

Abstract

We consider the two-phase Stefan problem $u_t = \alpha(u)$ where $\alpha(u) = u + 1$ for $u < -1$, $\alpha(u) = 0$ for $-1 \leq u \leq 1$, and $\alpha(u) = u - 1$ for $u \geq 1$. We show that if u is an L^2_{loc} distributional solution then $\alpha(u)$ is continuous.

Regularity for solutions of the two-phase Stefan problem

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1 Introduction

In this paper we will discuss the regularity of weak solutions to the two-phase Stefan problem

$$\frac{\partial u}{\partial t} = \Delta \alpha(u) \tag{1.1}$$

in a domain $\Omega \subset \mathbb{R}^n \times (0, T)$, for some $T > 0$. Here $\alpha(u) = 0$ if $-1 \leq u \leq 1$, $\alpha(u) = u - 1$ for $u > 1$, and $\alpha(u) = u + 1$ for $u < -1$.

We will show that if $u \in L^2_{loc}(\Omega)$ is a solution in the sense of distributions of (1.1) (defined precisely below) then $\alpha(u)$ is continuous. In the case when $u \geq 0$, u is a solution of the one-phase Stefan problem and Andreucci and Korten [AnKo] (see also Korten [Ko]) have shown that if $u \in L^1_{loc}$, then $\alpha(u)$ is continuous. Although we believe this to be true in the two-phase case, we have not been able to obtain this generality and must assume $u \in L^2_{loc}$.

Under the assumption that u is bounded and $\nabla \alpha(u) \in L^2$, Caffarelli and Evans [CaE] showed that $\alpha(u)$ is continuous. Similar results for more general singular parabolic equations were shown by Sacks [S], Ziemer [Z] and by DiBenedetto [DiB]. We will assume these results. We will show that a locally L^2 weak solution of (1.1) satisfies the hypotheses of these results (of any of these authors) to conclude the continuity of $\alpha(u)$.

Related to this equation is the porous medium equation $u_t = \Delta u^m$, $m > 1$. This has been studied extensively by many authors, but we mention in particular the regularity result of Dahlberg and Kenig [DK] who showed that a nonnegative L^m_{loc} solution to the porous medium equation is a.e. equal to a continuous function. The methods in this present paper are descendants (via the work of Andreucci and Korten) of the methods of Dahlberg and Kenig found in [DK]. However, the fact that we are working with solutions which can be both positive and negative complicates matters. To achieve our results we will perform numerous integrations by parts and cannot determine the sign of the resulting boundary terms as in the one-phase case. Consequently we devise a different strategy and introduce new ideas and techniques.

Equation (1.1) is a formulation of the two-phase Stefan problem, describing the flow of heat within a substance which can be in a liquid phase or a solid phase, and for which

there is a latent heat to initiate phase change. This allows for the presence of a “mushy zone”, that is, a region which is between the liquid and solid phases. In this model u represents the enthalpy and $\alpha(u)$ the temperature. We have assumed that the thermal conductivity in both the solid and liquid phases is the same. These conductivities are determined by the slope of the function $\alpha(u)$ in the regions $u \geq 1$, and $u \leq -1$. The results below all continue to hold (with minor modifications) if the slope of $\alpha(u)$ differs in these regions.

We now state our main result. Suppose $u \in L^2_{loc}(\Omega)$ where Ω is a domain contained in $\mathbb{R}^n \times (0, T)$. We consider distributional solutions of the equation $u_t = \Delta\alpha(u)$, that is, u which satisfy

$$\iint_{\Omega} \alpha(u)\Delta\varphi + u\varphi_t dx dt = 0$$

for every $\varphi \in C^\infty$ with compact support in Ω .

Theorem 1.1. *Suppose $u \in L^2_{loc}(\Omega)$ is a solution of $u_t = \Delta\alpha(u)$. Then $\alpha(u)$ is a.e. equal to a continuous function.*

We do not expect, in general, such a result for u . As noted in Korten [Ko1], the solution to the Cauchy problem $u_t = \Delta\alpha(u)$ on \mathbb{R}^{n+1}_+ with initial data $0 \leq u_I(x) \leq 1$ is just $u(x, t) = u_I(x)$. Thus, we cannot expect $u(x, t)$ to be any smoother than $u_I(x)$.

