4) and having a higher isolation ratio than

$[a, b)$. We will next formalize this argument and will apply it recursively, proving both rapid growth of the isolation ratio and rapid decrease of the interval length in this recursive process.

Let us examine step i, for $i = 0$. Write $h = h_0$, $M = M_0$ (to simplify the notation). Since $c_0 = b + (b-a)h$ [see (7.3)], the inequalities listed in the beginning of this section imply that

$$(a-b)(h+1) \le \lambda_r - c_0 < (a-b)h \ , \qquad r = j+1, \dots, j+k \ ,$$

$$\lambda_r - c_0 \le (N+1+2h)(a-b)/2 \ , \qquad r = j+k+1, \dots, n \ ,$$

$$\lambda_r - c_0 \ge (N-1-2h)(b-a)/2 \ , \qquad r = 1, \dots, j \ .$$

Therefore,

$$S_0 = \sum_{r=j+1}^{j+k} \frac{1}{\lambda_r - c_0} \le \frac{k}{(a-b)(h+1)} \ ,$$

$$|S_0| \ge \frac{k}{(b-a)(h+1)} \ , \tag{10.1}$$

$$\frac{2(n-j-k)}{(N+1+2h)(a-b)} \le S_1 = \sum_{r=1+j+k}^{n} \frac{1}{\lambda_r - c_0} < 0 \ ,$$

$$0 < S_2 = \sum_{r=1}^{j} \frac{1}{\lambda_r - c_0} \le \frac{2j}{(N-1-2h)(b-a)} \ ,$$

$$|S_1 + S_2| \le 2M/(b-a) \ ,$$

$$M = \max\{\frac{n-j-k}{N+1+2h} \ , \ \frac{j}{N-1-2h}\} \le \frac{n-1}{N-1-2h}$$

[compare (7.5)]. It follows that

$$-\frac{p'(c_0)}{k\,p(c_0)} = \frac{1}{k}\sum_{r=1}^{n} \frac{1}{\lambda_r - c_0} = \frac{S_0}{k}(1 + \frac{S_1+S_2}{S_0}) = \frac{S_0}{k}(1+\rho) \ , \qquad \rho = \frac{S_1+S_2}{S_0} \ ,$$

$$-\frac{k\,p(c_0)}{p'(c_0)} = \frac{k}{(1+\rho)S_0} \ ; \tag{10.2}$$

consequently,

$$|\rho| = |S_1+S_2|/|S_0| \le 2(h+1)\ M/k \le \frac{2(h+1)(n-1)}{k(N-1-2h)} \ . \tag{10.3}$$

We deduce from (7.1) that

$$\frac{1}{\lambda_{j+1} - c_0} \le \frac{S_0}{k} = \frac{1}{k}\sum_{r=j+1}^{j+k} \frac{1}{\lambda_r - c_0} \le \frac{1}{\lambda_{j+k} - c_0} \ .$$

Therefore,

$$\lambda_{j+k} \le (k/S_0) + c_0 \le \lambda_{j+1} \ . \tag{10.4}$$

On the other hand, we recall from (7.4) and (7.6), for $i = 0$, that

$$\mu_0 = c_0 - k\,p(c_0)/p'(c_0) \ , \tag{10.5}$$

$t_1 = 2(b-a)(h+1)^2 M/(k-2(h+1)M)$. (10.6)

Later on we will show that under the latter choice of t_1 we have $2t_1 < b-a$. Our choice of h and N guarantees that $p'(c_0) \neq 0$ (since h was chosen less than $\frac{(N-1)k+2-2n}{2(n+k-1)}$) and $|\rho| < 1$ (cf. (10.2) and remark 7.1), and we deduce from (10.3) that

$$|\rho/(1+\rho)| \leq \frac{2(h+1)M}{k(1-|\rho|)} \leq \frac{2(h+1)M}{k(1-2(h+1)M/k)} = \frac{2(h+1)M}{k-2(h+1)M} \ .$$

By combining the latter inequality with the bound $k/|S_0| \leq (b-a)(h+1)$, of (10.1) and with the equations (10.6) and

$$\frac{k|\rho|}{|(1+\rho)S_0|} = k \ \left| \ \frac{p(c_0)}{p'(c_0)} + \frac{1}{S_0} \ \right|$$

[implied by (10.2)], we obtain that

$$t_1 \geq \frac{k|\rho|}{|(1+\rho)S_0|} = k \ \left| \ \frac{p(c_0)}{p'(c_0)} + \frac{1}{S_0} \ \right| \ . \tag{10.7}$$

¿From (10.4) and (10.7), we deduce that

$$\lambda_{j+1} + t_1 \geq (k/S_0) + c_0 + k \ \left| \ \frac{p(c_0)}{p'(c_0)} + \frac{1}{S_0} \ \right| \geq c_0 - kp(c_0)/p'(c_0) \ ,$$

and due to (10.5), we conclude that $\lambda_{j+1} + t_1 \geq \mu_0$. Similarly, we deduce from (10.4), (10.5) and (10.7) that $\lambda_{j+k} - t_1 \leq \mu_0$.

