

# Chapter 11

## Trees

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# Terminology

NODE



- Definition of a general tree
  - A general tree  $T$  is a set of one or more nodes such that  $T$  is partitioned into disjoint subsets:
    - A single node  $r$ , the root
    - Sets that are general trees, called subtrees of  $r$
- Definition of a binary tree
  - A binary tree is a set  $T$  of nodes such that either
    - $T$  is empty, or
    - $T$  is partitioned into three disjoint subsets:
      - A single node  $r$ , the root
      - Two possibly empty sets that are binary trees, called left and right subtrees of  $r$

# Terminology

Id  
 $a - b / c$

Pre  
 $-a / b c$

POST ORDER

$a b -$

IN ORDER

$a - b$

Pre order

$- a b$

POST  
 $a b c / -$

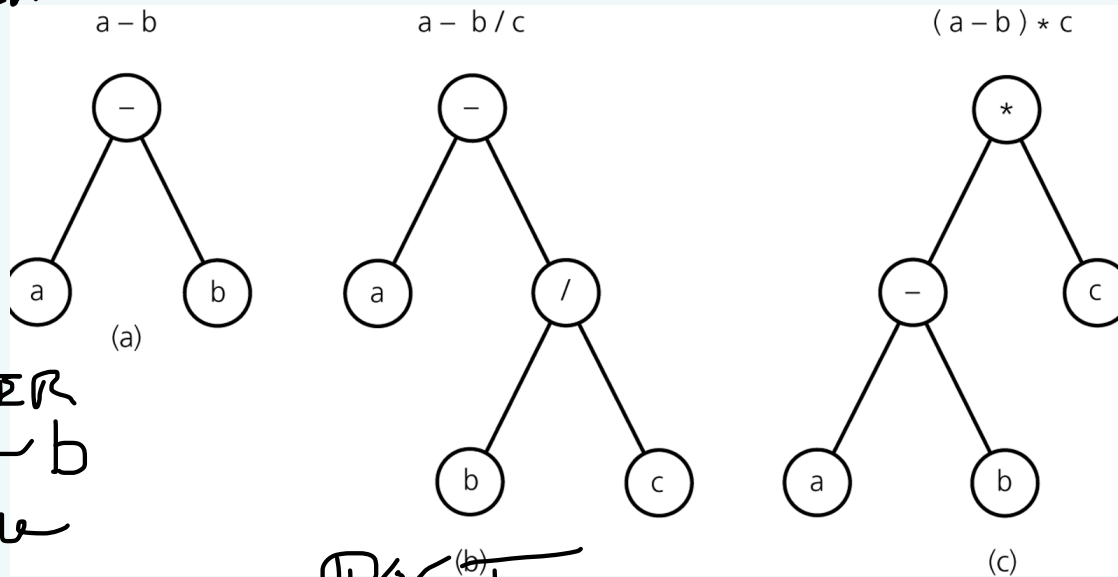


Figure 11-4

Binary trees that represent algebraic expressions

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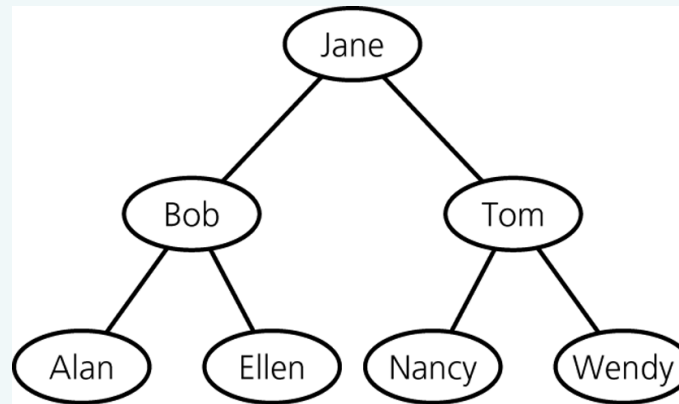
11 A-3

# Terminology

- A binary search tree
  - A binary tree that has the following properties for each node  $n$ 
    - $n$ 's value is greater than all values in its left subtree  $T_L$
    - $n$ 's value is less than all values in its right subtree  $T_R$
    - Both  $T_L$  and  $T_R$  are binary search trees

Figure 11-5

A binary search tree of names



# Terminology

- The height of trees
  - Level of a node  $n$  in a tree  $T$ 
    - If  $n$  is the root of  $T$ , it is at level 1
    - If  $n$  is not the root of  $T$ , its level is 1 greater than the level of its parent
  - Height of a tree  $T$  defined in terms of the levels of its nodes
    - If  $T$  is empty, its height is 0
    - If  $T$  is not empty, its height is equal to the maximum level of its nodes

