



Chapter 1 Introduction

Introduction to OS

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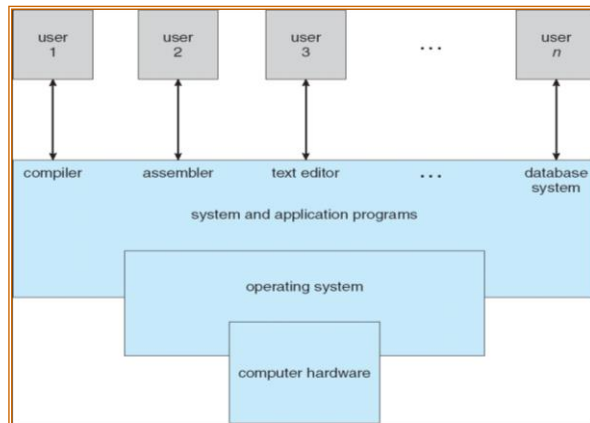
What is an Operating System?

- ❑ A program that acts as an intermediary between a *user* of a computer and the *computer hardware*.
- ❑ **Various operating system goals:**
 - *Mainframe* operating systems: to optimize utilization of hardware.
 - *PC* operating systems: to support complex games, business applications ...
 - *Handheld computers (laptop, smart phone, etc.)*: to help users easily interface with the computer to execute programs.
- ❑ **Some operating systems are designed to be convenient, others to be efficient, and others some combination of the two.**

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Four Components of a Computer System (1)

- ❑ Computer system can be divided into four components: *hardware*, the *operating system*, the *application programs*, and the *users*.



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Four Components of a Computer System (2)

- ❑ **Hardware** – provides basic computing resources.
 - CPU, memory, I/O devices.
- ❑ **Operating system** – controls and coordinates use of hardware among various applications and users
- ❑ **Application programs** – define the ways in which the system resources are used to solve the computing problems of the users.
 - Word processors, compilers, web browsers, database systems, video games.
- ❑ **Users** – people, machines, other computers.

An operation system is similar to a **government**. It provides an environment within which other (user) programs can do useful work.

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Viewpoints From Users (1)

- ❑ **PC: the OS is designed for *one user only*.**
 - Resources are monopolized.
 - The goal is to maximize the work of the user.
 - The OS is generally designed for ***ease of use***, with some attention paid to performance and non paid to resource utilization.
- ❑ **Mainframe: the OS is designed for *multiple users* – accessing the same computer through terminals.**
 - These users share resources.
 - The OS is designed to ***maximize resource utilization*** – to assure that all available CPU time, memory ...

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Viewpoints From Users (2)

- ❑ **Workstation:**
 - Users sit at workstations connected to networks of other workstations and servers – file, computer, print server.
 - The OS is designed to compromise between individual usability and resource utilization.
- ❑ **Handheld computer: are standalone units for individual users.**
 - The OS is designed mostly for individual usability.
 - But performance per amount of battery life is important as well.
- ❑ **Computer with little (or no) user view: embedded home devices.**
 - The OS is designed to run without user intervention.

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Viewpoints From Computers (3)

- ❑ OS for computer is the program involved with the hardware.
- ❑ OS is a **resource allocator**.
 - Manages all resources.
 - Decides between conflicting requests for efficient and fair resource use.
- ❑ OS is a **control program**.
 - Controls execution of programs to prevent errors and improper use of the computer.

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Operating System Definition (1)

- ❑ What is an operating system?
 - No universally accepted definition.
- ❑ Bare computer (hardware) alone is not easy to use, so application programs are developed.
 - These programs require certain **common operations**, such as those controlling the I/O device.
 - These common functions of **controlling** and **allocating** resources are then brought together into one piece of software: the *operating system*.

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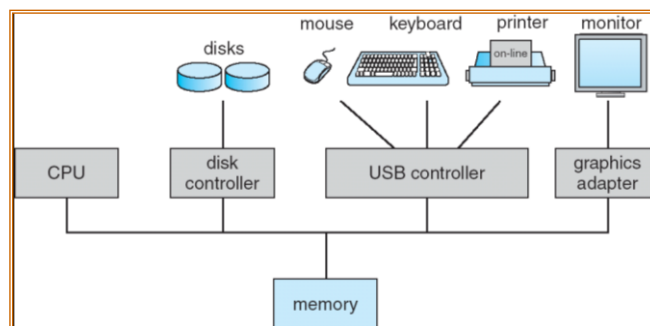
Operating System Definition (2)

- ❑ **OS is ...**
 - “Everything a vendor ships when you order an operating system”
 - But varies wildly, for example, text/graphic mode.
- ❑ **A more common definition:**
 - “The one program running at all times on the computer” is the **kernel**.
 - Everything else is either a system program or an application program.
- ❑ **The matter of what constitutes an operating system has become increasingly important.**
 - Antitrust of Microsoft windows.
 - Microsoft included too much functionality in its operating systems and thus prevented application vendors from competing.

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Computer System Organization (1)

- ❑ **Computer-system operation:**
 - One or more **CPUs, device controllers** connect through common **bus** that provides access to shared memory.
 - Each device controller is in charge of a specific type of **device** (disk drives, audio/video devices).



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Computer System Organization (2)

- ❑ Each device controller has a local buffer and a set of special-purpose registers.
 - E.g., your SATA hard disk may contain 8M buffer.
- ❑ CPU moves data from/to main memory to/from local buffers.
- ❑ I/O devices and the CPU can execute concurrently.
- ❑ Concurrent I/O is from the device to local buffer of controller.

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Computer System Operation (1)

- ❑ When a computer is powered up or rebooted ...
 - A **bootstrap program** is loaded to Initialize all aspects of system, from CPU registers to device controllers to memory contents.
 - Typically stored in ROM (read-only memory) or EEPROM, (erasable programmable read-only memory) generally known as **firmware**.
 - **Load into memory the operating-system kernel.**
 - The operating system then starts executing the first process and waits for some event to occur.
 - **Events** are usually signaled by an **interrupt** from either the hardware or the software.
 - Hardware :I/O operations — disk drive access, keystroke, ...
 - Software: system calls.

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Computer System Operation (2)

- ❑ **Why interrupt? — I/O operations *without* interrupt as an example.**
 - The handshaking process of a host (a program) reads data through a port (device):
 1. The controller does the I/O to the device (hardware operations).
 2. The host **repeatedly** read the busy bit (of the device) until that bit becomes clear.
 3. The host reads data from the device controller.
 4. The I/O is finished.
 - In step 2, the host is **busy-waiting** or **polling**.
 - It is in a *loop*, reading the busy bit over and over until the bit becomes clear.
 - The wait may be long, the host should probably switch to another task.
 - **Interrupt**: the *hardware mechanism* that enables a device to **notify** the CPU when it is ready for service.