If $t_1 \leq t$, we satisfy (7.2) by choosing $\mu = \mu_0$. Otherwise, we have 3 cases:

Case a). $n_-(\mu_0 - t_1) > n_-(a)$. Then $\lambda_{j+k} < \mu_0 - t_1 \leq \lambda_{j+1}$, and $\mu = \mu_0 - t_1$ satisfies (7.2).

Case b). $n_-(\mu_0 - t_1) = n_-(a)$, $n_-(\mu_0 + t_1) < n_-(b)$. Then $\lambda_{j+k} \leq \mu_0 + t_1 < \lambda_{j+1}$, and $\mu = \mu_0 + t_1$ satisfies (7.2).

Case c). $n_-(\mu_0 - t_1) = n_-(a)$, $n_-(\mu_0 + t_1) = n_-(b)$. Then $\mu_0 - t_1 \leq \lambda_{j+k} \leq \lambda_{j+1} < \mu_0 + t_1$, and by setting

$$a_1 = \mu_0 - t_1 \ , \qquad b_1 = \mu_0 + t_1 \ ,$$

we bracket the eigenvalues $\lambda_{j+k}, \ldots, \lambda_{j+1}$ in the interval $[a_1, b_1)$ of length $2t_1$. The distance from μ_0 to the closest eigenvalue of A lying outside the interval $[a_1, b_1)$ is at least $C - t_1$ [for C of (7.1)]. Therefore, the isolation ratio of this interval is at least

$$N_1 = (C/t_1) - 1 = \frac{b-a}{2t_1}(N-1) - 1 = \frac{(N-1)(k-2(h+1)M)}{4(h+1)^2 M} - 1 \ , \tag{10.8}$$

which is (7.7) for $i = 0$. We choose N so as to ensure that $N_1 + 1 > N - 1$ (cf. (7.5)). Then $2t_1 = b_1 - a_1 < b - a$ [cf. (10.6), (10.8)], and the first step of algorithm 7.1 either solves problem 7.1 or reduces it to the same problem, but with a, b, N replaced by a_1, b_1, N_1, respectively. We recursively repeat the i-th step of algorithm 7.1, for $i = 1, 2, \ldots$.

Substitute the bound $M_i \le \dfrac{k}{N_i - 1 - 2h_i}$, implied by (7.5), into (7.6) and (7.7) and deduce that

$$N_{i+1} \ge (N_i - 1)(N_i - 1 - 2h_i)\frac{k - 2(h_i+1)M_i}{4(h_i+1)^2(n-1)} - 1 \ ,$$

$$b_{i+1} - a_{i+1} = 2t_{i+1} = 2t_i \frac{N_i - 1}{N_{i+1} + 1} \le \frac{4(b_i - a_i)(h_i+1)^2(n-1)}{(N_i - 1 - 2h_i)(k - 2(h_i+1)M_i)} \ ,$$

for $i = 0, 1, \ldots$. For larger N, quadratic growth of N_i and $1/t_i$ follows as $i \longrightarrow \infty$:

$$\frac{t_{i+1}}{t_i} = \frac{b_{i+1} - a_{i+1}}{b_i - a_i} = O(\frac{n}{kN_i}) \ , \quad N_i^2/N_{i+1} = O(n/k) \ .$$

(Note that by (7.5) and (7.6), $t_{i+1}N_i = O((b_i - a_i)n)$.)

If $h_i = 0$ for all i, the above lower bound on N_{i+1} implies that

$$\begin{aligned}
(4n-4)(N_{i+1}+1) &\ge (N_i - 1)^2(k - 2M_i) \\
&\ge (N_i - 1)^2(k - (2n-2)/(N_i - 1)) \\
&= (N_i - 1)(kN_i - 2n - k + 2) \\
&\ge (N_i - 1)(N_i - 2n + 1) \ .
\end{aligned}$$

Remark 10.1 Note that the latter inequality becomes stronger for $k > 1$, and so is the estimate (10.10) below.

Assume that $N = \gamma_0 n$, $\gamma_0 > 6$, and recursively deduce that

$$N_{i+1} > \gamma_{i+1} n \ , \quad \gamma_{i+1} = (\gamma_i - 2)\,\gamma_i/4 > 6 \ , \quad i = 0, 1, \ldots \ .$$

Set $\gamma_i = 4\gamma_i^* + 2$, $i = 0, 1, \ldots$, and obtain that $\gamma_{u+i}^* > (\gamma_u^*)^{2^i}$ for all integers $i > 0$ and $u \ge 0$. It follows that, for any fixed $u \ge 0$,

$$N_{i+u} > (4(\gamma_u^*)^{2^i} + 2)n \ , \quad \frac{t_{i+u+1}}{t_{i+u}} = \frac{N_{i+u} - 1}{N_{i+u+1} + 1} \le \frac{4n-4}{N_{i+u} - 2n + 1} < (\gamma_u^*)^{-2^i} \ ,$$

$$t_{i+u+1} < (\gamma_u^*)^{1-2^{i+1}} t_u \ , \qquad i = 0, 1, \ldots \ . \tag{10.9}$$