The paper is structured as follows. In section 2 we prove energy estimates for weak solutions of the two phase problem. These show that $\nabla\alpha(u)$ and $\alpha(u)_t$ exist locally in L^2 . In section 3, we show that $|\alpha(u)|$ is subcaloric. An immediate consequence is that $\alpha(u)$ is locally bounded. This, combined with the energy estimates and previously mentioned theorem of DiBenedetto [DiB] (or others mentioned above) gives the continuity of $\alpha(u)$.

Throughout, the letter C will denote a constant which may vary from line to line.

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2 Energy Estimates

We establish that $\alpha(u)$ has derivatives which are locally in L^2 .

Theorem 2.1. *Suppose $\Omega \subseteq \mathbb{R}^{n+1}_+$ and $u \in L^2_{loc}(\Omega)$ is a distributional solution of $u_t = \Delta\alpha(u)$ on Ω . Suppose $r < R$, $T_0 < t_0 < t_1 < T_1$, set $\omega = (t_0, t_1) \times B(x_0, r)$ and $\tilde{\omega} = (T_0, T_1) \times B(x_0, R)$, and suppose the closure of $\tilde{\omega}$ is contained in Ω . Then $\nabla\alpha(u)$, $\alpha(u)_t$ exist in $L^2(\omega)$ and there exists a constant C , depending only on ω and $\tilde{\omega}$ such that*

$$\iint_{\omega} |\nabla\alpha(u)|^2 dx dt \leq C \iint_{\tilde{\omega}} u^2 dx dt \tag{2.1}$$

and

$$\iint_{\omega} \left| \frac{\partial}{\partial t} \alpha(u) \right|^2 dx dt \leq C \iint_{\tilde{\omega}} u^2 dx dt \quad (2.2)$$

Proof. Let $\varphi_m(y, s) = \rho_m(y)\tau_m(s)$, $m = 1, 2, \dots$ where ρ_m, τ_m are smooth mollifiers, radial, centered at 0, compactly supported, and tending to δ_0 . For $(x, t) \in \Omega$ and m sufficiently large (depending on (x, t)), $\varphi_m(x - y, t - s)$ is a test function supported in Ω and thus

$$\iint_{\Omega} u(y, s) \frac{\partial \varphi_m}{\partial t}(x - y, t - s) + \alpha(u(y, s)) \Delta \varphi_m(x - y, t - s) dy ds = 0.$$

In the course of the proof, we will need to define three nested domains between ω and $\tilde{\omega}$. To simplify notation, set $\omega_1 = \omega$, $\omega_5 = \tilde{\omega}$ and we will define ω_2, ω_3 and ω_4 with $\omega_1 \subset \omega_2 \subset \omega_3 \subset \omega_4 \subset \omega_5$.

For $m = 1, 2, 3, \dots$ set

$$u_m(x, t) = \iint_{\Omega} u(y, s) \chi_{\omega_5}(y, s) \varphi_m(x - y, t - s) dy ds.$$

Then for all (x, t) and m , $|u_m(x, t)| \leq M(u \chi_{\omega_5}(x, t))$ where M denotes the Hardy-Littlewood maximal function (in both the variables (x, t)).

Choose a , $\frac{3T_0+t_0}{4} < a < \frac{T_0+t_0}{2}$ and b , $\frac{t_1+T_1}{2} < b < \frac{t_1+3T_1}{4}$ such that

$$\int_{B(x_0, R)} |M(u \chi_{\omega_5})(x, a)|^2 dx \leq C \iint_{\omega_5} |M(u \chi_{\omega_5})(x, t)|^2 dx dt. \quad (2.3)$$

with a similar inequality for b .

In a similar fashion, set $w_m = \alpha(u) \chi_{\omega_5} * \varphi_m$. Define $\omega_4 = B(x_0, \frac{r+3R}{4}) \times (\frac{3T_0+t_0}{4}, \frac{t_1+3T_1}{4})$. Then on ω_4 , $\frac{\partial}{\partial t} w_m - \Delta w_m = 0$ for all m sufficiently large. Using cylindrical coordinates we can choose an r_1 , $\frac{r+R}{2} < r_1 < \frac{r+3R}{4}$ so that

$$\int_{\partial B(x_0, r_1) \times (T_0, T_1)} |M(\alpha(u) \chi_{\omega_5})|^2 d\sigma \leq C \iint_{\omega_5} |M(\alpha(u) \chi_{\omega_5})(x, t)|^2 dx dt. \quad (2.4)$$

