

Triangulation complexity of fibred 3-manifolds

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Notes :

1. Thanks
2. Caveate -
3. Pitch - students

CUNY 2020

Part I: Triangulations

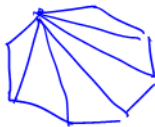
Definition. A triangulation of a surface is a gluing of triangles such that:

- ▶ edges glue to edges,
- ▶ vertices to vertices,
- ▶ interiors of triangles are disjoint.



Theorem

Every surface can be triangulated.



$4g$ -gon

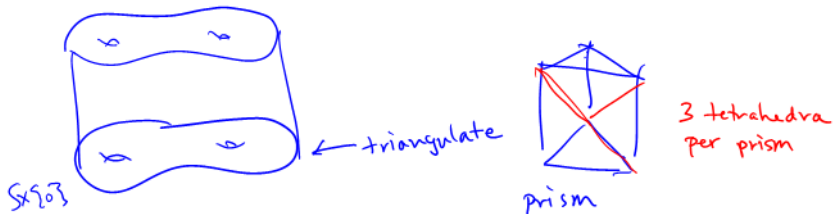
$4g-2$
triangles

3-manifold triangulations

Theorem (Moise 1952)

Every 3-manifold can be triangulated.

(Example: $S \times I$)



How is it used?

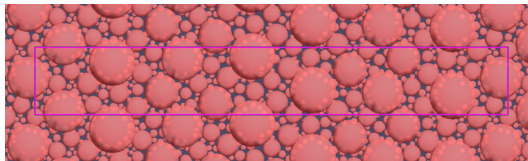
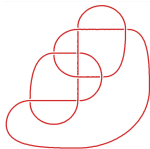
Computer:

3-manifold software:

- ▶ Regina (Burton, Budney, Petersson)
- ▶ SnapPy (Culler, Dunfield, Goerner, Weeks)

Manifolds represented by triangulations.

More “complicated” triangulations lead to slow algorithms, long processing time.



Measuring “complexity”

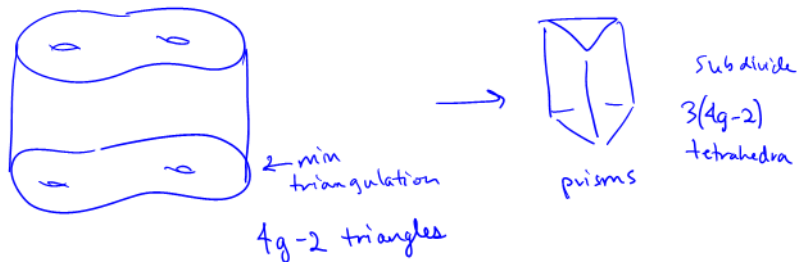
Simplest way: How many tetrahedra?

Measuring “complexity”

Simplest way: How many tetrahedra?

Definition. $\Delta(M) = \min$ number of tetrahedra in a triangulation of M .

(Example: $S \times I$)



$$\Delta(S \times I) \leq 3(4g-2).$$

Q: Can we do better?

Problem:

Given M , find $\Delta(M)$.

Known results:

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Known results:

- ▶ Enumerations of manifolds built with up to k tetrahedra:
 - ▶ Matveev–Savvateev 1974: up to $k = 5$
 - ▶ Martelli–Petronio 2001: up to 9
 - ▶ Matveev–Tarkaev 2005: up to 11.
 - ▶ Regina: Includes all 3-manifolds up to 13 tetrahedra.

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- ▶ Infinite families:
 - ▶ Anisov 2005: some punctured torus bundles
 - ▶ Jaco–Rubinstein–Tillmann 2009, 2011: infinite families of lens spaces
 - ▶ Jaco–Rubinstein–Spreer–Tillmann 2017, 2018: some covers, all punctured torus bundles, ...

Finding $\Delta(M)$

Finding exact value of $\Delta(M)$: **HARD**

Finding bounds: **Maybe not as hard?**

Upper bound: **Typically easy.**

Lower bound: **Hard**

Previous 2-sided bounds for families: Matveev–Petronio–Vesnin...

Today: 2-sided bounds for fibred 3-manifolds.

Löbell manifolds
Fibonacci manifolds

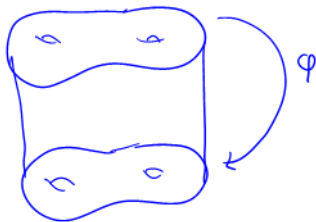
Fibred 3-manifold

Definition. Let S be a closed surface, $\phi : S \rightarrow S$ orientation preserving homeomorphism.

$$M_\phi = (S \times I) / (x, 0) \sim (\phi(x), 1)$$

Say M_ϕ *fibres over the circle* S^1 with fibre S .