In particular, for $u = 0$, we obtain that $t_{i+1} < (\gamma_0^*)^{1-2^{i+1}}(b-a)/2$ (and in fact, a little stronger bound can be obtained for $u > 0$). Therefore,

$$t_i < t \quad \text{if} \quad i \ge \lceil \log(1 + \log(\frac{b-a}{2t})/\log\gamma_0^*) \rceil \ ,$$

or, equivalently, if $i \ge \widehat{T}(\gamma_0^*)$, for

$$\widehat{T}(\gamma_0^*) = \lceil \log(1 + H/\log\gamma_0^*) \rceil \tag{10.10}$$

and for H of (3.2). Thus, $\widehat{T}(\gamma_0^*)$ recursive steps of algorithm 7.1 suffice in order to solve problem 7.1, assuming that $N = \gamma_0 n$, $\gamma_0 > 6$ [cf. (4.2)], $\gamma_0^* > 1$, and $h_i = 0$ for all i. In particular, we have

$$\widehat{T}(2) = \lceil \log(H+1) \rceil \ , \quad \text{for} \quad N = 10n \ ,$$

$$\widehat{T}(16) = \lceil \log(H+4) \rceil - 2 \ , \quad \text{for} \quad N = 66n \ .$$

11 Analysis of algorithm 9.1

We will analyze algorithm 9.1 by extending our analysis from section 10 and specifying N_i for all i. For $S_0 = \sum_{r=j+1}^{j+k} \frac{1}{\lambda_r - c_0}$, we have

$$q_0 = S_0 + \sum_{r=1}^{j} d_r + \sum_{r=j+k+1}^{n} d_r \ , \tag{11.1}$$

$$d_r = \frac{1}{\lambda_r - c_0} - \frac{1}{\lambda_r^* - c_0} = \frac{\lambda_r^* - \lambda_r}{(\lambda_r - c_0)(\lambda_r^* - c_0)} \ , \quad \text{for all } r \ . \tag{11.2}$$

We recall that

$$\frac{1}{|\lambda_r - c_0|} \leq \frac{2}{(N-1-2h)(b-a)} \ ,$$

for $r \leq j$ and for $r > j+k$, which we extend to the bound

$$\frac{1}{|\lambda_r^* - c_0|} \leq \frac{2}{(N-2-2h)(b-a)} \ ,$$

due to (9.1). Combine these bounds with (9.1), (11.1), and (11.2) and obtain that

$$|q_0 - S_0| \leq (n-k)/(\,(N-1-2h)(N-2-2h)t^*) \ .$$

Write $\hat{\rho} = (q_0 - S_0)/S_0$, so that $q_0 = (1+\hat{\rho})S_0$. Deduce from the latter relations and from (10.1) and (9.1) that

$$k/|S_0| \leq (b-a)(h+1) \ ,$$

$$\hat{\rho} \leq |\rho^*| \ , \quad \rho^* := 2(h+1)(n-k)/(\,(N-1-2h)(N-2-2h)k) \ . \tag{11.3}$$

Our choice of (small) h and (large) N will guarantee that $|\hat{\rho}| < 1$ (cf. remark 7.1), and we will obtain the following bound:

$$|k/S_0 - k/q_0| = |\hat{\rho}(k/S_0)/(1+\hat{\rho})| \leq t_1 \ ,$$

$$t_1 := 2(h+1)^2(n-k)(b-a)/(\ (N-1-2h)(N-2-2h)k(1+\rho^*)) \ . \tag{11.4}$$

We deduce from (10.4) that

$$\lambda_{j+k} - t_1 \leq \mu_0^* = c_0 + k/q_0 \leq \lambda_{j+1} + t_1 \ .$$

Thus, step 0 of algorithm 9.1 either solves problem 4.1 or, else, brackets the eigenvalues $\lambda_{j+k}, \ldots, \lambda_{j+1}$ in the interval $[a_1, b_1)$ of length $2t_1$, where $a_1 = \mu_0^* - t_1$, $b_1 = \mu_0^* + t_1$, and t_1 is defined by (11.4).

The isolation ratio of this interval is at least

$$\begin{aligned} N_1 = \ & (b-a)(N-1)/(2t_1) - 1 \\ = \ & |1+\rho^*|(N-1)(N-1-2h)(N-2-2h)k/(4(h+1)^2(n-k)) - 1 \ , \end{aligned} \tag{11.5}$$

which is substantially greater than N_1 of (10.8) for large $N = N_0$.