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Interrupt Handling

- ❑ The operating system preserves the state of the CPU by storing registers and the program counter.
- ❑ Determines which type of interrupt has occurred:
 - **polling**
 - **vectored** interrupt system
- ❑ **Separate segments of code** determine what action should be taken for each type of interrupt.

Interrupt Mechanism (1)

- ❑ The CPU hardware has a wire called the *interrupt-request line* that the CPU senses after executing every instruction.
- ❑ When the CPU detects that a controller has asserted a signal on the line, the CPU performs a state save and transfers control to a generic routine.
- ❑ The generic routine examines the interrupt information and calls the **interrupt-specific handler**.
 - Polling all the devices to see which one raised the interrupt.
- ❑ **Ideally, interrupts must be handled quickly** (data overflow on keyboard controller).
 - Fortunately, only a predefined number of interrupts is possible.
 - The modern interrupt mechanism accepts an **address** (index) in accordance with a **interrupt vector** (table) to provide fast interrupt service.

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Interrupt Mechanism (2)

- ❑ The **interrupt vector** contains the addresses of all the specific interrupt handle routines.
- ❑ The **address** (index) is an offset in the interrupt vector.
- ❑ This vectored interrupt mechanism can reduce the need for a single interrupt handler to search all possible sources of interrupts.
- ❑ Operating systems as different as Windows and Unix dispatch interrupt in this manner.

| vector number | description |
|---------------|--|
| 0 | divide error |
| 1 | debug exception |
| 2 | null interrupt |
| 3 | breakpoint |
| 4 | INTO-detected overflow |
| 5 | bound range exception |
| 6 | invalid opcode |
| 7 | device not available |
| 8 | double fault |
| 9 | coprocessor segment overrun (reserved) |
| 10 | invalid task state segment |
| 11 | segment not present |
| 12 | stack fault |
| 13 | general protection |
| 14 | page fault |
| 15 | (Intel reserved, do not use) |
| 16 | floating-point error |
| 17 | alignment check |
| 18 | machine check |
| 19-31 | (Intel reserved, do not use) |
| 32-255 | maskable interrupts |

Used for device-generated interrupts

The design of the interrupt vector for the Intel Pentium processor.

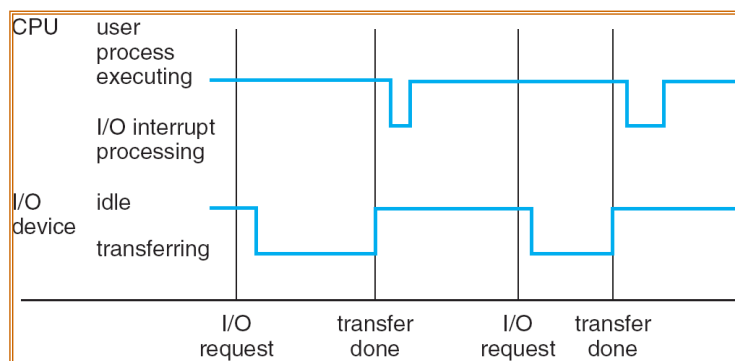
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Interrupt Mechanism (3)

- ❑ The interrupt mechanism must also save the address of the interrupted instruction.
 - It may also save the **state** (processor register values).
- ❑ After the interrupt is serviced, the saved address (and saved state) is loaded, and the interrupted computation resumes as though the interrupt had not occurred.
- ❑ **Note:**
 - Incoming interrupts are *disabled* while another interrupt is being processed to prevent a *lost interrupt*.
 - A **trap** is a **software-generated interrupt** caused either by an error or a user request (system call).

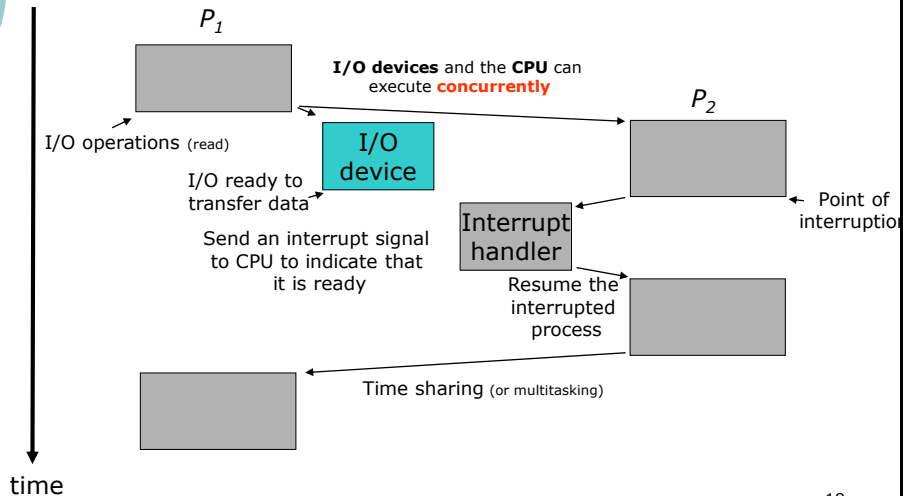
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Interrupt Timeline



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Example of Interrupt



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Storage Definitions and Notation Review

- The basic unit of computer storage is the **bit**. A bit can contain one of two values, 0 and 1. All other storage in a computer is based on collections of bits. Given enough bits, it is amazing how many things a computer can represent: numbers, letters, images, movies, sounds, documents, and programs, to name a few. A **byte** is 8 bits, and on most computers it is the smallest convenient chunk of storage. For example, most computers don't have an instruction to move a bit but do have one to move a byte. A less common term is **word**, which is a given computer architecture's native unit of data. A word is made up of one or more bytes. For example, a computer that has 64-bit registers and 64-bit memory addressing typically has 64-bit (8-byte) words. A computer executes many operations in its native word size rather than a byte at a time.
- Computer storage, along with most computer throughput, is generally measured and manipulated in bytes and collections of bytes.
 - A **kilobyte**, or **KB**, is $1,024$ bytes
 - a **megabyte**, or **MB**, is $1,024^2$ bytes
 - a **gigabyte**, or **GB**, is $1,024^3$ bytes
 - a **terabyte**, or **TB**, is $1,024^4$ bytes
 - a **petabyte**, or **PB**, is $1,024^5$ bytes
- Computer manufacturers often round off these numbers and say that a megabyte is 1 million bytes and a gigabyte is 1 billion bytes. Networking measurements are an exception to this general rule; they are given in bits (because networks move data a bit at a time).