# Terminology

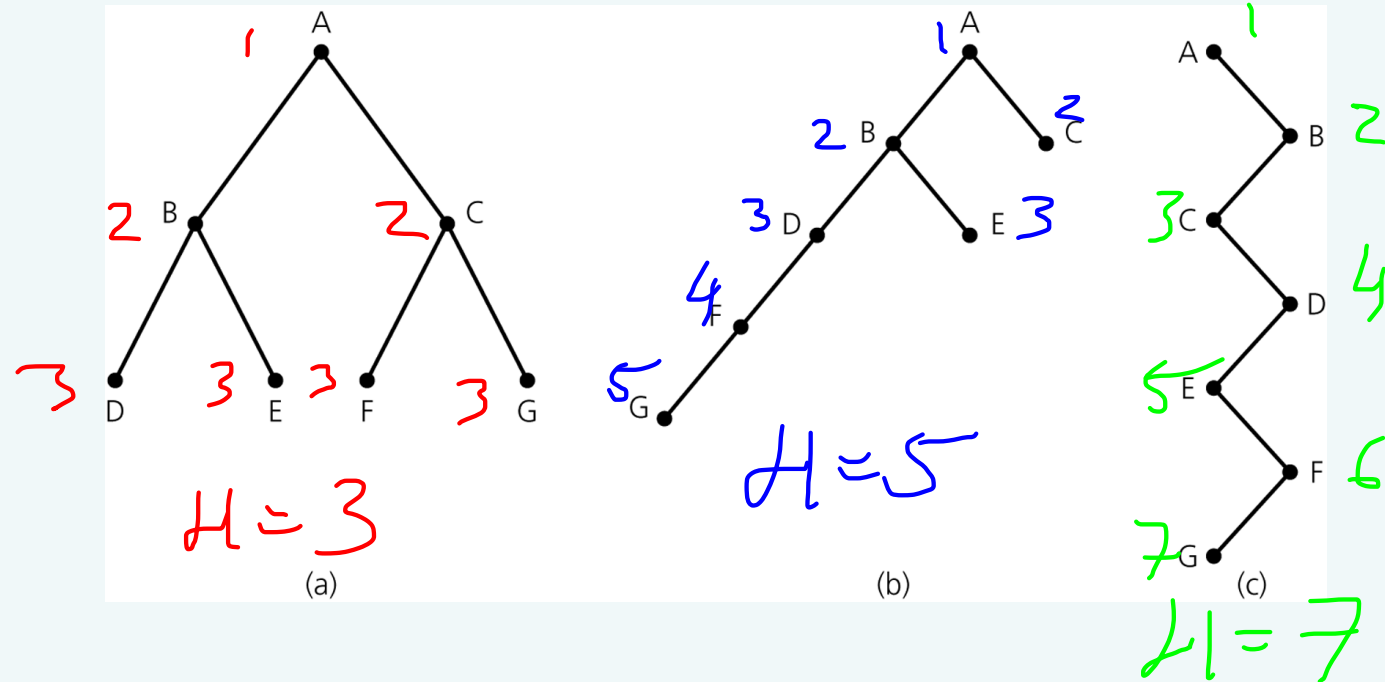


Figure 11-6

Binary trees with the same nodes but different heights

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# Terminology

- Full, complete, and balanced binary trees
  - Recursive definition of a full binary tree
    - If  $T$  is empty,  $T$  is a full binary tree of height 0
    - If  $T$  is not empty and has height  $h > 0$ ,  $T$  is a full binary tree if its root's subtrees are both full binary trees of height  $h - 1$

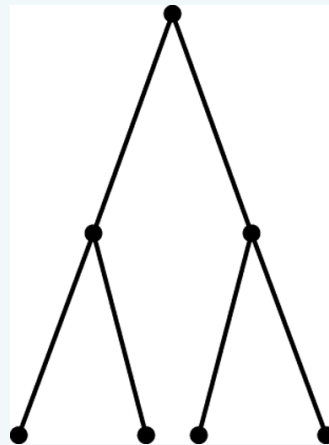


Figure 11-7

A full binary tree of height 3

# Terminology

- Complete binary trees
  - A binary tree  $T$  of height  $h$  is complete if
    - All nodes at level  $h - 2$  and above have two children each, and
    - When a node at level  $h - 1$  has children, all nodes to its left at the same level have two children each, and
    - When a node at level  $h - 1$  has one child, it is a left child

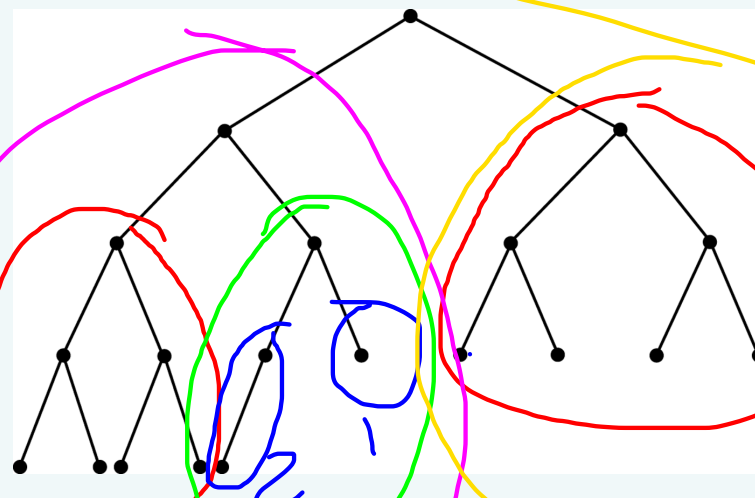


Figure 11-8

A complete binary tree

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# Terminology

- Balanced binary trees
  - A binary tree is balanced if the height of any node's right subtree differs from the height of the node's left subtree by no more than 1
- Full binary trees are complete
- Complete binary trees are balanced

# Terminology

- Summary of tree terminology
  - General tree
    - A set of one or more nodes, partitioned into a root node and subsets that are general subtrees of the root
  - Parent of node  $n$ 
    - The node directly above node  $n$  in the tree
  - Child of node  $n$ 
    - A node directly below node  $n$  in the tree
  - Root
    - The only node in the tree with no parent

# Terminology

- Summary of tree terminology (Continued)
  - Leaf
    - A node with no children
  - Siblings
    - Nodes with a common parent
  - Ancestor of node  $n$ 
    - A node on the path from the root to  $n$
  - Descendant of node  $n$ 
    - A node on a path from  $n$  to a leaf
  - Subtree of node  $n$ 
    - A tree that consists of a child (if any) of  $n$  and the child's descendants