Replacing a, b, N by a_1, b_1, N_1, we may recursively repeat the computations. For $N = \Theta\, n^{0.5+v}$, $\Theta \geq 1$, we have

$$\Theta\, n^{0.5+3v}/N_1 = O(1)\ ,\ \text{as}\ v \longrightarrow \infty\ ,$$

which shows a *nearly cubic growth* of the isolation ratio in the transition from $[a, b)$ to $[a_1, b_1)$. $b - a$ decreases at a similar rate.

Let us set $h = 0$, denote $N = N_0$, and obtain from (11.3) and (11.5) that

$$(4n-4)(N_1+1) \geq (N_0-1)[(N_0-1)(N_0-2) - 2(n-1)] = (N_0-1)[(N_0)^2 - 3N_0 - 2n + 4]\ .$$

Similarly, we may bound the isolation ratios N_{i+1} in terms of N_i at the next recursive steps, for $i = 1, 2, \ldots$, provided that $h_i = 0$ for all i. Setting $N = N_0 = \Theta_0 n^{1/2} + 2$, for $\Theta_0 > 4$, we may recursively deduce from these bounds that

$$N_{i+1} > \Theta_{i+1} n^{1/2} + 2\ ,\quad \Theta_{i+1} = (\Theta_i^2 - 2)\Theta_i/4\ ,\qquad i = 0, 1, \ldots\ .$$

Denote $\Theta_i^* = (\Theta_i/2) - 1$ and obtain that

$$\Theta_i = 2\Theta_i^* + 2\ ,\quad N_{i+1} > (2\Theta_{i+1}^* + 2)n^{1/2} + 2\ ,\quad \Theta_{i+1}^* > (\Theta_i^*)^3\ ,\qquad i = 0, 1, \ldots\ .$$

Therefore, for all integers $i > 0$, $u \geq 0$, we have

$$\Theta_{i+u}^* > (\Theta_u^*)^{3^i}\ ,\quad N_{i+u} > (2(\Theta_u^*)^{3^i} + 2)n^{1/2} + 2\ .$$

For any fixed $u \geq 0$, we have

$$t_{i+u+1}/t_{i+u} = (N_{i+u} - 1)/(N_{i+u+1} + 1) \leq \frac{4n-4}{(N_{i+u})^2 - 3N_{i+u} - 2n + 4} < (\Theta_u^*)^{-3^i}\ ,$$

$i = 0, 1, \ldots$, and consequently,

$$t_{i+u+1} < (\Theta_u^*)^{(1-3^{i+1})/2} t_u\ ,\quad i = 0, 1, \ldots\ . \tag{11.6}$$

In particular, for $u = 0$, we obtain that

$$t_{i+1} < (\Theta_0^*)^{(1-3^{i+1})/2}(b-a)/2\ .$$

Therefore, for H of (3.2), denoting $\log((b-a)/(2t))$, we obtain that

$$\widetilde{T}(\Theta_0^*) = \lceil (\log(1 + 2H/\log\Theta_0^*))/\log 3 \rceil \tag{11.7}$$

recursive steps of algorithm 9.1 suffice in order to solve problem 7.1 provided that $h_i = 0$ for all i, $N = (2\Theta_0^* + 2)n^{1/2} + 2$, $\Theta_0^* > 1$, $\Theta_0 = 2\Theta_0^* + 2 > 4$ [cf. (11.3)]. In particular, we obtain that

$$\widetilde{T}(2) = \lceil (\log(1 + 2H))/\log 3 \rceil \ , \quad \text{for} \quad N = 6n^{1/2} + 2 \ ,$$

$$\widetilde{T}(16) = \lceil (\log(2 + H) - 1)/\log 3 \rceil \ , \quad \text{for} \quad N = 34n^{1/2} + 2 \ .$$

Remark 11.1. By choosing $u > 1$ and writing $N = \Theta_0 n^{1/2} + 2$, we may extend (11.7) to similar bounds for any $\Theta_0^* > \sqrt{3/2} - 1$ or, equivalently, for any $\Theta_0 > \sqrt{6}$ [cf. (4.3)].

Remark 11.2. To accelerate convergence at the expense of performing a little more work per iteration, we may generalize algorithms 7.1 and 9.1 by replacing (7.4) by more general expressions, such as

$$\tilde{\mu}_i = c_i - (k/\tilde{q}_i)^{1/d} \ ,$$

$$\tilde{q}_i = \sum_{r=1}^{n} \frac{1}{(\lambda_r - c_i)^d} - \sum_{r=1}^{j} \frac{1}{(\lambda_r^* - c_i)^d} - \sum_{r=j+k+1}^{n} \frac{1}{(\lambda_r^* - c_i)^d} \ ,$$

for some fixed natural $d > 1$, say, for $d = 3$. Note that the value

$$\sum_{r=1}^{n} \frac{1}{(\lambda_r - c_i)^d} = \text{trace}\left((A - c_i I)^{-d} \right)$$

can be computed by extending the techniques of section 2. (In the extension of the same approach to approximating polynomial zeros, cited in the introduction, the latter value can be easily obtained from the d leading coefficients of the input polynomial $p(x)$, by using either Newton's identities or a simpler known algorithm, cf. pp. 34–35 of [BP94].)