Then by (2.3), for all sufficiently large m ,

$$\begin{aligned} \int_{B(x_0, r_1)} u_m(x, a)^2 dx &\leq \int_{B(x_0, R)} |M(u \chi_{\omega_5})(x, a)|^2 dx \\ &\leq C \iint_{\omega_5} |M(u \chi_{\omega_5})(x, t)|^2 dx dt \\ &\leq C \iint_{\omega_5} u^2 dx dt \end{aligned} \quad (2.5)$$

Likewise, by (2.4)

$$\begin{aligned}
\int_{\partial B(x_0, r_1) \times (a, b)} w_m^2 d\sigma &\leq \int_{\partial B(x_0, r_1) \times (T_0, T_1)} |M(\alpha(u)\chi_{\omega_5})|^2 d\sigma \\
&\leq C \iint_{\omega_5} |M(\alpha(u)\chi_{\omega_5})|^2 dx dt \\
&\leq C \iint_{\omega_5} |\alpha(u)|^2 dx dt.
\end{aligned} \tag{2.6}$$

Let $\alpha_m(s)$ be a smooth regularization of $\alpha(s)$ such that $\alpha_m(s) = \alpha(s)$ for $|s| \geq 1 + \frac{1}{m}$, $\alpha_m(s)$ is strictly increasing and $\alpha_m(s) \neq 0$ except for $s = 0$. Put $\omega_3 = B(x_0, r_1) \times (a, b)$. Let v_m be a solution to

$$\begin{cases} v_t = \Delta \alpha_m(v) & \text{on } \omega_3 \\ v(x, a) = u_m(x, a) & x \in B(x_0, r_1) \\ \alpha_m(v) = w_m & \text{on } \partial B(x_0, r_1) \times (a, b). \end{cases}$$

Choose $\phi(x)$ so that $\phi = 0$ on $\partial B(x_0, r_1)$, $\Delta \phi = 1$ on $B(x_0, r_1)$. Then $\phi < 0$ on $B(x_0, r_1)$ and $\frac{\partial \phi}{\partial n} = c_1 > 0$ on $\partial B(x_0, r_1)$, where n is the outward normal and c_1 is a constant depending only on r_1 and the dimension.

By Green's theorem we have

$$\begin{aligned}
&\int_{B(x_0, r_1)} (\alpha_m(v_m))^2 \Delta \phi dx \\
&= \int_{B(x_0, r_1)} \Delta (\alpha_m(v_m))^2 \phi dx + \int_{\partial B(x_0, r_1)} (\alpha_m(v_m))^2 \frac{\partial \phi}{\partial n} d\sigma - \int_{\partial B(x_0, r_1)} \phi \frac{\partial}{\partial n} [\alpha_m(v_m)]^2 d\sigma \\
&= 2 \int_{B(x_0, r_1)} \Delta \alpha_m(v_m) \alpha_m(v_m) \phi dx + 2 \int_{B(x_0, r_1)} |\nabla \alpha_m(v_m)|^2 \phi dx + c_1 \int_{\partial B(x_0, r_1)} \alpha_m(v_m)^2 d\sigma \\
&\leq 2 \int_{B(x_0, r_1)} v_{m,t} \alpha_m(v_m) \phi dx + c_1 \int_{\partial B(x_0, r_1)} \alpha_m(v_m)^2 d\sigma \\
&= 2 \frac{d}{dt} \int_{B(x_0, r_1)} A_m(v_m) \phi dx + c_1 \int_{\partial B(x_0, r_1)} \alpha_m(v_m)^2 d\sigma
\end{aligned}$$

where A_m is an antiderivative of α_m . Integrate from a to b to obtain

$$\begin{aligned}
\int_a^b \int_{B(x_0, r_1)} \alpha_m(v_m)^2 \Delta \phi dx dt &\leq 2 \int_{B(x_0, r_1)} A_m(v_m(x, b)) \phi dx - 2 \int_{B(x_0, r_1)} A_m(v_m(x, a)) \phi dx \\
&\quad + \int_a^b \int_{\partial B(x_0, r_1)} \alpha_m(v_m)^2 d\sigma dt.
\end{aligned}$$