# Terminology

- Summary of tree terminology (Continued)
  - Height
    - The number of nodes on the longest path from the root to a leaf
  - Binary tree
    - A set of nodes that is either empty or partitioned into a root node and one or two subsets that are binary subtrees of the root
    - Each node has at most two children, the left child and the right child
  - Left (right) child of node  $n$ 
    - A node directly below and to the left (right) of node  $n$  in a binary tree

# Terminology

- Summary of tree terminology (Continued)
  - Left (right) subtree of node  $n$ 
    - In a binary tree, the left (right) child (if any) of node  $n$  plus its descendants
  - Binary search tree
    - A binary tree where the value in any node  $n$  is greater than the value in every node in  $n$ 's left subtree, but less than the value of every node in  $n$ 's right subtree
  - Empty binary tree
    - A binary tree with no nodes

# Terminology

- Summary of tree terminology (Continued)
  - Full binary tree
    - A binary tree of height  $h$  with no missing nodes
    - All leaves are at level  $h$  and all other nodes each have two children
  - Complete binary tree
    - A binary tree of height  $h$  that is full to level  $h - 1$  and has level  $h$  filled in from left to right
  - Balanced binary tree
    - A binary tree in which the left and right subtrees of any node have heights that differ by at most 1

# The ADT Binary Tree: Basic Operations of the ADT Binary Tree

- The operations available for a particular ADT binary tree depend on the type of binary tree being implemented
- Basic operations of the ADT binary tree
  - `createBinaryTree()`
  - `createBinaryTree(rootItem)`
  - `makeEmpty()`
  - `isEmpty()`
  - `getRootItem()` throws `TreeException`

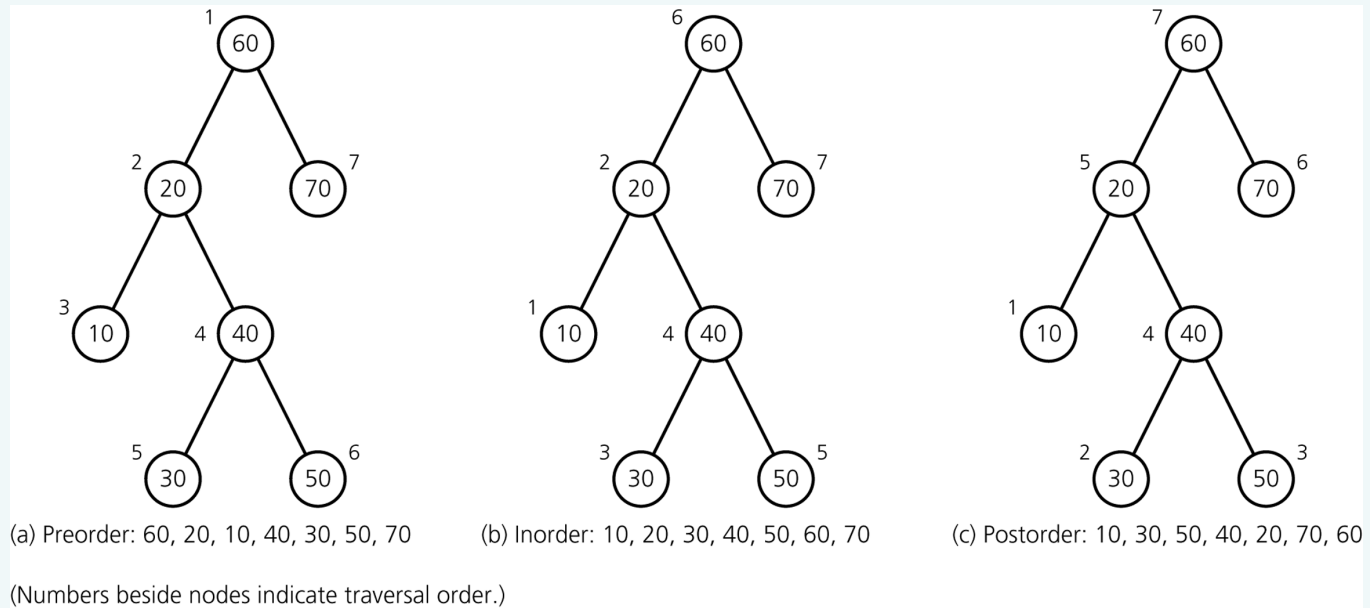
# General Operations of the ADT Binary Tree

- General operations of the ADT binary tree
  - `createBinaryTree (rootItem, leftTree, rightTree)`
  - `setRootItem(newItem)`
  - `attachLeft(newItem)` throws `TreeException`
  - `attachRight(newItem)` throws `TreeException`
  - `attachLeftSubtree(leftTree)` throws `TreeException`
  - `attachRightSubtree(rightTree)` throws `TreeException`
  - `detachLeftSubtree()` throws `TreeException`
  - `detachRightSubtree()` throws `TreeException`

# Traversals of a Binary Tree

- A traversal algorithm for a binary tree visits each node in the tree
- Recursive traversal algorithms
  - Preorder traversal
  - Inorder traversal
  - Postorder traversal
- Traversal is  $O(n)$

# Traversal of a Binary Tree



**Figure 11-10**

Traversals of a binary tree: a) preorder; b) inorder; c) postorder

# Possible Representations of a Binary Tree

- An array-based representation
  - A Java class is used to define a node in the tree
  - A binary tree is represented by using an array of tree nodes
  - Each tree node contains a data portion and two indexes (one for each of the node's children)
  - Requires the creation of a free list which keeps track of available nodes