12 Summary of the complexity estimates

We are ready to summarize our previous analysis so as to estimate the arithmetic complexity of approximating the k eigenvalues $\lambda_{j+k}, \ldots, \lambda_{j+1}$, assuming (3.1). We recall that approximating all the k eigenvalues in the input interval $J = [a, b)$ requires at most $2k - 1$ calls for algorithms 8.1 or 8.1a, that is, at most $(2k - 1)(T_0 + T_1(N))$ evaluations of $n_-(x)$, for $k \leq n$, and $(2k - 1)T_2(N)$ evaluations of $p(x)/p'(x)$, where [compare (3.2) and (6.3)] $T_0 = 1 + (g_1 + 1)g_1/2$, $g_1 = \lceil \log(H - 1) \rceil$, and $T_1(N) = \lceil \log((N - 1)/2) \rceil$ are the numbers of the evaluations of $n_-(x)$ in each application of the algorithms of sections 5 and 6, respectively, and $T_2(N) = \lceil \log(cH + d) \rceil$ is the number of the evaluations of $p(x)/p'(x)$ in each application of one of algorithms 8.1 or 8.1a. The constants c and d depend on the choice between algorithms 8.1 and 8.1a and on the choice of the values N and h_i. In particular, by choosing algorithm 8.1 and setting $N = (4\gamma_0^* + 2)n$, $h_i = 0$, for all i, we arrive at

$T_2(N) = \widehat{T}(\gamma_0)$, where $\widehat{T}(\gamma_0)$ satisfies (10.10). Applying algorithms 8.1*a* and 9.1, we recall about the need for $3n$ extra arithmetic operations in every iteration. By using the worst case operation count for the evaluation of $p(x)$ and $R_n^*(x) = p'(x)/p(x)$ from section 2, we obtain that

$$(2k-1)(n \pm O(1))(4T_0 + 4T_1(N) + \nu T_2(N)) + n - 1 \tag{12.1}$$

arithmetic operations and comparisons suffice for approximating (within an error tolerance t) the k eigenvalues of A in $J = [a, b)$ [cf. (3.1)] (for any choice of N satisfying (4.2) or (4.3) for $k = n$) provided that either $N > 6n$ and $\nu T_2(N) = 8\widehat{T}(\gamma_0^*)$ [compare (4.2) and (10.10)] or $N > \sqrt{6n} + 2$ and $\nu T_2(N) = 11\widetilde{T}(\Theta_0^*)$ [compare (11.7) and remark 11.1], depending on which of algorithms 8.1 or 8.1a we apply. (12.1) implies the 2 following estimates for the numbers of arithmetic operations involved when our 2 algorithms are applied in order to approximate the k eigenvalues of (3.1), respectively:

$$(2k-1)(n \pm O(1))[2\lceil \log(H-1) \rceil (1 + \lceil \log(H-1) \rceil) + 4 \log n + 8 \log H \pm O(1)], \tag{12.2}$$

$$(2k-1)(n \pm O(1))\,[2\lceil \log(H-1) \rceil (1 + \lceil \log(H-1) \rceil) + 2 \log n + 11 \log H / \log 3 \pm O(1)]\,, \tag{12.3}$$

where $11/\log 3 \approx 6.94$. The bound (12.3) is superior to (12.2), thus suggesting a lower complexity of our second algorithm, which, however, requires some additional assumptions and also is built on the top of the first one. The operation count above includes

$$(2k-1)(n \pm O(1))(T_0 + T_1(N)) = (2k-1)(n \pm O(1))(1 + (g_1+1)g_1/2 + \lceil \log((N-1)/2) \rceil\ )$$

comparisons needed for calculation of the sign agreements (see section 2), where $g_1 = \lceil \log(H-1) \rceil$ and N is defined by (4.2) or (4.3). This count, however, does not include the cost of the $(2k-1)nT_2(N)$ tests determining whether $R_j = 0$ or $R_j \neq 0$ and involved in the computation of $p'(x)/p(x)$. The estimates (12.1)$-$(12.3) are the worst case estimates, which tend to be overly pessimistic for the average input (cf. remarks 6.1, 8.1 and 10.1).

13 Numerical Experiments

Two sets of numerical experiments have been performed to compare the bisection algorithm with algorithms 8.1 and 8.1a. In the first set of experiments we computed all of the eigenvalues of symmetric tridiagonal matrices, and in the second set we computed a single eigenvalue.