Now $0 \leq A_m(x) \leq x^2$, $\phi < 0$, $\Delta\phi = 1$ and recalling $\omega_3 = B(x_0, r_1) \times (a, b)$, this yields:

$$\begin{aligned}
\iint_{\omega_3} \alpha_m(v_m)^2 dx dt &\leq C \int_{B(x_0, r_1)} v_m(x, a)^2 dx + \int_a^b \int_{\partial B(x_0, r_1)} \alpha_m(v_m)^2 d\sigma dt \\
&= C \int_{B(x_0, r_1)} u_m(x, a)^2 dx + \int_a^b \int_{\partial B(x_0, r_1)} w_m^2 d\sigma dt \\
&\leq C \iint_{\omega_5} u^2 dx dt
\end{aligned} \tag{2.7}$$

where for the last inequality we have used (2.5) and (2.6). Let $\psi(x)$ be a nonnegative $C_0^\infty(\mathbb{R}^n)$ function such that $\psi \equiv 1$ on $B(x_0, \frac{3r+R}{4})$, $\psi \equiv 0$ outside $B(x_0, \frac{r+R}{2})$. To simplify notation set $B(x_0, \frac{3r+R}{4}) = B_1$, $B(x_0, \frac{r+R}{2}) = B_2$. Then

$$\begin{aligned}
\int_{B_2} \psi \alpha_m(v_m) v_{m,t} dx &= \int_{B_2} \psi \alpha_m(v_m) \Delta \alpha_m(v_m) dx \\
&= - \int_{B_2} \nabla \psi \cdot \nabla \alpha_m(v_m) \alpha_m(v_m) dx - \int_{B_2} \psi |\nabla \alpha_m(v_m)|^2 dx \\
&= \frac{1}{2} \int_{B_2} \Delta \psi \alpha_m(v_m)^2 dx - \int_{B_2} \psi |\nabla \alpha_m(v_m)|^2 dx.
\end{aligned}$$

Rearrange and integrate from a to b to obtain

$$\begin{aligned}
\int_a^b \int_{B_2} \psi (\nabla \alpha_m(v_m))^2 dx dt &= \frac{1}{2} \int_a^b \int_{B_2} \Delta \psi |\alpha_m(v_m)|^2 dx dt - \int_a^b \int_{B_2} \psi \frac{d}{dt} A_m(v_m) dx dt \\
&\leq C \int_a^b \int_{B_2} \alpha_m(v_m)^2 dx dt + \int_{B_2} \psi(x) A_m(v_m(x, a)) dx \\
&\leq C \int_a^b \int_{B_2} \alpha_m(v_m)^2 dx dt + \int_{B_2} v_m(x, a)^2 dx \\
&\leq C \iint_{\omega_3} \alpha_m(v_m)^2 dx dt + \int_{B(x_0, r_1)} v_m(x, a)^2 dx \\
&\leq C \iint_{\omega_5} u^2 dx dt
\end{aligned} \tag{2.8}$$

where we have used (2.7) and (2.5) and the definition of v_m for the last inequality.

We now seek a similar estimate for the t derivative. Let $\eta(x)$ be a nonnegative $C_0^\infty(\mathbb{R}^n)$ function such that $\eta \equiv 1$ on $B(x_0, r)$, $\eta \equiv 0$ outside B_1 and so that $\|\frac{\nabla \eta}{\sqrt{\eta}}\|_\infty < \infty$. Note

that $\alpha_m(v_m)_t = \alpha'_m(v_m)v_{mt}$ and $0 < \alpha'_m \leq 1$ so that $(\alpha_m(v_m)_t)^2 \leq \alpha_m(v_m)_t v_{mt}$. Then

$$\begin{aligned}
\int_{B_1} \eta(\alpha_m(v_m)_t)^2 dx &\leq \int_{B_1} \eta \alpha_m(v_m)_t v_{mt} dx \\
&= \int_{B_1} \eta \alpha_m(v_m)_t \Delta \alpha_m(v_m) dx \\
&= - \int_{B_1} \nabla \eta \cdot \nabla \alpha_m(v_m) \alpha_m(v_m)_t dx - \int_{B_1} \eta \nabla \alpha_m(v_m)_t \cdot \nabla \alpha_m(v_m) dx \\
&= - \int_{B_1} \nabla \eta \cdot \nabla \alpha_m(v_m) \alpha_m(v_m)_t dx - \frac{1}{2} \frac{d}{dt} \int_{B_1} \eta |\nabla \alpha_m(v_m)|^2 dx
\end{aligned}$$