# Possible Representations of a Binary Tree

$$L = 2n + 1$$

$$R = 2n + 2$$

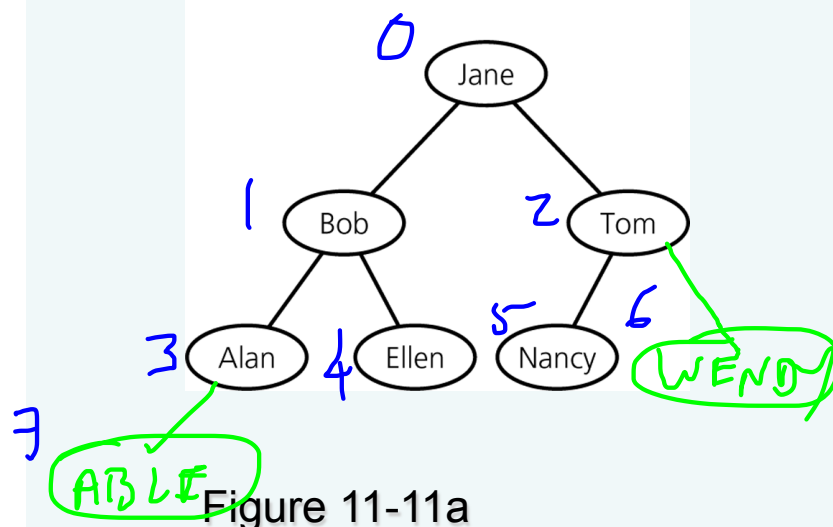


Figure 11-11a

a) A binary tree of names

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(b)

tree				
	item	leftChild	rightChild	root
0	Jane	1	2	0
1	Bob	3	4	free
2	Tom	5	-1	6
3	Alan	-1	-1	
4	Ellen	-1	-1	
5	Nancy	-1	-1	
6	?	-1	7	
7	?	-1	8	
8	?	-1	9	
·	·	·	·	
·	·	·	·	
·	·	·	·	

Free list

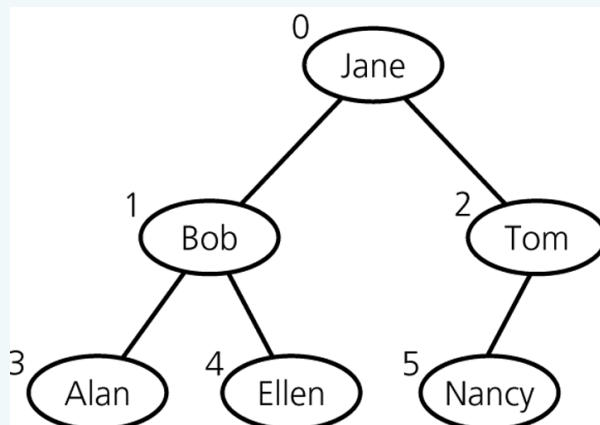
Figure 11-11b

b) its array-based implementations 11 A-20

# Possible Representations of a Binary Tree

- An array-based representation of a complete tree
  - If the binary tree is complete and remains complete
    - A memory-efficient array-based implementation can be used

# Possible Representations of a Binary Tree



**Figure 11-12**

Level-by-level numbering of a complete binary tree

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0	Jane
1	Bob
2	Tom
3	Alan
4	Ellen
5	Nancy
6	
7	

**Figure 11-13**

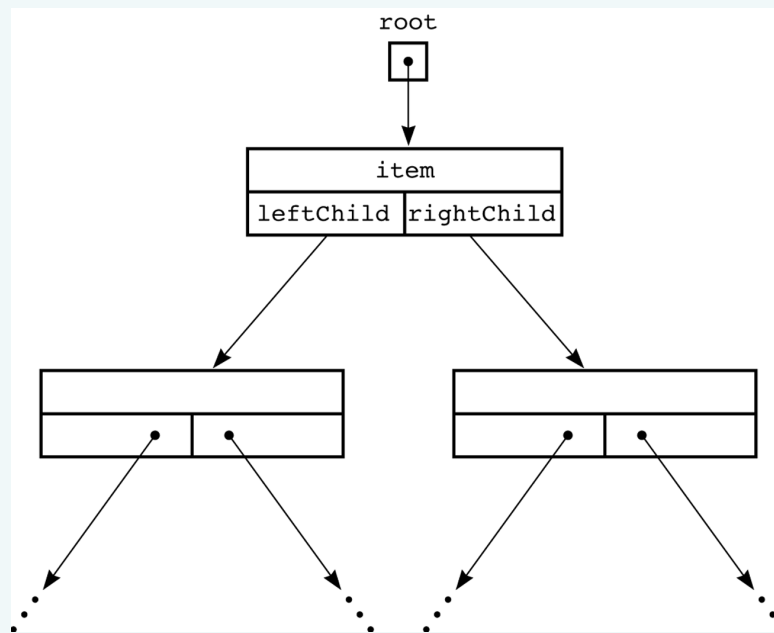
An array-based implementation of the complete binary tree in Figure 10-12

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# Possible Representations of a Binary Tree

- A reference-based representation
  - Java references can be used to link the nodes in the tree

Figure 11-14  
A reference-based  
implementation of a binary  
tree



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# A Reference-Based Implementation of the ADT Binary Tree

- Classes that provide a reference-based implementation for the ADT binary tree
  - `TreeNode`
    - Represents a node in a binary tree
  - `TreeException`
    - An exception class
  - `BinaryTreeBasis`
    - An abstract class of basic tree operation
  - `BinaryTree`
    - Provides the general operations of a binary tree
    - Extends `BinaryTreeBasis`

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# Tree Traversals Using an Iterator