For algorithm 8.1 we set $N = 8n$, and for algorithm 8.1a we set $N = 4\sqrt{n} + 2$. (Even though the latter choice of N corresponds to the choice of $\Theta_0 = 4$, $\Theta_0^* = 1$, the cubic convergence was expected and actually observed due to the *strict* inequality $N_{i+1} > (2\Theta_{i+1} + 2)n^{1/2} + 2$.) In both cases we always

set $n_i = 0$. For all algorithms, the endpoints of an interval containing all eigenvalues were found by using the Gershgorin circle theorem [GL]. The experiments were performed in standard IEEE double precision arithmetic.

Even though in this paper we described our algorithms performed with infinite precision, they turned out to be robust enough so that their implementation with finite (double) precision only required a single and very minor change and only in the case of algorithm 8.1a. The analysis in section 11 allows us to choose t_{i+1} according to

$$t_{i+1} = \frac{2(h_i+1)^2(n-k)(b_i-a_i)}{(N_i-1-2h_i)(N_i-2-2h_i)k(1+\rho_i^*)} \quad .$$

However, with such a choice of t_{i+1} the numerical value of $n_-(\mu_i + t_{i+1})$ was often equal to the numerical value of $n_-(\mu_i - t_{i+1})$. We, therefore, computed t_{i+1} according to (9.2), which did not allow the suspect intervals to get too small. This was, of course, just a translation of the above stopping criteria into a language understood by a computer: when t_{i+1} is set to $0.9t$ the algorithm should terminate.

In order to improve the performance of our algorithms in practice, we made some small changes versus sections 7–12 when we implemented algorithms 8.1 and 8.1a. These changes do not affect the worst case complexity bounds for those algorithms.

For convenience, we stored the suspect intervals in an ordered doubly linked list. This allowed us to quickly compute a lower bound for the isolation ratio of a suspect interval from the length of the interval and the distance between the interval and its neighbors.

We used this approach instead of relying on (7.7) when we computed N_{i+1} (lower bounds on the isolation ratios) in algorithms 7.1 and 9.1. Because these calculated lower bounds were at least as strong as (7.7), we did not make the worst case performance bounds any worse, and in practice we improved the performance.

Secondly, if during the double exponential sieve process we could bound the isolation ratio of the suspect interval by 2, we stopped the double exponential sieve process and then performed a single bisection step to bring the isolation ratio to at least 3. Because the double exponential sieve process would have had to use at least one additional evaluation of $n_-(x)$ to increase the isolation ratio to 3, we again did not affect the worst case bounds.

Thirdly, in step 2 of algorithm 8.1 (or its modification), we stopped the bisection steps when we computed a lower bound on the isolation ratio that was greater than N; this clearly never required more, and in fact sometimes used fewer, bisection steps than the $\lceil \log((N-1)/2) \rceil$ steps that would otherwise be required for step 2 of Algorithm 8.1.

To describe the final change, let the input interval to the double exponential sieve process be an interval $J = [a, b)$. If we know that there are no eigenvalues in $[a - (b - a), a)$, or that there are no eigenvalues in $[a, b + (b - a))$, then the actual purpose of performing the bisection step at the beginning of the double exponential sieve process is already achieved, and we can skip this step. Because we stored the suspect intervals in an ordered doubly linked list, we could sometimes make that determination and skip the bisection step at the beginning of the double exponential sieve process.

For the numerical experiments, we have chosen t by setting the *relative error*, $t/(\lambda_1 - \lambda_n)$, equal to 10^{-15}, 10^{-11}, and 10^{-7}. We computed t by first computing λ_1 and λ_n with the LAPACK subroutine dstev [A], these eigenvalues could have been alternatively estimated with Gershgorin's circle theorem.

We compared the results computed with the bisection algorithm and algorithms 8.1 and 8.1a with those computed by the LAPACK subroutine. The differences between the eigenvalues computed with algorithms 8.1 and 8.1a and the eigenvalues computed with the LAPACK subroutine were always smaller than the requested precision. The differences between the eigenvalues computed with the bisection algorithm and the eigenvalues computed with the LAPACK subroutine were smaller than the requested precision when the relative error was set to 10^{-13} or larger, but they were sometimes up to 44% larger than the requested precision when the relative error was set to 10^{-15}. This discrepancy can be explained by the fact that the LAPACK subroutine does not, of course, compute the exact eigenvalues.

We measured the costs of using the various algorithms both by the actual running time of the algorithms (on an IBM RISC System / 6000 model 530) and by the number of computations of $n_-(x)$ [$4n - O(1)$ operations] and equivalents. The advantage of the first method is that it takes all overheads into account, while the second method is machine and code independent. (The code we wrote was not highly optimized. The timings for all algorithms would clearly improve with hand tuning.) We counted computing $p(x)/p'(x)$ [$8n - O(1)$ arithmetic operations] as equivalent to 2 computations of $n_-(x)$, and we counted computing

$$-\sum_{r=1}^{j} \frac{1}{\lambda_r^* - c_i} - \sum_{r=j+k+1}^{n} \frac{1}{\lambda_r^* - c_i}$$

[in $3n - O(k+1)$ operations] as equivalent to 3/4 of the cost of computing $n_-(x)$.