Storage Structure (1)

- ❑ **Main memory and the registers are the only storage that the CPU can access directly.**
- ❑ **Registers:**
 - Are built into the CPU.
 - CPU can decode instructions and perform simple operations on register contents.
- ❑ **Main memory:**
 - Computer programs must be in main memory to be executed.
 - Random Access, Typically volatile
 - Is the **only large storage area** that the CPU can access directly.

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Storage Structure (2)

- ❑ **A typical (instruction) execution cycle first *fetches* an instruction from memory.**
 - The instruction is stored in the ***instruction register***.
- ❑ **CPU then *decodes* the instruction.**
 - May cause operands to be fetched from memory and stored in some ***internal register***.
- ❑ **After the instruction on the operands has been executed, the result may be stored back in memory.**
- ❑ **Memory contains information about data and programs.**

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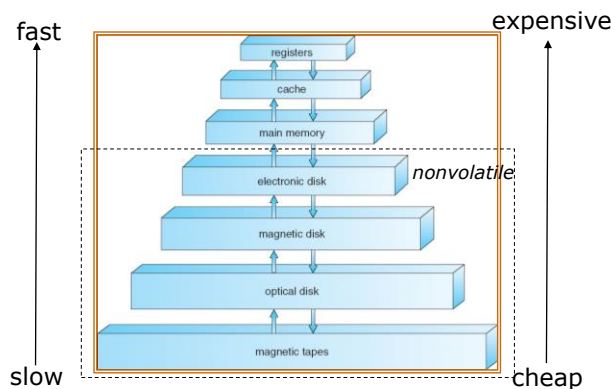
Storage Structure (3)

- ❑ Ideally, we want the programs and data to reside in main memory permanently.
 - **Impossible!!**
 - Main memory is too **small** to store all needed programs and data.
 - Main memory is a **volatile** storage device that loses its contents when power is turned off.
- ❑ **Secondary storage** – extension of main memory that provides large nonvolatile storage capacity.
 - Magnetic disks – The most common secondary storage.

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Storage Structure (cont'd)

- ❑ Other storage units: CD-ROM, tapes, and so on.
- ❑ Storage systems organized in *hierarchy* according to speed, cost, and volatility.



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Caching

- ❑ Important principle, performed at many levels in a computer (in hardware, operating system, software).
- ❑ Information in use copied from slower to faster storage temporarily.
- ❑ **Faster storage (cache) checked first to determine if information is there.**
 - If it is, information used directly from the cache (fast)
 - If not, data copied to cache and used there
- ❑ **Cache smaller than storage being cached.**
 - Cache management important design problem
 - Cache size and replacement policy

I/O Structure (1)

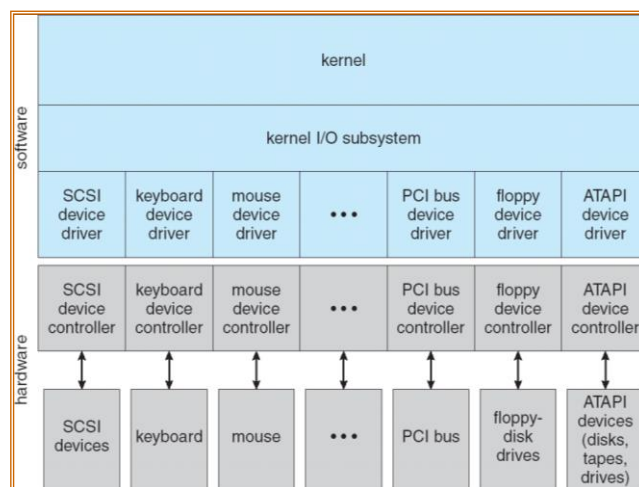
- ❑ **A large portion of operating system code is dedicated to managing I/O.**
 - Importance to the reliability and performance of a system.
 - The varying nature of the devices.
- ❑ **A general-purpose computer system consists of *CPUs* and multiple *device controllers* that are connected through a common *bus*.**
 - Each device controller is in charge of a specific type of device (e.g., disk controller and disks).

I/O Structure (2)

- ❑ A device controller maintains some local *buffer storage* and a set of *registers*.
 - Controller is responsible for moving the data between the devices that it controls and its local buffer storage.
- ❑ Operating systems have a *device driver* for each device controller.
 - The device driver understands the device controller and presents a **uniform interface** to the device to the operating system.

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I/O Structure (3)



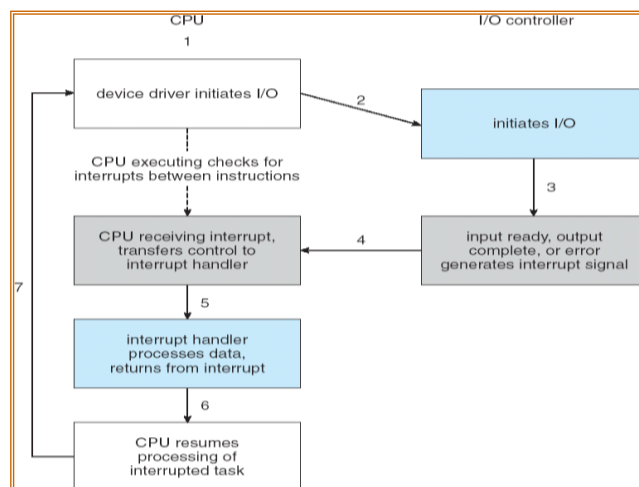
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I/O Structure (4)

- ❏ To start an I/O operation (such as “read a character from the keyboard”):
- The **device driver** loads the appropriate registers with the device controller.
 - The **device controller**, in turn, examines the contents of these registers to determine what action to take.
 - The controller starts the transfer the data from the device to its local buffer.
 - Once the transfer the data is complete, the device controller informs the device driver via an **interrupt**.
 - The device driver then returns control (the received data) to the operating systems.

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I/O Structure (5)



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I/O Structure (6)

- ❑ The purpose of device driver is to hide the differences among device controllers from the I/O subsystem of the kernel.
 - An I/O `read()` can read data from SATA, ATA, or SCSI hard disks by using specific device drivers.
- ❑ Device drivers are internally custom-tailored to each device but export standard interfaces to the I/O subsystem of the kernel.
 - Benefit:
 - Simplify the job of the operating system developer.
 - New devices are easily attached to a computer system without waiting for the operating-system vendor to develop support code.