Integrate from c to d , where c and d are to be chosen momentarily. We obtain

$$\begin{aligned}
&\int_c^d \int_{B_1} \eta(\alpha_m(v_m)_t)^2 dx dt \\
&\leq \int_c^d \left| \int_{B_1} \sqrt{\eta} \frac{\nabla \eta}{\sqrt{\eta}} \nabla \alpha_m(v_m) \alpha_m(v_m)_t dx \right| dt + \frac{1}{2} \int_{B_1} \eta(x) |\nabla \alpha_m(v_m)(x, c)|^2 dx \\
&\leq \left\| \frac{\nabla \eta}{\sqrt{\eta}} \right\|_{\infty} \left(\int_c^d \int_{B_1} |\nabla \alpha_m(v_m)|^2 dx dt \right)^{\frac{1}{2}} \left(\int_c^d \int_{B_1} \eta(\alpha_m(v_m)_t)^2 dx dt \right)^{\frac{1}{2}} \\
&\quad + \frac{1}{2} \int_{B_1} \eta(x) |\nabla \alpha_m(v_m)(x, c)|^2 dx.
\end{aligned} \tag{2.9}$$

Choose c_m (depending on m), $\frac{T_0+3t_0}{4} < c_m < t_0$, so that

$$\int_{B_1} \eta(x) |\nabla \alpha_m(v_m)(x, c_m)|^2 dx \leq C \int_a^b \int_{B_2} \psi |\nabla \alpha_m(v_m)|^2 dx dt. \tag{2.10}$$

Put $d = t_1$, $c = c_m$ in (2.9). Then recalling that $\psi \equiv 1$ on B_1 , and using (2.10) and (2.8) we have

$$\begin{aligned}
&\int_{c_m}^{t_1} \int_{B_1} \eta(\alpha_m(v_m)_t)^2 dx dt \\
&\leq \left\| \frac{\nabla \eta}{\sqrt{\eta}} \right\|_{\infty} \left(\int_{c_m}^{t_1} \int_{B_2} \psi |\nabla \alpha_m(v_m)|^2 dx dt \right)^{\frac{1}{2}} \cdot \left(\int_{c_m}^{t_1} \int_{B_1} \eta(\alpha_m(v_m)_t)^2 dx dt \right)^{\frac{1}{2}} + C \iint_{\omega_5} u^2 dx \\
&\leq \left\| \frac{\nabla \eta}{\sqrt{\eta}} \right\|_{\infty} \left(\iint_{\omega_5} u^2 dx dt \right)^{\frac{1}{2}} \left(\int_{c_m}^{t_1} \int_{B_1} \eta(\alpha_m(v_m)_t)^2 dx dt \right)^{\frac{1}{2}} + C \iint_{\omega_5} u^2 dx dt
\end{aligned}$$

from which it follows that

$$\int_{c_m}^{t_1} \int_{B_1} \eta(\alpha_m(v_m)_t)^2 dx dt \leq C \iint_{\omega_5} u^2 dx dt$$

and consequently

$$\iint_{\omega_1} (\alpha_m(v_m)_t)^2 dx dt \leq C \iint_{\omega_5} u^2 dx dt. \quad (2.11)$$

Thus, recalling $\omega = \omega_1$, $\tilde{\omega} = \omega_5$, (2.8) and (2.11) give

$$\iint_{\omega} |\nabla \alpha_m(v_m)|^2 dx dt \leq C \iint_{\tilde{\omega}} u^2 dx dt \quad \text{and} \quad \iint_{\omega} (\alpha_m(v_m)_t)^2 dx dt \leq C \iint_{\tilde{\omega}} u^2 dx dt. \quad (2.12)$$

To obtain (2.1) and (2.2) we will need to take limits. We first remark that with more care, similar estimates could be obtained with any compact set $K \subset \omega_3$ replacing $\omega = \omega_1$ on the left hand side of the inequalities in (2.12); naturally, the constants on the right hand side depend on the position of K within ω_3 . Thus, from (2.7) and this observation, we have:

$$\begin{aligned} \iint_{\omega_3} \alpha_m(v_m)^2 dx dt &\leq C \iint_{\tilde{\omega}} u^2 dx dt, & \iint_K |\nabla \alpha_m(v_m)|^2 dx dt &\leq C(K) \iint_{\tilde{\omega}} u^2 dx dt \\ \text{and} \quad \iint_K \left| \frac{\partial}{\partial t} \alpha_m(v_m) \right|^2 dx dt &\leq C(K) \iint_{\tilde{\omega}} u^2 dx dt \end{aligned} \quad (2.13)$$

for every compact $K \subset \omega_3$.