- `TreeIterator`
  - Implements the Java `Iterator` interface
  - Provides methods to set the iterator to the type of traversal desired
  - Uses a queue to maintain the current traversal of the nodes in the tree
- Nonrecursive traversal (optional)
  - An iterative method and an explicit stack can be used to mimic actions at a return from a recursive call to `inorder`

# The ADT Binary Search Tree

- A deficiency of the ADT binary tree which is corrected by the ADT binary search tree
  - Searching for a particular item
- Each node  $n$  in a binary search tree satisfies the following properties
  - $n$ 's value is greater than all values in its left subtree  $T_L$
  - $n$ 's value is less than all values in its right subtree  $T_R$
  - Both  $T_L$  and  $T_R$  are binary search trees

# The ADT Binary Search Tree

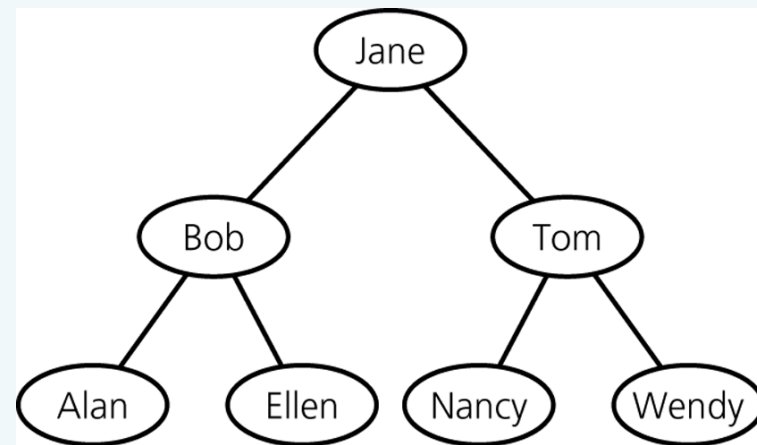
- Record
  - A group of related items, called fields, that are not necessarily of the same data type
- Field
  - A data element within a record
- A data item in a binary search tree has a specially designated search key
  - A search key is the part of a record that identifies it within a collection of records
- KeyedItem class
  - Contains the search key as a data field and a method for accessing the search key
  - Must be extended by classes for items that are in a binary search tree

# The ADT Binary Search Tree

- Operations of the ADT binary search tree
  - Insert a new item into a binary search tree
  - Delete the item with a given search key from a binary search tree
  - Retrieve the item with a given search key from a binary search tree
  - Traverse the items in a binary search tree in preorder, inorder, or postorder

Figure 11-19

A binary search tree



# Algorithms for the Operations of the ADT Binary Search Tree

- Since the binary search tree is recursive in nature, it is natural to formulate recursive algorithms for its operations
- A search algorithm
  - `search(bst, searchKey)`
    - Searches the binary search tree `bst` for the item whose search key is `searchKey`

```

Search(Node n, key k) {
    if (n != null) {
        if (n.k == k) {
            return n;
        } else if (n.k > k) {
            return search(n.leftChild, k);
        } else {
            return search(n.rightChild, k);
        }
    } else {
        return null;
    }
}

```

# Algorithms for the Operations of the ADT Binary Search Tree: Insertion

- `insertItem(treeNode, newItem)`
  - Inserts `newItem` into the binary search tree of which `treeNode` is the root

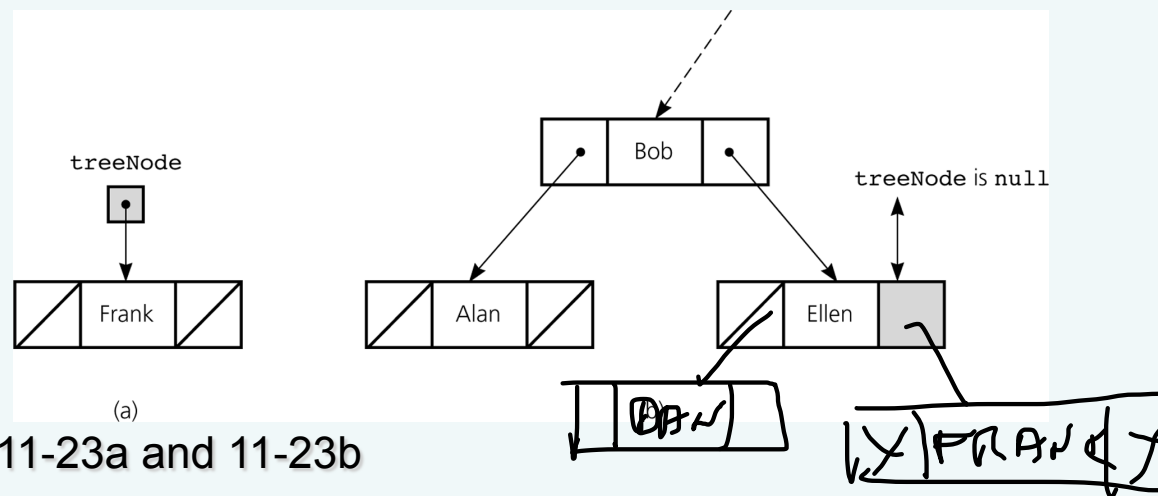
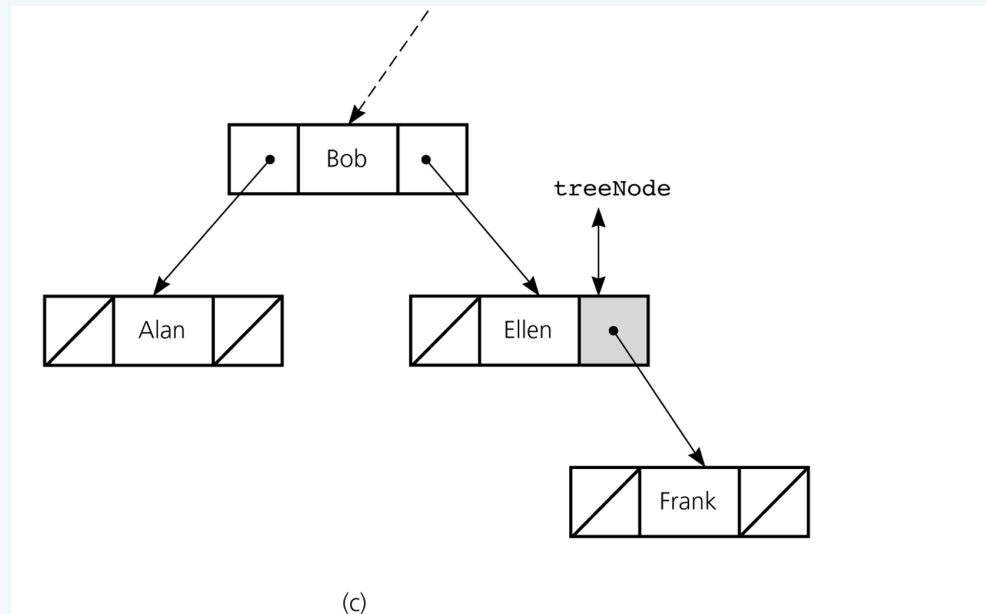