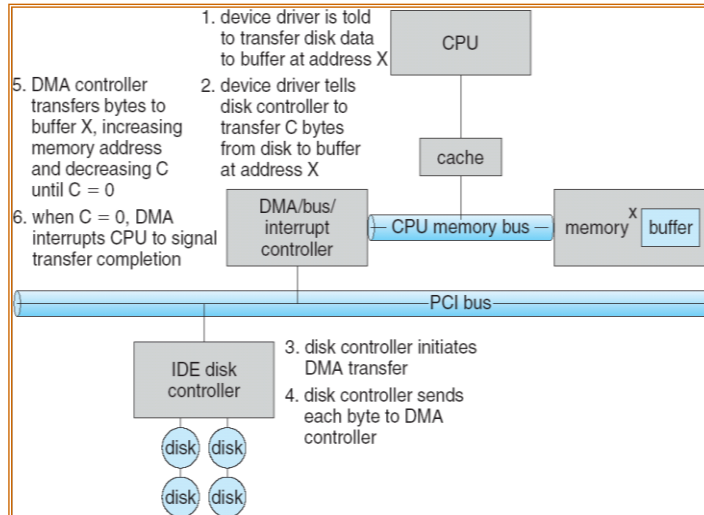
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I/O Structure (7)

- ❑ The interrupt-driven I/O is fine for moving small amounts of data.
 - But can produce high overhead when used for bulk data movement (e.g., disk I/O).
- ❑ **Direct memory access (DMA)** is used to solve this problem.
 - First set up buffers, pointers (to memory block), and counters for the I/O device.
 - The device controller transfer the entire block of data directly to/from its buffer to/from memory, with no intervention by the CPU.
 - One interrupt for each block access, rather than per byte.

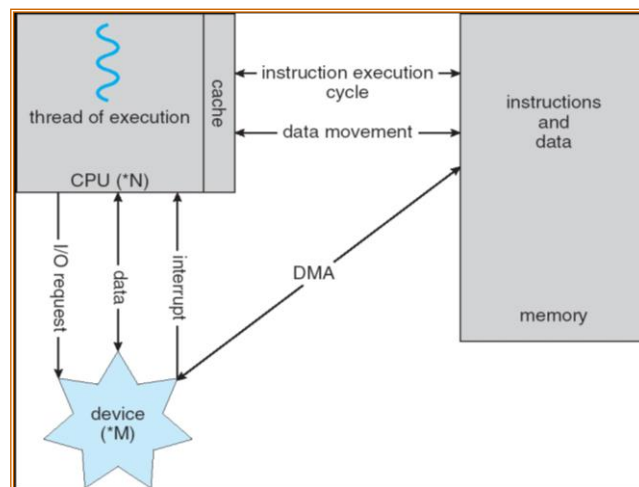
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I/O Structure (8)



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I/O Structure (9)



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Computer System Architecture (1)

- ❑ Computer systems can be categorized according to the number of general-purpose processors used.

- ❑ **Single-processor systems:**

- There is *one main CPU* capable of executing a general-purpose instruction set.
- Almost all systems have other *special-purpose processors* as well.
 - Device-specific processors (e.g., graphics controllers).
 - Do not run user processes and are managed by the operating system.
 - Relieve the overhead of the main CPU.

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Computer System Architecture (2)

- ❑ **Multiprocessor Systems:**

- As known as ***parallel systems, tightly coupled systems***.
- Have **two or more processors** in close communication.
- Share the same computation resources (memory, bus, ...).
- Main advantages:
 - **Increased throughput:**
 - We expect to get more work done in less time.
 - The speed-up ratio with N processors is not N , however; rather, it is less than N .
 - A certain amount of overhead is incurred in keeping all the parts working correctly.

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Computer System Architecture (3)

➤ Main advantages:

▪ **Economy of scale:**

- Cost less than equivalent multiple single-processor systems, because they share computation resources.
 - Store data on the same disk vs. many copies of the data.

▪ **Increased reliability:**

- If functions can be distributed properly among several processors, then the failure of one processor will not halt the system, only slow it down.

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Computer System Architecture (4)

❑ The multiple-processor systems in use today are of two types:

➤ **Asymmetric multiprocessing** (master-slave relationship):

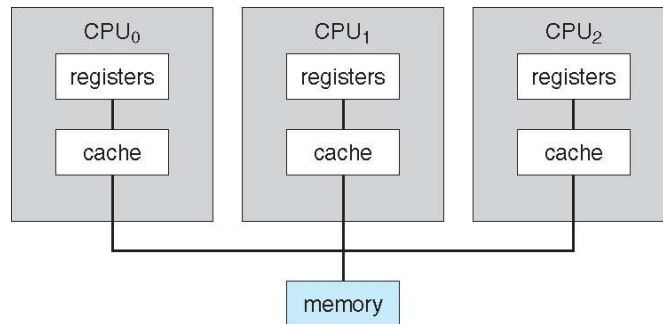
- Each processor is assigned a specific task.
- A **master** process controls the system.
- The master processor schedules and allocates work to the **slave** processors.

➤ **Symmetric multiprocessing** (SMP):

- All processors are **peers**, performs all tasks within the operating system.
- Operating system must be written carefully to avoid unbalanced resource arrangement.
 - One processor may be sitting idle while another is overloaded.
- Virtually all modern operating systems (windows, Mac OSX, Linux) now provide support for SMP.

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Symmetric Multiprocessing Architecture

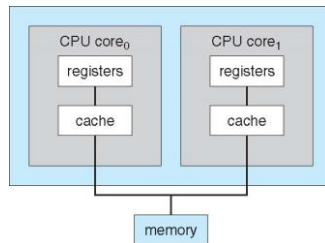


Computer System Architecture (5)

- ❑ A recent trend in CPU design is to include multiple **compute core** on a single chip.
 - In essence, these are multiprocessor chips.
 - These multi-core CPUs look to the operating system just as N standard processors.