By Rellich-Kondrachov there exists a subsequence $\{\alpha_{m_k}(v_{m_k})\}$ of $\{\alpha_m(v_m)\}$ (which we still write as $\{\alpha_m(v_m)\}$) and $h \in L^2(\omega_3)$ such that $\alpha_m(v_m) \rightarrow h$ in $L^2(K)$ for every compact set $K \subset \omega_3$. By taking subsequences, if necessary, we also may assume this convergence is a.e. By weak compactness, and again, by taking subsequences, we may assume that $\alpha_m(v_m) \rightarrow h$ weakly in $L^2(\omega_3)$. Equation (2.13) implies that the $L^2(\omega_3)$ norms of the v_m are uniformly bounded, hence there exists a subsequence, (still denoted by v_m) such that $v_m \rightarrow v \in L^2(\omega_3)$ weakly.

We claim that $\alpha(v) = h$. First note that $\|\alpha_m - \alpha\|_{\infty} \rightarrow 0$, so that for a.e $x \in \omega_3$, $\alpha(v_m) \rightarrow h$. Consider the set where $h > 0$. Then for a.e x in this set, $\alpha(v_m(x)) \rightarrow h(x) > 0$, and hence $v_m(x) \rightarrow h(x) + 1$. Thus, $v(x) = h(x) + 1$ for a.e x in the set where $h(x) > 0$. Similarly, on $h < -1$, $v(x) = h(x) - 1$ a.e. On the set $h(x) = 0$ we must have $-1 \leq \liminf v_m(x) \leq \limsup v_m(x) \leq 1$ a.e. To see this consider an x at which there exists a subsequence $v_{m_k}(x)$ which converges to $y_0 \notin [-1, 1]$. Then for this x , $\alpha(v_{m_k}(x)) \rightarrow \alpha(y_0) \neq 0$ which implies $\alpha(v_m(x)) \not\rightarrow h(x)$. Thus, $-1 \leq \liminf v_m(x) \leq \limsup v_m(x) \leq 1$ a.e. on $h(x) = 0$, and hence $-1 \leq v(x) \leq 1$ a.e. on $h = 0$. We conclude that $\alpha(v) = h$ a.e.

Summarizing, we have $v_m \rightarrow v$ weakly in $L^2(\omega_3)$ and $\alpha_m(v_m) \rightarrow \alpha(v)$ weakly in $L^2(\omega_3)$, a.e. on ω_3 and in $L^2(K)$ for every compact subset K of ω_3 . To finish the proof we show that $\alpha(u) = \alpha(v)$ a.e. on ω_3 . Using integration by parts, and recalling that

$\alpha_m(v_m) = w_m$ on $\partial B(x_0, r_1) \times (a, b)$, we compute

$$\begin{aligned}
& \iint_{\omega_3} (v_m - u_m)(\alpha_m(v_m) - w_m) dx dt \\
&= \int_a^b \int_{B(x_0, r_1)} \int_a^t v_{mt}(x, \tau) - u_{mt}(x, \tau) d\tau (\alpha_m(v_m(x, t)) - w_m(x, t)) dx dt \\
&= - \int_a^b \int_{B(x_0, r_1)} \int_a^t \nabla(\alpha_m(v_m) - w_m)(x, \tau) d\tau \nabla(\alpha_m(v_m) - w_m) dx dt \\
&= -\frac{1}{2} \int_a^b \int_{B(x_0, r_1)} \frac{d}{dt} \left| \int_a^t \nabla(\alpha_m(v_m) - w_m) d\tau \right|^2 dx dt \\
&= -\frac{1}{2} \int_{B(x_0, r_1)} \left| \int_a^b \nabla(\alpha_m(v_m) - w_m) d\tau \right|^2 dx \leq 0
\end{aligned} \tag{2.14}$$

We need to take limits as $m \rightarrow \infty$ in this inequality. Write

$$\begin{aligned}
& \iint_{\omega_3} (v_m - u_m)(\alpha_m(v_m) - w_m) dx dt = \iint_{\omega_3} v_m \alpha_m(v_m) dx dt + \iint_{\omega_3} v_m (-w_m) dx dt \\
& \quad + \iint_{\omega_3} (-u_m)(\alpha_m(v_m)) dx dt + \iint_{\omega_3} u_m w_m dx dt = I + II + III + IV
\end{aligned}$$