Figure 11-23a and 11-23b

a) Insertion into an empty tree; b) search terminates at a leaf

# Algorithms for the Operations of the ADT Binary Search Tree: Insertion

Figure 11-23c  
c) insertion at a leaf



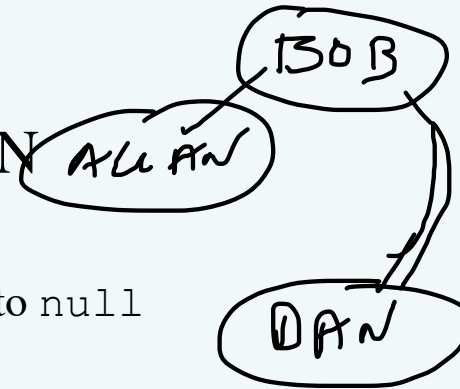
# Algorithms for the Operations of the ADT Binary Search Tree:

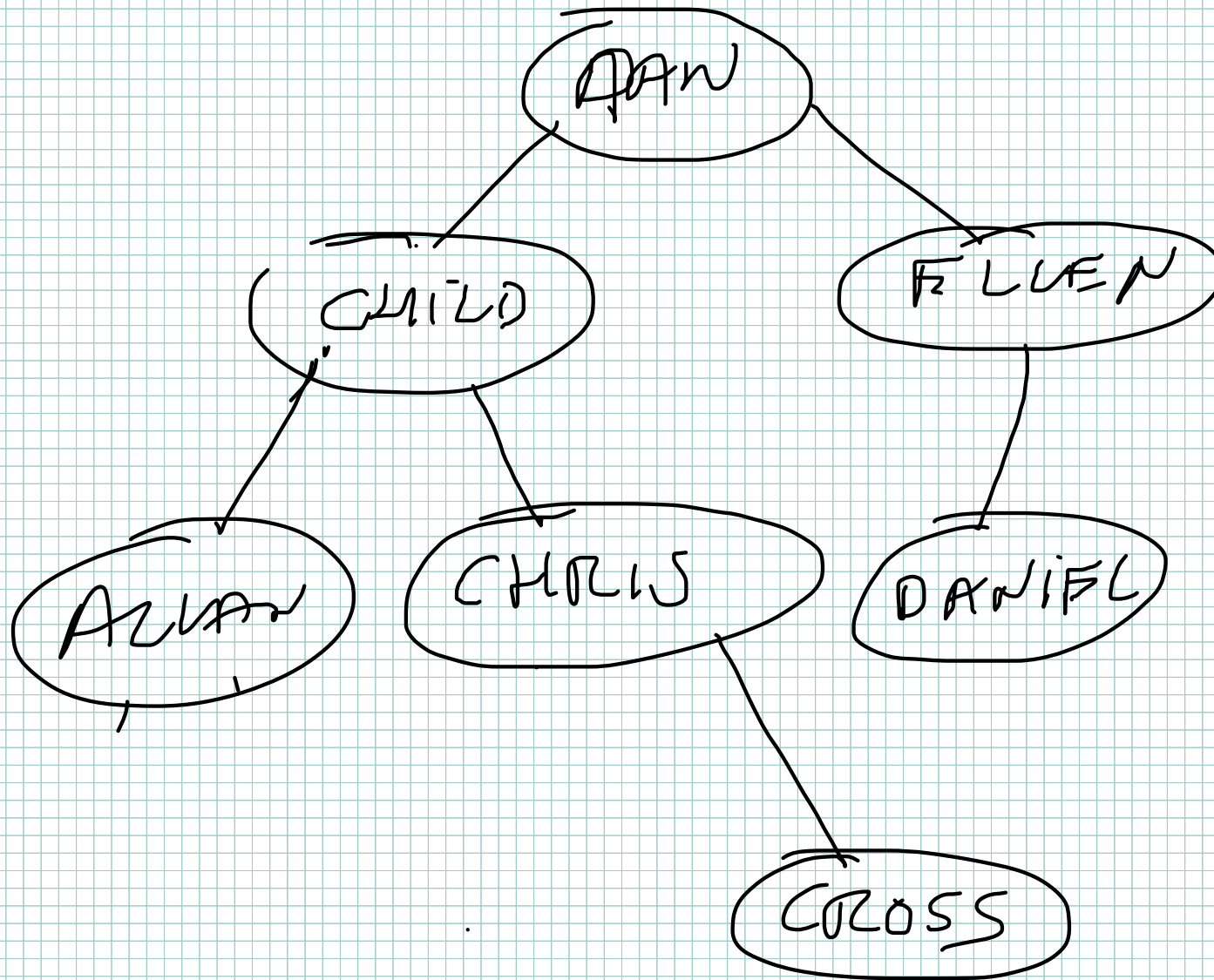
## Deletion

- Steps for deletion
  - Use the search algorithm to locate the item with the specified key
  - If the item is found, remove the item from the tree
- Three possible cases for node N containing the item to be deleted
  - N is a leaf
  - N has only one child
  - N has two children