A Dual-Core Design

- ❑ Multi-chip and multicore
- ❑ Systems containing all chips
 - Chassis containing multiple separate systems



Clustered Systems (1)

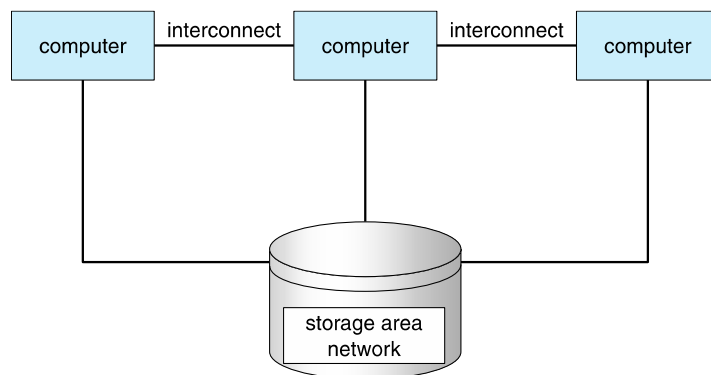
- ❑ **Clustered Systems:**
 - Clustered computers **share storage** and **are linked via a local-area network (LAN)** or Storage-area Network (SAN).
 - Differ from multiprocessor systems in that they are composed of two or more individual system coupled together.
 - **Goal: to provide high-availability service.**
 - Service will continue even if one or more systems in the cluster fail.
 - A layer of cluster software runs on the cluster nodes.
 - Each node can monitor one or more of the others (over the LAN).
 - If the monitored machine fails, the monitoring machine can take over the failed machine.

Clustered Systems (2)

- Clustering can be structured **asymmetrically** or **symmetrically**.
- **Asymmetric clustering:**
 - One machine is in **hot-standby** mode, does nothing but monitor the active nodes.
 - If an active fails, the hot-standby host becomes the active node.
- **Symmetric mode:**
 - Host are monitoring each other.
 - More efficient as it uses all of the available hardware.
- Some clusters are for **high-performance computing (HPC)**
 - Applications must be written to use **parallelization**
- Some have **distributed lock manager (DLM)** to avoid conflicting operations

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Clustered Systems



Operating System Structure (1)

- ❑ Operating systems vary greatly in their makeup, since they are organized along many different lines.
 - However, there are many commonalities.
- ❑ One of the most important aspect of operating systems is the ability to *multiprogramming*.
 - User cannot keep CPU and I/O devices busy at all times.
 - Jobs have to wait for some task, such as an I/O operation, to complete.
 - The CPU would sit idle.
 - Multiprogramming organizes jobs so **CPU always has one to execute.**

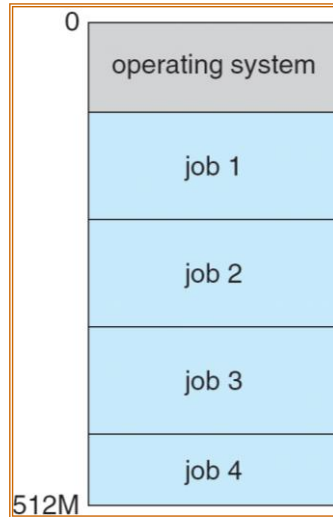
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Operating System Structure (2)

- ❑ **Multiprogramming:**
 - A subset of total jobs in system is kept in memory.
 - One job is selected and run.
 - When it has to wait (for I/O for example), OS switches to another job.
 - When that job needs to wait, the CPU is switched to another job, and so on.
 - Eventually, the first job finishes waiting and gets the CPU back.
 - As long as at least one job needs to execute, **the CPU is never idle.**

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Operating System Structure (3)



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Operating System Structure (4)

- ❑ **Time sharing (multitasking):**
 - Is logical **extension of multiprogramming**.
 - CPU switches jobs **frequently**.
- ❑ **Time sharing is frequently used in *interactive computer system*.**
 - For example, windows systems, which provide direct communication between the user and the system (using keyboard or mouse).
 - The response time (of each job) should be short!!
 - The operating system must switch rapidly from one job (for one user) to next, such that each user is given the impression that the entire computer system is dedicated to his use.

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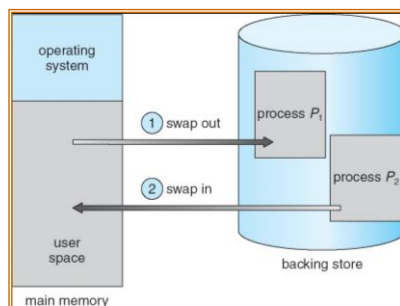
Operating System Structure (5)

- ❑ Time sharing and multiprogramming require several jobs to be kept simultaneously in memory.
 - A program loaded into memory and executing is called a **process**.
- ❑ Since main memory is too small to accommodate all jobs, the jobs are kept initially on the disk in the **job pool**.
 - The pool consists of all processes residing on disk awaiting allocation of main memory.
- ❑ **Job scheduling** (chapter 5) selects jobs from the pool and loads them into memory for execution.
- ❑ If several jobs ready to run at the same time **CPU scheduling** (chapter 5) chooses among them.

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Operating System Structure (6)

- ❑ If processes don't fit in memory, **swapping** moves them in and out to run.
 - Swap to a backing store (e.g., hard disks).
 - For example a higher-priority process arrives and wants service, the memory manager can swap out the lower-priority process and then load and execute the higher-priority process.
 - **Virtual memory** allows execution of processes not completely in memory.



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Operating-System Operations (1)

- ❑ Modern operating systems are event driven.
 - Waiting for something (event) to happen.
- ❑ Events are signaled by the occurrence of an interrupt or a trap (software interrupt).
 - **Interrupt** driven by **hardware**.
 - **Software error** or **request** creates **trap**.
 - E.g., division by zero, request for operating system service.
- ❑ The operation structure of interrupt (event) driven operating system:
 - For each interrupt, separate segments of code in the operating system determine what action should be taken.
 - An **interrupt service routine** (IRS) is provided that is responsible for dealing with the interrupt.

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Operating-System Operations (2)

- ❑ Since there are multiple running processes, we (operating system) need to make sure that an error in a program can not affect other programs.
 - Infinite loop in one process could prevent the correct operation of many other processes.
 - One erroneous (malicious) program might modify another program/data/OS.
- **Protection** and **security** are very important!!