We ran the numerical experiments described in this section on the ten matrices discussed in [PS]. In Tables 13.1–13.3 we give the costs (both in terms of computations of $n_-(x)$ and equivalents and in milliseconds) of computing all the eigenvalues of these ten matrices with the bisection algorithm, algorithm 8.1 and algorithm 8.1a.

When we measured the cost of performing the algorithms by the number of computations of $n_-(x)$

and equivalents, algorithm 8.1a was almost always more efficient than algorithm 8.1. For a relative error of 10^{-15}, algorithm 8.1a required only about 57% of the computations of $n_-(x)$ and equivalents used by the bisection algorithm for all ten matrices. The improvement over the bisection algorithm became smaller as the requested precision was made larger, until for a requested relative precision of 10^{-7} the bisection algorithm used fewer computations of $n_-(x)$ and equivalents than algorithm 8.1a.

When we used actual timings, we have found out that algorithm 8.1 was overall more efficient than algorithm 8.1a. For all ten matrices, algorithm 8.1 used 68% of the time used by the bisection algorithm when the requested relative error was 10^{-15}. The improvement over the bisection algorithm became smaller as the requested precision was made larger, until for a requested relative precision of 10^{-7} the bisection algorithm used less time than algorithm 8.1 for all ten matrices.

These experimental results do not show the quadratic or cubic convergence in the Newton iteration stage of algorithms 8.1 and 8.1a, of course, since besides this stage the algorithms generally include the slower bisection stages (needed for increasing the isolation ratios) and splitting steps. However, the high-order convergence of the new algorithms ($O((\log H)^2)$ operations, as compared to $O(H)$ for the bisection algorithm) can be seen from the relatively slow increase of the cost of performing these algorithms – when compared to the cost of performing the classical bisection algorithm – as the allowed tolerance to the errors is reduced and higher output precision is required; in fact, for matrix 1 the cost of performing algorithm 8.1a was the same for relative tolerances of 10^{-7}, and 10^{-11}. Indeed, the numerical experiments presented in this section do suggest that algorithms 8.1 and 8.1a can give a significant improvement over bisection when the desired output precision is high, but that this improvement disappears for low output precision. This is consistent with the high order convergence properties of algorithms 8.1 and 8.1a.

In order to judge the performance of algorithm 8.1 for finding a subset of the set of all the eigenvalues of a symmetric tridiagonal matrix, we used both algorithm 8.1 and the bisection algorithm to find λ_1 for the ten test matrices discussed in this paper. (Algorithm 8.1a can only be used to find a proper subset of the eigenvalues without actually computing all of the eigenvalues if those eigenvalues not in the subset are already known.) Let i be the smallest integer for which $\lambda_1 - \lambda_i > 10^{-14} \times \mid \lambda_1 \mid$. For both algorithms, we began with a suspect interval with the left endpoint set to $(\lambda_1 + \lambda_i)/2$. The right endpoint was set by calculating an upper bound on λ_1 with Gershgorin's circle theorem.

For the same values for requested relative tolerances that we used in the previous set of experiments, neither of the two tested algorithms had any splitting steps with this choice for an initial suspect interval. Thus the number of iterations that the bisection algorithm used varied little from matrix to matrix – it depended only on the ratio of the size of the initial suspect interval to the requested

precision, and this ratio did not vary much between matrices.

The method that we used to set the endpoints of the initial suspect interval could be used to give an *a-priori* bound on the isolation ratio of the initial suspect interval, and this bound could be used to speed up algorithm 8.1. However, we did not use this knowledge in implementing algorithm 8.1; we assumed that there could be eigenvalues anywhere in $(-\infty, (\lambda_1 + \lambda_i)/2)$.

The results of this second set of experiments are shown in Tables 13.4–13.6. From these tables, we can see that the story is much the same as when we were computing all of the eigenvalues: implementing algorithm 8.1 has a lower cost than implementing the bisection algorithm when the requested precision is high, while the opposite occurs when the requested output precision is low. However, algorithm 8.1 performed even better in this set of experiments than in the previous set of experiments; we see a greater decrease in the cost of using algorithm 8.1 to find only a single eigenvalue (over finding all the eigenvalues) than we do with the bisection algorithm.

For desired relative tolerances of 10^{-11} and larger, algorithm 8.1 used significantly fewer iteration to caluclate λ_1 for matrix 7 than for the other matrices. The reason why so few iterations were needed is that the largest two eigenvalues of matrix 7 are closely clustered, so the suspect interval with which we began algorithm 8.1 (as well as the bisection algorithm) had its left endpoint very close to λ_1. This resulted in the double exponential sieve algorithm converging quickly to a fairly small interval.