# Algorithms for the Operations of the ADT Binary Search Tree: Deletion

- Strategies for deleting node N
  - If N is a leaf
    - Set the reference in N's parent to null
  - If N has only one child
    - Let N's parent adopt N's child
  - If N has two children
    - Locate another node M that is easier to remove from the tree than the node N
    - Copy the item that is in M to N
    - Remove the node M from the tree





# Algorithms for the Operations of the ADT Binary Search Tree: Retrieval

- Retrieval operation can be implemented by refining the `search` algorithm
  - Return the item with the desired search key if it exists
  - Otherwise, return a `null` reference

# Algorithms for the Operations of the ADT Binary Search Tree: Traversal

- Traversals for a binary search tree are the same as the traversals for a binary tree
- Theorem 11-1

The inorder traversal of a binary search tree  $T$  will visit its nodes in sorted search-key order

# A Reference-Based Implementation of the ADT Binary Search Tree

- `BinarySearchTree`
  - Extends `BinaryTreeBasis`
  - Inherits the following from `BinaryTreeBasis`
    - `isEmpty()`
    - `makeEmpty()`
    - `getRootItem()`
    - The use of the constructors
- `TreeIterator`
  - Can be used with `BinarySearchTree`

# The Efficiency of Binary Search Tree Operations

- The maximum number of comparisons for a retrieval, insertion, or deletion is the height of the tree
- The maximum and minimum heights of a binary search tree
  - $n$  is the maximum height of a binary tree with  $n$  nodes

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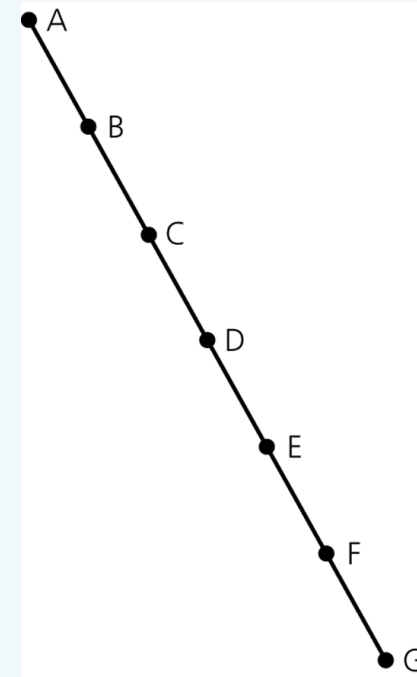


Figure 11-30  
A maximum-height binary tree  
with seven nodes

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```

Public int Height(TreeNode root)
{
    if (root == null)
    {
        return 0;
    }
    int lh = Height(root.leftChild);
    int rh = Height(root.rightChild);
    return Math.max(lh, rh) + 1;
}
}

```

```

Public boolean isBalanced(TreeNode root) {
    boolean answer = true;
    if (root == null) {
        return answer;
    }
    int lh = height(root.leftChild());
    int rh = height(root.rightChild());
    answer = (abs(lh - rh) <= 1) &&
        isBalanced(root.leftChild()) &&
        isBalanced(root.rightChild());
    return answer;
}

```

Diagram illustrating the recursive calls for the `isBalanced` function:

- Red arrow 'a' points from `isBalanced(root.leftChild())` to the `isBalanced` function call.
- Red arrow 'b' points from `isBalanced(root.rightChild())` to the `isBalanced` function call.

```

Public TreeNode balance(arr, First, Last) {
    TreeNode node = null;
    if (First <= LAST) {
        mid = (First + LAST) / 2;
        node = new TreeNode(arr[mid]);
        node.leftChild = balance(arr, First, mid - 1);
        node.rightChild = balance(arr, mid + 1, LAST);
    }
    return node;
}

```

```

Public void Balance() {
    if (!isBalanced()) {
        TreeIterator iter = new TreeIterator(this);
        iter.setInorder();
        Object[] arr = new Object[iter.size()];
        int index = 0;
        while (iter.hasNext()) {
            arr[index++] = iter.next();
        }
        this.root = Balance(arr, 0, arr.length - 1);
    }
}

```