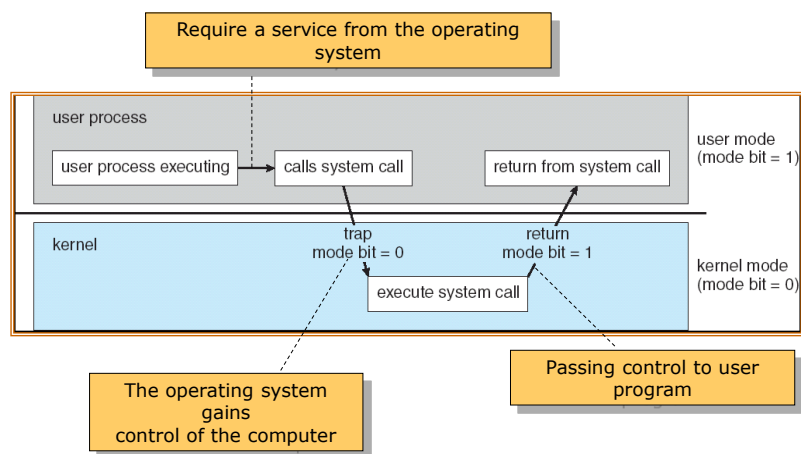
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Operating-System Operations (3)

- ❑ To ensure the proper execution of the operating system, we must be able to distinguish between the execution of operating-system code and user-defined code.
 - Computation resources **can only** be managed by operating-system code.
 - User-defined code can not cross the line.
 - Supported by hardware mechanism.
- ❑ **Dual-mode: user mode and kernel mode.**
 - **Mode bit** provided by hardware, kernel (0) or user (1).
 - Recent versions of the Intel CPU do provide dual-mode.
 - When a user application requests a service from operating system, it must transition from user to kernel mode to fulfill the request.
 - Request only through **system call**.
- ❑ **Increasingly CPUs support multi-mode operations**
 - i.e. **virtual machine manager (VMM)** mode for guest **VMs**

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Transition from User Mode to Kernel Mode (1)



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Transition from User Mode to Kernel Mode (2)

- ❑ The dual mode protects the operating system from errant users.
 - We designate some machine instructions that may cause **harm** as ***privileged instructions***, and only executable in kernel mode.
 - I/O control, interrupt management ... are examples of privileged instruction.
 - Generally, control is switched to the operating system via an interrupt, a trap, or a system call.

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Transition from User Mode to Kernel Mode (3)

- ❑ More description of system call:
 - When a system call is called, it is treated by the hardware as a software interrupt.
 - The mode bit is set to kernel mode.
 - Control passes through the interrupt vector to a service routine in the operating system.
 - The kernel examines the parameter of the interrupt to determine what type of service the user program is requesting.
 - The kernel verifies and executes the request.
 - And returns control to the instruction following the system call (user mode).

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Operating-System Operations: Timer

- ❑ Operating system must prevent a user program from running too long.
 - E.g., Getting stuck in an infinite loop.
- ❑ A **timer** can be set to prevent a user program from running too long.
 - Timer can be set to interrupt the computer after a period.
 - Before turning over control to the user (program), operating system initializes a **counter**.
 - Every timer interrupt decrements the counter by 1.
 - When counter becomes negative, the operating system terminates program.

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Process Management (1)

- ❑ **Process:**
 - A program in execution.
 - Program is a *passive entity*, process is an *active entity*.
 - A unit of work within the system.
- ❑ **Process needs resources to accomplish its task.**
- ❑ **Process termination requires reclaim of any reusable resources.**
 - CPU, memory, I/O, files.
- ❑ **Single-threaded process has one *program counter* specifying location of next instruction to execute.**
- ❑ **Multi-threaded process has one program counter per thread.**
 - Process executes instructions sequentially, one at a time, until completion.

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Process Management (2)

- ❑ Typically system has many processes, some user, some operating system running concurrently on one or more CPUs.
- ❑ The operating system is responsible for the following activities in connection with process management (chapters 3 ~ 6):
 - Creating and deleting both user and system processes
 - Suspending and resuming processes.
 - Providing mechanisms for process synchronization.
 - Providing mechanisms for process communication.
 - Providing mechanisms for deadlock handling.

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Memory Management (1)

- ❑ The *main memory* is generally the only large storage device that the CPU is able to address and access directly.
 - Main memory is a large array of **words** or **bytes**, ranging in size from hundreds of thousands to billions.
 - Each word or byte has its own (memory) address.
- ❑ **Data must be in memory before and after processing.**
 - For example, load data from disk into memory.
- ❑ **All instructions must be in memory in order to execute.**

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Memory Management (2)

- ❑ **General-purpose computers must keep several programs in memory to improve the computer performance.**
 - Creating a need for memory management (chapters 8 and 9).
- ❑ **Memory management activities:**
 - Keeping track of which parts of memory are currently being used and by whom.
 - Deciding which processes (or parts thereof) and data to move into and out of memory.
 - Allocating and de-allocating memory space as needed.

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Storage Management

- ❑ **The operating system provides uniform, logical view of physical storage media.**
 - Abstract physical properties to Logical storage unit — file.
 - Physical storage media — disk, tapes, ...
 - Varying properties include access speed, capacity, data-transfer rate, access methods (sequential or random)
- ❑ **The operating system maps files onto physical media and access these files via the storage devices.**

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File-System Management

- ❑ **A *file* is a collection of related information defined by its creator.**
 - Represent programs and data.
 - Data: numeric, alphabetic, or binary. free-form or non-free form.
- ❑ **Files usually organized into *directories* to make them easier to use.**
- ❑ **Multiple user can access to the same file.**
 - **Access control** on most operating systems to determine who can access what.
- ❑ **OS activities include:**
 - Creating and deleting files and directories.
 - Primitives to manipulate files and directories.
 - **Mapping files onto secondary storage.**
 - Backup files onto stable (non-volatile) storage media.

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Mass-Storage Management (1)

- ❑ **Computer system must provide *secondary storage* to back up main memory (for a long period of time).**
 - **Disks** are used as the principal storage medium for programs and data.
- ❑ **Disks are frequently used as the source and destination of program processing.**
 - Proper management is of central importance.
 - Speed of computer operation hinges on disk subsystem.
- ❑ **OS activities:**
 - Free-space management.
 - Storage allocation.
 - Disk scheduling.

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Mass-Storage Management (2)

□ **Tertiary storage:**

- Storage that is slower and lower in cost than secondary storage.
 - Optical storage, magnetic tape.
- Backup disk data.
- Still must be managed.

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Caching Revisited

□ **Important principle of computer systems.**

- Information is normally kept in some storage system (large, slow, and cheap).
- As it is used, it is copied into a faster (small, and expensive) storage system — the *cache*.

□ **When we need a particular piece of information, we first check faster storage (cache) to determine if information is there.**

- If it is, information used directly from the cache (fast).
- If not, **data copied to cache** and used there.

□ **Because cache is smaller than storage being cached, cache management is an important design problem.**

- Careful selection of the **cache size** and **replacement policy**.