Since $u_m \rightarrow u$ a.e. and in $L^2(\omega_3)$, $w_m \rightarrow \alpha(u)$ a.e. and in $L^2(\omega_3)$, $v_m \rightarrow v$ weakly, and $\alpha_m(v_m) \rightarrow \alpha(v)$ weakly, we conclude

$$\begin{aligned}
II &\rightarrow \iint_{\omega_3} v(-\alpha(u)) dx dt, & III &\rightarrow \iint_{\omega_3} (-u)(\alpha(v)) dx dt, \\
& \text{and } IV &\rightarrow \iint_{\omega_3} u\alpha(u) dx dt.
\end{aligned}$$

Expand out

$$\iint_{\omega_3} (\alpha_m(v_m) - \alpha_m(v))(v_m - v) dx \geq 0,$$

take $m \rightarrow \infty$ (make use of the fact that $\|\alpha_m - \alpha\|_\infty \rightarrow 0$) to conclude

$$\liminf_{m \rightarrow \infty} \iint_{\omega_3} \alpha_m(v_m) v_m dx \geq \iint_{\omega_3} \alpha(v) v dx.$$

This combined with the estimates for II-IV and (2.14) yields

$$\iint_{\omega_3} (v - u)(\alpha(v) - \alpha(u)) dx dt \leq 0.$$

Since the integrand of this is nonnegative, we conclude $\alpha(u) = \alpha(v)$ a.e. on ω_3 . This completes the proof of the theorem. \square

3 $|\alpha(u)|$ is subcaloric

Theorem 3.1. $|\alpha(u)|$ is weakly subcaloric, that is, it satisfies

$$\int_{\Omega} -\nabla|\alpha(u)|\nabla\eta + |\alpha(u)|\eta_t dx dt \geq 0$$

for any nonnegative $\eta \in W_0^{1,2}(\Omega)$.

Proof. Let $0 \leq \eta \in W_0^{1,2}(\Omega)$. For $h > 0$ set

$$\phi_h(x) = \begin{cases} 1 & \text{if } x > h \\ \frac{2}{h}x - 1 & \text{if } \frac{h}{2} \leq x < h \\ 0 & \text{if } |x| < \frac{h}{2} \\ \frac{2}{h}x + 1 & \text{if } -h < x \leq -\frac{h}{2} \\ -1 & \text{if } x < -h. \end{cases}$$

Then $\eta\phi_h(\alpha(u))$ is supported in $\{|\alpha(u)| > \frac{h}{2}\}$ and thus, $\iint (\alpha(u) - u)[\eta\phi_h(\alpha(u))]_t dx dt = 0$.

Then

$$\begin{aligned} 0 &= \iint \alpha(u)[\eta\phi_h(\alpha(u))]_t - \nabla\alpha(u)\nabla[\eta\phi_h(\alpha(u))] dx dt \\ &= \iint \alpha(u)\eta_t\phi_h(\alpha(u)) dx dt + \iint \alpha(u)\eta\phi_h'(\alpha(u))\alpha(u)_t dx dt \\ &\quad - \iint \nabla\alpha(u)\nabla\eta\phi_h(\alpha(u)) dx dt - \iint \nabla\alpha(u)\eta\phi_h'(\alpha(u))\nabla\alpha(u) dx dt \\ &= I + II + III + IV \end{aligned} \tag{3.1}$$

We investigate each of these as $h \rightarrow 0$. As $h \rightarrow 0$, $\phi_h(\alpha(u)) \rightarrow \text{sgn}(\alpha(u))$ so that $I \rightarrow \iint |\alpha(u)|\eta_t dx dt$. To estimate II , first note that

$$\phi_h'(\alpha(u)) = \frac{2}{h}\chi_{\{\frac{h}{2} < |\alpha| < h\}}.$$

Then

$$II = \iint \alpha(u)\eta\frac{2}{h}\chi_{\{\frac{h}{2} < |\alpha(u)| < h\}}\frac{\partial}{\partial t}\alpha(u) dx dt$$

and consequently,

$$|II| \leq \iint |\alpha(u)|\eta\frac{2}{h}\chi_{\{\frac{h}{2} < |\alpha(u)| < h\}}\left|\frac{\partial}{\partial t}\alpha(u)\right| dx dt \leq 2 \iint \eta\chi_{\{\frac{h}{2} < |\alpha(u)| < h\}}\left|\frac{\partial}{\partial t}(\alpha(u))\right| dx dt.$$