```
Public boolean isBalanced() {  
    return isBalanced(root);  
}
```

public int height() {

return height(root);

}

# The Efficiency of Binary Search Tree Operations

- Theorem 11-2

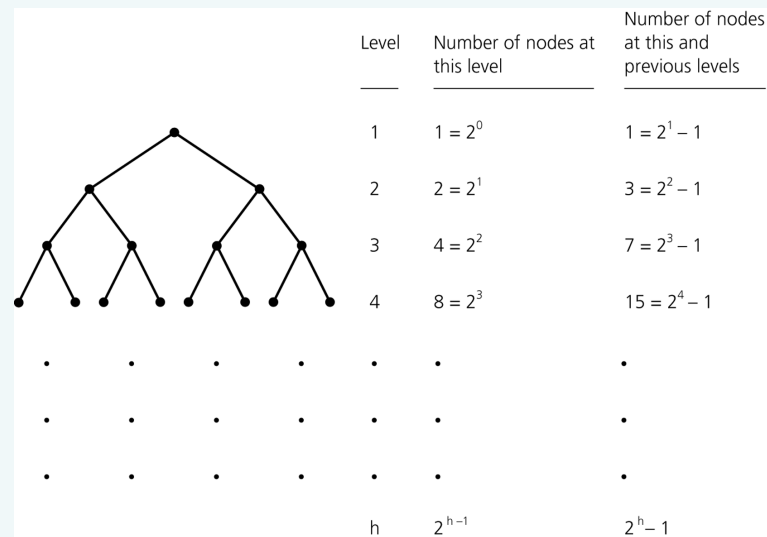
A full binary tree of height  $h \geq 0$  has  $2^h - 1$  nodes

- Theorem 11-3

The maximum number of nodes that a binary tree of height  $h$  can have is  $2^h - 1$

**Figure 11-32**

Counting the nodes in a full binary tree of height  $h$



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# The Efficiency of Binary Search Tree Operations

- Theorem 11-4

The minimum height of a binary tree with  $n$  nodes is  $\lceil \log_2(n+1) \rceil$

- The height of a particular binary search tree depends on the order in which insertion and deletion operations are performed

<u>Operation</u>	<u>Average case</u>	<u>Worst case</u>
Retrieval	$O(\log n)$	$O(n)$
Insertion	$O(\log n)$	$O(n)$
Deletion	$O(\log n)$	$O(n)$
Traversal	$O(n)$	$O(n)$

**Figure 11-34**

The order of the retrieval, insertion, deletion, and traversal operations for the reference-based implementation of the ADT binary search tree

# Treesort

- Treesort
  - Uses the ADT binary search tree to sort an array of records into search-key order
  - Efficiency
    - Average case:  $O(n * \log n)$
    - Worst case:  $O(n^2)$

# Saving a Binary Search Tree in a File

- Two algorithms for saving and restoring a binary search tree
  - Saving a binary search tree and then restoring it to its original shape
    - Uses preorder traversal to save the tree to a file
  - Saving a binary tree and then restoring it to a balanced shape
    - Uses inorder traversal to save the tree to a file
    - Can be accomplished if
      - The data is sorted
      - The number of nodes in the tree is known

# The JCF Binary Search Algorithm

- JCF has two binary search methods
  - Based on the natural ordering of elements:  
**static** <T> **int**  
binarySearch (List<? **extends** Comparable<? **super** T>> list, T key)
  - Based on a specified Comparator:  
**static** <T> **int** binarySearch (List<? **extends** T> list, T key,  
Comparator<? **super** T> c)

# General Trees

- An  $n$ -ary tree
  - A generalization of a binary tree whose nodes each can have no more than  $n$  children

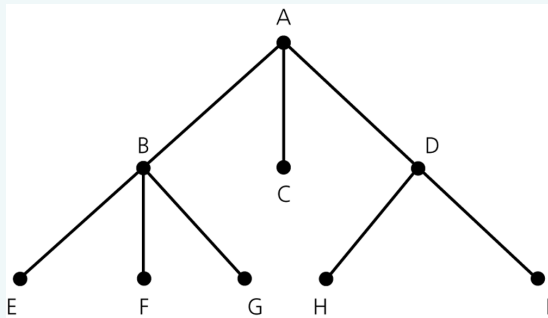


Figure 11-38

A general tree

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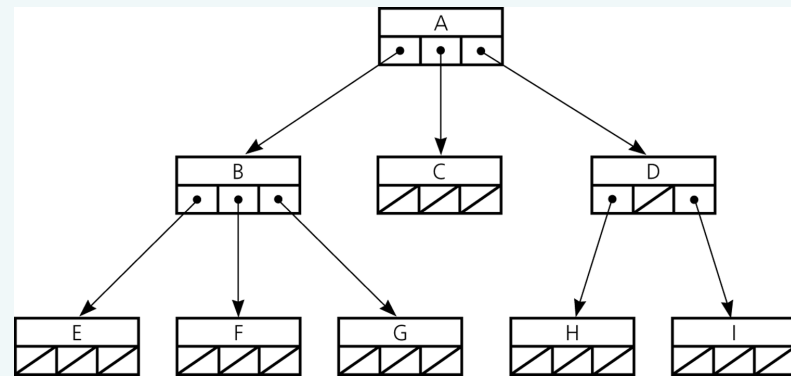


Figure 11-41

An implementation of the  $n$ -ary tree in Figure 11-38

11 B-43

# Summary

- Binary trees provide a hierarchical organization of data
- Implementation of binary trees
  - The implementation of a binary tree is usually referenced-based
  - If the binary tree is complete, an efficient array-based implementation is possible
- Traversing a tree is a useful operation
- The binary search tree allows you to use a binary search-like algorithm to search for an item with a specified value

# Summary

- Binary search trees come in many shapes
  - The height of a binary search tree with  $n$  nodes can range from a minimum of  $\lceil \log_2(n + 1) \rceil$  to a maximum of  $n$
  - The shape of a binary search tree determines the efficiency of its operations
- An inorder traversal of a binary search tree visits the tree's nodes in sorted search-key order
- The treesort algorithm efficiently sorts an array by using the binary search tree's insertion and traversal operations

# Summary

- Saving a binary search tree to a file
  - To restore the tree as a binary search tree of minimum height
    - Perform inorder traversal while saving the tree to a file
  - To restore the tree to its original form
    - Perform preorder traversal while saving the tree to a file