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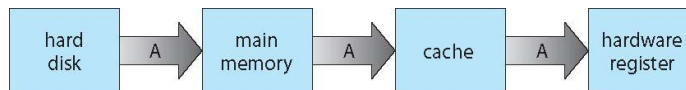
Performance of Various Levels of Storage

| Level | 1 | 2 | 3 | 4 | 5 |
|---------------------------|--|-------------------------------|------------------|------------------|------------------|
| Name | registers | cache | main memory | solid state disk | magnetic disk |
| Typical size | < 1 KB | < 16MB | < 64GB | < 1 TB | < 10 TB |
| Implementation technology | custom memory with multiple ports CMOS | on-chip or off-chip CMOS SRAM | CMOS SRAM | flash memory | magnetic disk |
| Access time (ns) | 0.25 - 0.5 | 0.5 - 25 | 80 - 250 | 25,000 - 50,000 | 5,000,000 |
| Bandwidth (MB/sec) | 20,000 - 100,000 | 5,000 - 10,000 | 1,000 - 5,000 | 500 | 20 - 150 |
| Managed by | compiler | hardware | operating system | operating system | operating system |
| Backed by | cache | main memory | disk | disk | disk or tape |

Movement between levels of storage hierarchy can be explicit or implicit

Migration of data “A” from Disk to Register (1)

- ❑ In a hierarchical storage structure, the same data may appear in different levels of the storage system.
- ❑ An integer A that is to be incremented by 1 is located in file B on disk.



- Once the increment takes place in the register, **the value of A differs in the various storage system!!**
- ❑ In an environment where only one process executes at a time.
 - An access to A will always to be the copy at the highest level of the storage hierarchy.

Migration of data “A” from Disk to Register (2)

- ❑ **In multitasking environments:**
 - each process (has its memory space) must obtain the most recently updated value of A.
- ❑ **In multiprocessor environment:**
 - Each CPU also contains a local cache.
 - **A copy of A may exist simultaneously in several caches.**
 - Since CPUs can execute **concurrently**, an update of A in one cache must be reflected in all other caches where A resides — **cache coherency**.
- ❑ **Distributed environment situation even more complex.**
 - Several copies of a datum can exist.

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I/O Subsystem

- ❑ **The purpose of I/O subsystem of the operating system is to hide peculiarities of hardware devices from the user.**
- ❑ **I/O subsystem responsible for**
 - Memory management of I/O including buffering, caching, spooling.
 - General device-driver **interface**.
 - **Drivers** for specific hardware devices.

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Protection and Security (1)

- ❑ **A multi-user computer system allows the concurrent execution of multiple processes.**
 - Computation resources must be operated in a **proper** and **authorized** manner.
 - For example, a process can execute only within its own address space.
- ❑ **Protection** – any mechanism for controlling access of processes or users to resources defined by the operating system.
- ❑ **A system can have adequate protection but still be prone to failure and allow inappropriate access.**
 - A user's authentication information is stolen.
- ❑ **Security** – defense of the system against internal and external attacks.
 - Huge range, including denial-of-service, viruses, ...

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Protection and Security (2)

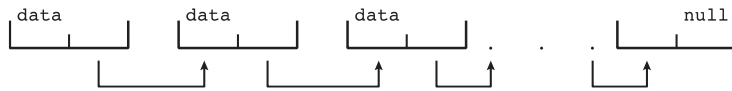
- ❑ **Protection and security require the operating system to be able to distinguish among all its users.**
- ❑ **Most systems maintain a list of user names and associated *user identifiers* (user IDs, security IDs).**
 - User ID is then associated with all files, processes of that user to determine access control.
- ❑ ***Group identifier* (group ID) allows set of users to be defined and managed, then also associated with each process, file.**
- ❑ ***Privilege escalation* allows user to change to effective ID with more rights for an activity.**
 - For example, on UNIX, the `setuid` attribute on a program causes that program to run with the user ID of the owner of the file, rather than the current user's ID.

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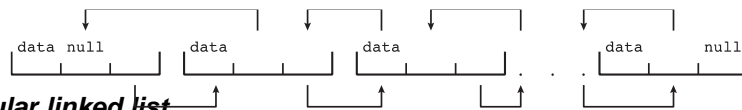
Kernel Data Structures

n Similar to standard programming data structures.

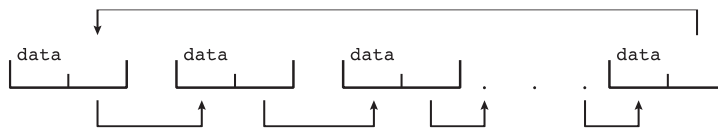
n **Singly linked list**



n **Doubly linked list**



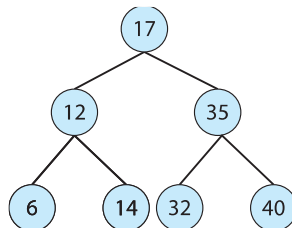
n **Circular linked list**



Kernel Data Structures

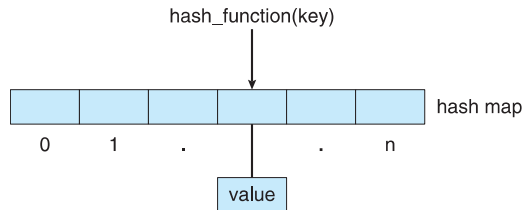
□ **Binary search tree**
left ≤ right

- Search performance is $O(n)$
- **Balanced binary search tree** is $O(\lg n)$



Kernel Data Structures

- Hash function can create a hash map.



- Bitmap – string of n binary digits representing the status of n items.
- Linux data structures defined in
include files <linux/list.h>, <linux/kfifo.h>, <linux/rbtree.h>

Computing Environments - Traditional

- Stand-alone general purpose machines.
- But blurred as most systems interconnect with others (i.e., the Internet).
- Portals provide web access to internal systems.
- Network computers (thin clients) are like Web terminals.
- Mobile computers interconnect via wireless networks.
- Networking becoming ubiquitous – even home systems use firewalls to protect home computers from Internet attacks.

Computing Environments - Mobile

- ❑ Handheld smartphones, tablets, etc.
- ❑ What is the functional difference between them and a “traditional” laptop?
- ❑ Extra feature – more OS features (GPS, gyroscope).
- ❑ Allows new types of apps like *augmented reality*.
- ❑ Use IEEE 802.11 wireless, or cellular data networks for connectivity.
- ❑ Leaders are Apple iOS and Google Android.