Since $\frac{\partial}{\partial t}\alpha(u) \in L_{loc}^2(\Omega)$, $II \rightarrow 0$ as $h \rightarrow 0$

To estimate III , note that when $|\alpha(u)| > h$, $\nabla\alpha(u)\phi_h(\alpha(u)) = \nabla|\alpha(u)|$. And when $\frac{h}{2} < |\alpha(u)| < h$,

$$|\nabla\alpha(u)\phi_h(\alpha(u))| \leq |\nabla\alpha(u)| \left(\frac{2}{h}|\alpha(u)| + 1 \right)$$

Consequently,

$$\left| \iint_{\{\frac{h}{2} < |\alpha(u)| < h\}} \nabla\alpha(u)\nabla\eta\phi_h(\alpha(u))dx dt \right| \leq \iint_{\{\frac{h}{2} < |\alpha(u)| < h\}} |\nabla\alpha(u)| \left[\frac{2}{h}|\alpha(u)| + 1 \right] |\nabla\eta|dx dt$$

$\rightarrow 0$ as $h \rightarrow 0$ since $\nabla\alpha(u) \in L^2_{loc}(\Omega)$.

Therefore, as $h \rightarrow 0$, $III \rightarrow -\iint \nabla|\alpha(u)|\nabla\eta dx dt$. Note that we can write IV as

$$IV = \iint |\nabla\alpha(u)|^2 \eta \phi'_h(\alpha(u)) dx dt = \iint |\nabla\alpha(u)|^2 \eta \frac{2}{h} \chi_{\{\frac{h}{2} < |\alpha(u)| < h\}} dx dt$$

Thus, letting $h \rightarrow 0$ in (3.1) yields:

$$0 = \iint |\alpha(u)|\eta_t dx dt - \iint \nabla|\alpha(u)|\nabla\eta dx dt - \lim_{h \rightarrow 0} \iint |\nabla\alpha(u)|^2 \frac{2}{h} \chi_{\{\frac{h}{2} < |\alpha(u)| < h\}} \eta dx dt$$

from which the theorem follows. □

Remark. Suppose that instead of ϕ_h as defined above, we defined

$$\phi_h(x) = \begin{cases} 1 & \text{if } x > h \\ \frac{2}{h}x - 1 & \text{if } \frac{h}{2} < x < h \\ 0 & \text{otherwise.} \end{cases}$$

Then following the computations as in (3.1) we obtain (3.1) with this version of ϕ_h . In this case $I \rightarrow \iint \alpha(u)^+ \eta_t dx dt$ and as in the above case, $II \rightarrow 0$, and $III \rightarrow -\iint \nabla\alpha(u)^+ \nabla\eta dx dt$.

Now we may write

$$IV = \iint |\nabla\alpha(u)^+|^2 \eta \frac{2}{h} \chi_{\{\frac{h}{2} < \alpha(u) < h\}} dx dt.$$

We obtain:

$$0 = \iint \alpha(u)^+ \eta_t dx dt - \iint \nabla\alpha(u)^+ \nabla\eta dx dt - \lim_{h \rightarrow 0} \iint |\nabla\alpha(u)^+|^2 \frac{2}{h} \chi_{\{\frac{h}{2} < \alpha(u) < h\}} \eta dx dt$$

Thus, $\alpha(u)^+$ is subcaloric. In a similar fashion, we may use the function

$$\phi_h(x) = \begin{cases} \frac{2}{h}x + 1 & -h < x < -\frac{h}{2} \\ -1 & \text{if } x < -h \\ 0 & \text{otherwise} \end{cases}$$

and computations such as those above to obtain

$$0 = \iint \alpha(u)^- \eta_t dx dt - \iint \nabla \alpha(u)^- \nabla \eta dx dt + \lim_{h \rightarrow 0} \iint |\nabla \alpha(u)^-|^2 \frac{2}{h} \chi_{\{-h < \alpha(u) < -\frac{h}{2}\}} \eta dx dt$$

to conclude that $\alpha(u)^-$ is supercaloric.

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