Table 13.1: Cost of three symmetric tridiagonal eigenvalue solvers for the test matrices from [PS] with relative error of 10^{-15}. The cost is given in the number of computations of $n_-(x)$ or equivalents and in milliseconds. The timing results were obtained by averaging over 10,000 runs.

Matrix	Bisection		Alg 8.1		Alg 8.1a	
	Comp $n_-(x)$	ms.	Comp $n_-(x)$	ms.	Comp $n_-(x)$	ms.
1	194	1.277	103	0.912	86.25	1.062
2	1347	59.507	884	35.248	682	38.077
3	1923	142.080	1412	92.526	1096.25	97.389
4	1246	75.144	972	54.444	769.75	52.542
5	691	30.997	569	24.542	474.25	26.276
6	240	1.935	135	1.395	110.5	1.594
7	201	1.934	233	3.491	175.75	2.918
8	626	19.541	512	16.372	391	15.282
9	1292	57.205	879	35.516	677.75	37.606
10	99	4.350	53	2.562	33.75	1.984
All	7859	393.970	5752	267.007	4497.25	274.730

Table 13.2: Cost of symmetric tridiagonal eigenvalue solvers with relative error of 10^{-11}.

Matrix	Bisection		Alg 8.1		Alg 8.1a	
	Comp $n_-(x)$	ms.	Comp $n_-(x)$	ms.	Comp $n_-(x)$	ms.
1	138	0.924	91	0.845	72	0.945
2	927	40.860	796	32.553	620.25	34.785
3	1223	89.655	1240	81.778	1010.75	89.604
4	853	51.019	793	44.096	649.75	43.953
5	372	16.792	371	16.416	320.75	17.225
6	170	1.383	123	1.305	96.25	1.431
7	117	1.153	150	2.781	116.75	2.181
8	429	13.415	395	12.333	308	11.635
9	902	39.838	787	32.255	620.75	34.417
10	71	3.183	49	2.400	33.75	1.977
All	5202	258.221	4795	226.761	3849	238.154

Table 13.3: Cost of symmetric tridiagonal eigenvalue solvers with relative error 10^{-15}.

Matrix	Bisection		Alg 8.1		Alg 8.1a	
	Comp $n_-(x)$	ms.	Comp $n_-(x)$	ms.	Comp $n_-(x)$	ms.
1	86	0.598	79	0.781	72	0.944
2	537	23.824	656	27.486	539.5	30.373
3	573	42.274	695	50.999	729.5	65.533
4	487	29.482	555	32.027	500.5	33.941
5	163	7.532	194	9.019	174	9.133
6	105	0.881	107	1.202	91.5	1.387
7	65	0.667	56	0.756	42.5	0.736
8	248	7.851	270	8.802	224	8.763
9	512	22.811	602	26.102	521	29.280
10	45	2.136	45	2.243	33.75	1.978
All	2821	138.056	3259	159.418	2928.25	182.068

Table 13.4: Cost of computing one eigenvalue with two symmetric tridiagonal eigenvalue solvers for the test matrices from [PS] with relative error of 10^{-15}. The cost is given in the number of computations of $n_-(x)$ or equivalents and in milliseconds. The timing results were obtained by averaging over 10000 runs.

Matrix	Bisection		Alg 8.1	
	Comp $n_-(x)$	ms.	Comp $n_-(x)$	ms.
1	48	0.347	27	0.275
2	47	2.182	32	1.454
3	48	3.675	30	2.092
4	45	2.837	29	1.677
5	48	2.225	29	1.261
6	48	0.423	27	0.305
7	46	0.479	32	0.571
8	45	1.482	28	0.890
9	45	2.085	29	1.263
10	49	2.087	30	1.422
All	469	17.823	293	11.210

Table 13.5: Cost of computing one eigenvalue with two symmetric tridiagonal eigenvalue solvers with relative error of 10^{-11}.

Matrix	Bisection		Alg 8.1	
	Comp $n_-(x)$	ms.	Comp $n_-(x)$	ms.
1	35	0.265	23	0.251
2	34	1.593	28	1.317
3	35	2.693	30	2.089
4	32	2.035	25	1.491
5	35	1.636	29	1.262
6	35	0.320	27	0.306
7	33	0.357	16	0.445
8	32	1.069	24	0.796
9	32	1.499	25	1.131
10	35	1.504	26	1.267
All	338	12.971	253	10.355

Table 13.6: Cost of computing one eigenvalue with two symmetric tridiagonal eigenvalue solvers with relative error of 10^{-7}.

Matrix	Bisection		Alg 8.1	
	Comp $n_-(x)$	ms.	Comp $n_-(x)$	ms.
1	22	0.183	23	0.251
2	20	0.961	24	1.180
3	22	1.721	26	1.865
4	18	1.175	21	1.310
5	22	1.050	25	1.127
6	22	0.217	23	0.280
7	20	0.234	7	0.250
8	19	0.656	20	0.699
9	19	0.917	21	0.995
10	22	0.971	26	1.265
All	206	8.084	216	9.221

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