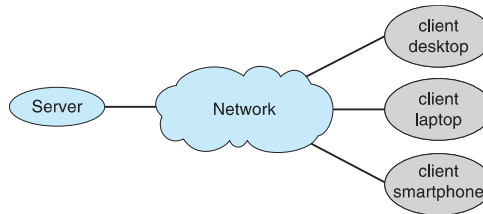
Computing Environments – Distributed

- ❑ **Distributed computing**
 - Collection of separate, possibly heterogeneous, systems networked together.
 - **Network** is a communications path, **TCP/IP** most common
 - **Local Area Network (LAN)**
 - **Wide Area Network (WAN)**
 - **Metropolitan Area Network (MAN)**
 - **Personal Area Network (PAN)**
 - **Network Operating System** provides features between systems across network.
 - Communication scheme allows systems to exchange messages
 - Illusion of a single system

Computing Environments – Client-Server

■ Client-Server Computing

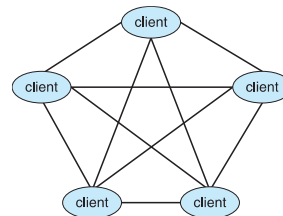
- Dumb terminals supplanted by smart PCs
- Many systems now **servers**, responding to requests generated by **clients**
 - **Compute-server system** provides an interface to client to request services (i.e., database)
 - **File-server system** provides interface for clients to store and retrieve files



Computing Environments - Peer-to-Peer

- Another model of distributed system.
- P2P does not distinguish clients and servers.

- Instead all nodes are considered peers
- May each act as client, server or both
- Node must join P2P network
 - Registers its service with central lookup service on network, or
 - Broadcast request for service and respond to requests for service via **discovery protocol**
- Examples include Napster and Gnutella, **Voice over IP (VoIP)** such as Skype



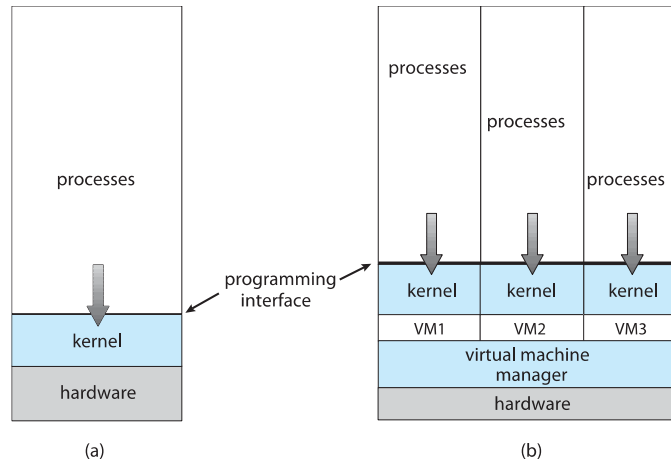
Computing Environments – Virtualization (1)

- ❑ **Allows operating systems to run applications within other OSeS**
 - Vast and growing industry
- ❑ **Emulation used when source CPU type different from target type (i.e. PowerPC to Intel x86)**
 - Generally slowest method
 - When computer language not compiled to native code – **Interpretation**
- ❑ **Virtualization – OS natively compiled for CPU, running guest OSeS also natively compiled**
 - Consider VMware running WinXP guests, each running applications, all on native WinXP **host** OS
 - **VMM** (virtual machine Manager) provides virtualization services

Computing Environments – Virtualization (2)

- ❑ **Use cases involve laptops and desktops running multiple OSeS for exploration or compatibility**
 - Apple laptop running Mac OS X host, Windows as a guest
 - Developing apps for multiple OSeS without having multiple systems
 - QA testing applications without having multiple systems
 - Executing and managing compute environments within data centers
- ❑ **VMM can run natively, in which case they are also the host**
 - There is no general purpose host then (VMware ESX and Citrix XenServer)

Computing Environments – Virtualization (3)

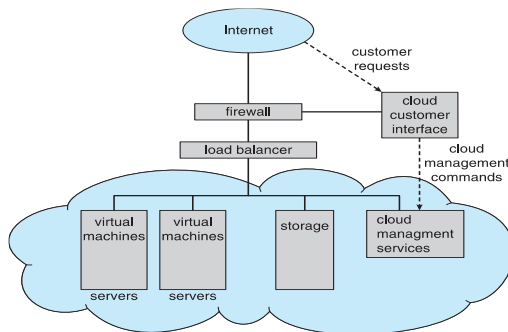


Computing Environments – Cloud Computing (1)

- ❑ **Delivers computing, storage, even apps as a service across a network.**
- ❑ **Logical extension of virtualization because it uses virtualization as the base for its functionality.**
 - Amazon **EC2** has thousands of servers, millions of virtual machines, petabytes of storage available across the Internet, pay based on usage
- ❑ **Many types**
 - **Public cloud** – available via Internet to anyone willing to pay
 - **Private cloud** – run by a company for the company's own use
 - **Hybrid cloud** – includes both public and private cloud components
 - **Software as a Service (SaaS)** – one or more applications available via the Internet (i.e., word processor)
 - **Platform as a Service (PaaS)** – software stack ready for application use via the Internet (i.e., a database server)
 - **Infrastructure as a Service (IaaS)** – servers or storage available over Internet (i.e., storage available for backup use)

Computing Environments – Cloud Computing (2)

- ❑ **Cloud computing environments composed of traditional OSes, plus VMMs, plus cloud management tools.**
 - Internet connectivity requires security like firewalls
 - Load balancers spread traffic across multiple applications



Computing Environments – Real-Time Embedded Systems

- ❑ **Real-time embedded systems most prevalent form of computers.**
 - Vary considerable, special purpose, limited purpose OS, **real-time OS**
 - Use expanding
- ❑ **Many other special computing environments as well.**
 - Some have OSes, some perform tasks without an OS
- ❑ **Real-time OS has well-defined fixed time constraints.**
 - Processing **must** be done within constraint
 - Correct operation only if constraints met

Open-Source Operating Systems

- ❑ Operating systems made available in source-code format rather than just binary closed-source.
- ❑ Counter to the copy protection and Digital Rights Management (DRM) movement.
- ❑ Started by Free Software Foundation (FSF), which has “copyleft” GNU Public License (GPL).
- ❑ Examples include GNU/Linux and BSD UNIX (including core of Mac OS X), and many more.
- ❑ Can use VMM like VMware Player (Free on Windows), Virtualbox (open source and free on many platforms - <http://www.virtualbox.com>) .
 - Use to run guest operating systems for exploration

Special-Purpose Systems

- ❑ **Embedded Systems:**
 - A special-purpose computer system designed to perform one or a few dedicated functions.
 - E.g., robotic arms.
 - Usually have little or no user interface.
 - Almost run **real-time operating systems**.
 - Rigid time requirements have been placed on the operation of a processor or the flow of data.
- ❑ **Multimedia Systems:**
 - A recent trend in technology is the incorporation of multimedia data into computer system.
 - Different from convention data, multimedia data must be delivered according to a certain time restrictions.
 - Chapter 20 explores the nature of multimedia data and the design of operating systems that support the multimedia.