ϕ is the *monodromy*.



Main theorem

Theorem (Lackenby – P)

Let M_ϕ be a closed 3-manifold that fibres over the circle with *pseudo-Anosov* monodromy ϕ . Then the following are within bounded ratios of each other, where the bound depends only on the genus of the fibre:

- ▶ $\Delta(M)$
- ▶ *Translation length* of ϕ in the *mapping class group*.
- ▶ (Additional) length_m $\text{Tr}(S), S_f(S)$

To do:

- ▶ Define terms
- ▶ Explain why this is the “right” theorem — comparisons with geometry
- ▶ Ideas of proof

Part II: Surfaces and their homeomorphisms

Definition. $\text{MCG}(S)$ *Mapping class group* of S
Orientation preserving homeomorphisms of S up to isotopy.

(Example: hyperelliptic involution)

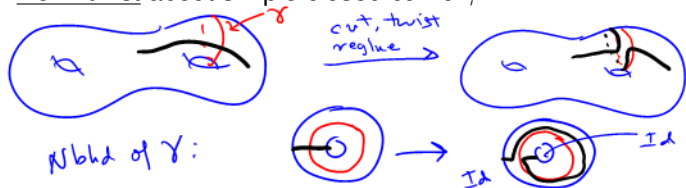


Generators of MCG

Theorem (Dehn 1910-ish, Lickorish 1963)

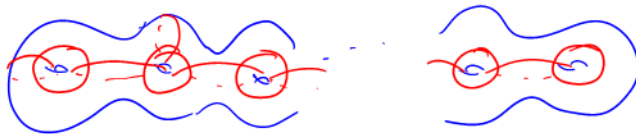
$MCG(S)$ is finitely generated, generated by **Dehn twists** about a finite number of curves.

Dehn twist about simple closed curve γ :



Humphries generators (1977):

min collection of curves s.t.
Dehn twists
generate
MCG.



Types of elements of MCG

1. *Periodic* $\varphi^n = \text{Id}$ for some n
E.g. hyperelliptic involution.
2. *Reducible*: Fixes a curve γ .
E.g. power of a single Dehn twist. γ fixed
3. *Pseudo-Anosov*: Everything else.
 \uparrow our theorem

Theorem (Thurston)

M_ϕ admits a complete hyperbolic metric if and only if ϕ is pseudo-Anosov.

Part III: Complexes and translation lengths

Definition. Let (X, d) be a metric space, ϕ an isometry. The *translation length* $\ell_X(\phi)$ is

$$\ell_X(\phi) = \inf \{ d(\phi(x), x) : x \in X \}$$

(Example: MCG)

$X = \text{MCG}(S)$ d = word length in a fixed set of generators.
e.g. Humphries generators.

$\phi \in \text{MCG}(S)$ written $\phi: \tau_1 \tau_2 \cdots \tau_n$
 $d(\phi, \psi) = \text{word length } \phi\psi$

$\phi \in \text{MCG}$ acts on $\text{MCG}(S)$ by isometry:

$$d(x, y) = d(\phi x, \phi y)$$

$$\ell_{\text{MCG}}(\phi) = \inf \{ d(\phi(x), x) : x \in \text{MCG} \}$$

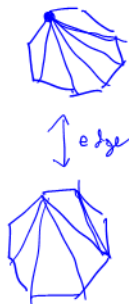
$$\leq n$$

$\text{I-1 } x = \text{Id}$
then $d(\phi, \text{Id}) = n$

Example 2: Triangulation complex

$X = \text{Tr}(S)$ complex of *1-vertex triangulations* of S .

- ▶ Vertices in $\text{Tr}(S) = 1\text{-vertex triangulations of } S$
- ▶ Edges: \exists edge between two triangulations
 $\Leftrightarrow \exists$ 2-2 Pachner move = diagonal exchange



Metric: Set each edge in $\text{Tr}(S)$ to have length 1.

d is distance under path metric.

(Connected geodesic metric space)

$\phi \in \text{MCG}(S)$ acts by isometry.

$\phi(\text{triang}) = \text{new triang.}$

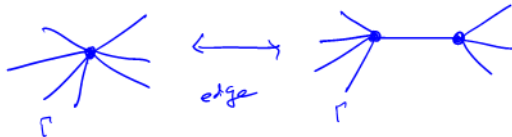
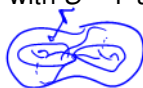
Therefore $\ell_{\text{Tr}(S)}(\phi)$ defined.

Example 3: Spine complex

$X = \text{Sp}(S)$ complex of *spines* on S .

Spine: Embedded graph $\Gamma \subset S$, with $S - \Gamma$ a disc, and no vertices of valence 0, 1, 2.

- ▶ Vertices in $\text{Sp}(S) = \text{spines of } S$
- ▶ Edges: \exists edge between two spines
 $\Leftrightarrow \exists$ edge contraction/expansion



Metric: Each edge has length 1, d is path metric.
(Connected geodesic metric space)

$\phi \in \text{MCG}(S)$ acts by isometry.

$\phi(\text{spine}) = \text{new spine}$

Therefore $\ell_{\text{Sp}(S)}(\phi)$ defined.

Quasi-isometries

Lemma

$Tr(S)$, $Sp(S)$, $MCG(S)$ are all quasi-isometric.

(Proof, for experts: Svarc–Milnor lemma)

Quasi-isometric: $\exists f : (X, d_X) \rightarrow (Y, d_Y)$ and constants $A \geq 1$, $B \geq 0$, $C \geq 0$ such that:

1. $\forall x, y \in X$,

i.e. within
bounded ratios
of one another.

$$\frac{1}{A} \cdot d_X(x, y) - B \leq d_Y(f(x), f(y)) \leq A \cdot d_X(x, y) + B$$

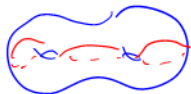
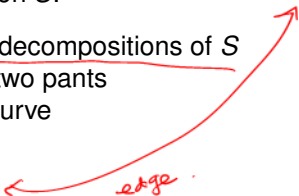
2. $\forall y \in Y$, $\exists x \in X$ such that $d_Y(y, f(x)) \leq C$.

Example 4: Pants complex

$X = P(S)$ complex of *pants decompositions* of S .

Pants decomposition: Collection of $3g - 3$ disjoint simple closed curves on S .

- ▶ Vertices in $P(S)$ = pants decompositions of S
- ▶ Edges: \exists edge between two pants
 $\Leftrightarrow \exists$ pants differ by one curve



Metric: Each edge has length 1, d is path metric.
(Connected geodesic metric space)

$\phi \in \text{MCG}(S)$ acts by isometry.

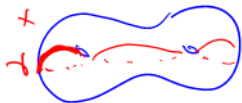
$$\ell_{P(S)}(\phi)$$

$\phi(\text{pants}) = \text{new pants decomp.}$

MCG is NOT quasi-isometric to $P(S)$

Proof.

Let $x, y \in P(S)$. Let ϕ Dehn twist about curve in x .



ϕ Dehn twist about γ . \Rightarrow fix $x \in P(S)$

$$\underbrace{d_{P(S)}(x, \phi^n(y))}_{\text{word length}} = \underbrace{d_{P(S)}(\phi^n(x), \phi^n(y))}_{\text{word length}} = \underbrace{d_{P(S)}(x, y)}_{\text{word length}} : \text{Independent of } n.$$

$\underbrace{d_{\text{MCG}}(x, \phi^n(y))}_{\text{word length}}$ growing with n .

word length

Main theorem revisited

Theorem (Lackenby-P)

For ϕ pseudo-Anosov, and $M_\phi = (S \times I)/\phi$, the following are within bounded ratios:

- ▶ $\Delta(M_\phi)$ \leftarrow New $\{$ hard.
 - ▶ $\ell_{MCG}(\phi)$
 - ▶ $\ell_{Tr}(\phi)$
 - ▶ $\ell_{Sp}(\phi)$
- } By Svarc-Milnor

Const: depend only on genus of S .

Compare to older theorem

Theorem (Brock 2003)

For ϕ pseudo-Anosov, $M_\phi = (S \times I)/\phi$, the following are within bounded ratios of each other:

- ▶ $\text{Vol}(M_\phi)$ hyperbolic volume
- ▶ $\ell_P(\phi)$ translation length in pants complex

Consts depend on sfc.

Why ours is the “right” theorem (for exports)

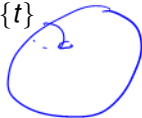
Suppose ϕ is a word in a very high power of a Dehn twist about some curve γ :

$$\phi = \tau_1 \tau_2 \dots \tau_k^N \dots \tau_\ell$$

Geometrically, M_ϕ contains a deep tube about $\gamma \times \{t\}$

Deep tubes and volume:

$$\text{vol}(\text{tube}) \leq \underbrace{\text{vol}(\text{cusp})}_{\text{finite bounded.}}$$



Deep tubes and triangulations: Layered solid tori (Jaco–Rubinstein)

LST : # tetrahedra grows as tube gets “deeper”

Unbounded.

Why ours is not yet the “most right” theorem

- ▶ Pseudo-Anosov shouldn't be required.
- ▶ Closed manifolds shouldn't be required.
- ▶ Brock extended volumes to Heegaard splittings. We should too.

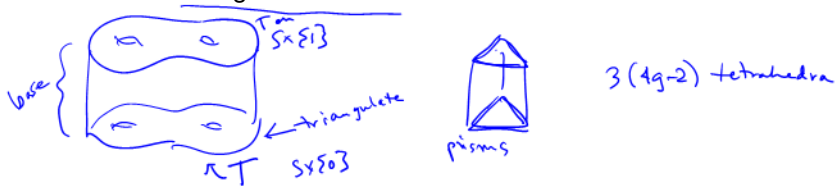
Part IV: Proof of upper bound

Theorem (Upper bound)

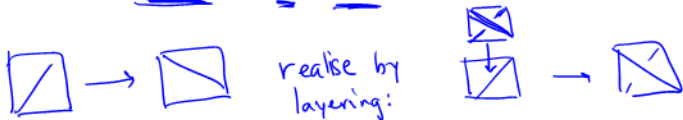
There exist constants C, D , depending only on $g(S)$ such that

$$\Delta(M_\phi) \leq C \ell_{\text{Tr}}(\phi) + D.$$

Proof. Give S a 1-vertex triangulation $T \in \text{Tr}(S)$: $4g - 2$ triangles.
Start with triangulation $S \times I$:



Let γ be path in $\text{Tr}(S)$ from T to $\phi(T)$. Each step: layer tetrahedron.

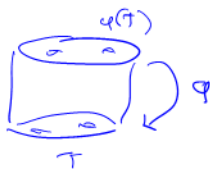


Proof of upper bound, continued

After $\ell_{\text{Tr}}(\phi)$ steps:

Have triangulation of $S \times I$ with

- ▶ $S \times \{0\}$ triangulated by T ,
- ▶ $S \times \{1\}$ triangulated by $\phi(T)$.



Glue to triangulate M_ϕ .

$$\Delta(M) \leq \underbrace{\ell_{\text{Tr}}(\phi)}_{\text{layering}} + \underbrace{3(4g-2)}_{\text{base}}.$$

Part V: Proof ideas for lower bound

 S_ϕ

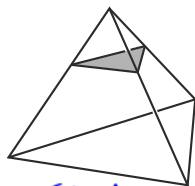
Idea: Suppose M_ϕ is triangulated with $\Delta(M_\phi)$ tetrahedra.

\exists copy of S in normal form. Cut along it to get $S \times I$.

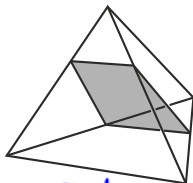
\exists copy of S in almost normal form.

Triangle, quad or
at most one

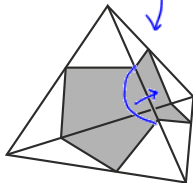
Normal form:
Intersects tetrahedra in
triangles & quads.



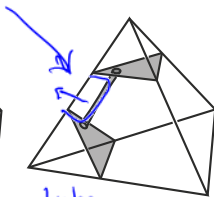
Triangle



quad.



octagon



tube

\exists well-understood ways of moving from almost normal to normal.

Goal: Bound moves to sweep spine from bottom to top:

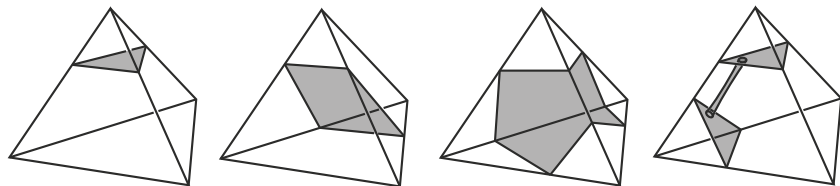
$$\ell_{Sp}(\phi) \leq A \Delta(M_\phi) + B$$

Part V: Proof ideas for lower bound

Idea: Suppose M_ϕ is triangulated with $\Delta(M_\phi)$ tetrahedra.

\exists copy of S in *normal form*. Cut along it to get $S \times I$.

\exists copy of S in *almost normal form*.



\exists well-understood ways of moving from almost normal to normal.

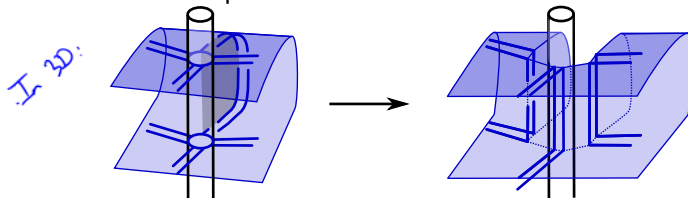
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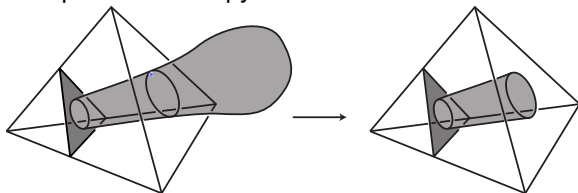
(This isn't going to work.)

Moves between almost normal, normal

- Face compression:

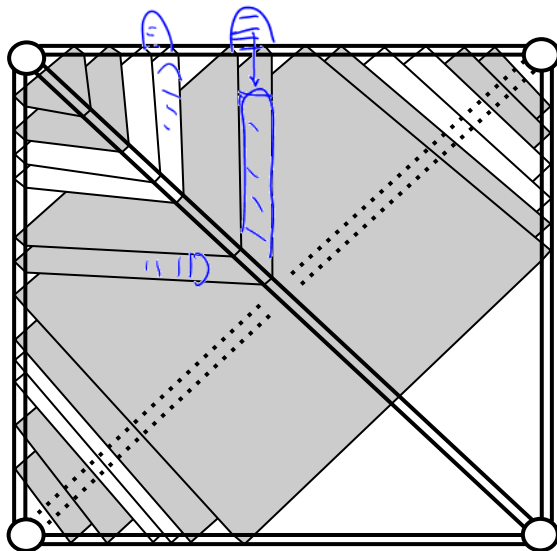


- Compression isotopy:



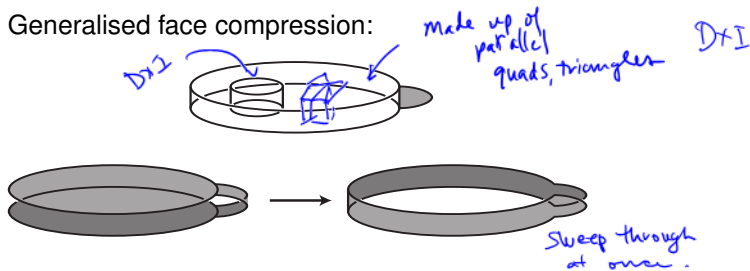
Problem: Parallelity bundles

No bound
on # triangles
& squares that
are parallel.

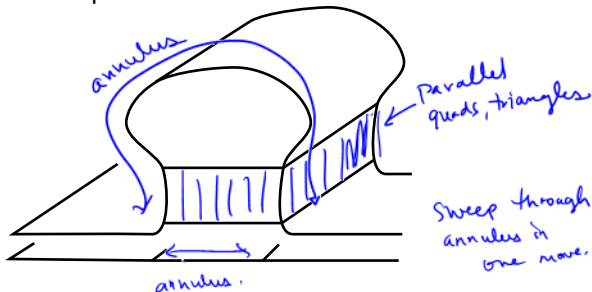


Fix: More drastic simplifications

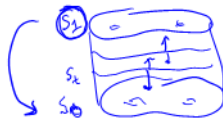
- Generalised face compression:



- Annular simplification:



Finishing up



Idea:

1. Start with M_ϕ . Cut along least weight normal surface S to obtain $S \times I$. Pick spine $s_0 \in S \times \{0\}$.
2. Find surfaces interpolating between $S \times \{0\}$ and $S \times \{1\}$, differing by generalised isotopy moves.
3. Bound number of steps in $\text{Sp}(S)$ required to transfer s_0 through interpolating surfaces to $S \times \{1\}$. Bound of form

$$\text{steps} \leq A_0 \Delta(M) + B_0.$$

4. Bound steps to transfer spine s_1 in $S \times \{1\}$ to $\phi(s_0)$, of form

$$\text{steps} \leq A_1 \Delta(M) + B_1.$$

5. Consequence:

$$\underline{\ell_{\text{Sp}}(\phi) \leq A \Delta(M) + B.}$$

Summary

$$\underbrace{\frac{1}{A} \ell_{\text{Sp}}(\phi) - B}_{\cdot} \leq \Delta(M_\phi) \leq \underbrace{\ell_{\text{Tr}}(\phi) + 3(4g - 2)}_{\cdot}$$

Thus

$\Delta(M_\phi)$ and $\ell_{\text{MCG}}(\phi)$ are within bounded ratios of each other.